



US010136778B2

(12) **United States Patent**
Conrad

(10) **Patent No.:** **US 10,136,778 B2**

(45) **Date of Patent:** **Nov. 27, 2018**

(54) **SURFACE CLEANING APPARATUS**

(71) Applicant: **Omachron Intellectual Property Inc.**,
Hampton (CA)

(72) Inventor: **Wayne Ernest Conrad**, Hampton (CA)

(73) Assignee: **Omachron Intellectual Property Inc.**,
Hampton, Ontario (CA)

(*) Notice: Subject to any disclaimer, the term of this
patent is extended or adjusted under 35
U.S.C. 154(b) by 212 days.

(21) Appl. No.: **14/933,057**

(22) Filed: **Nov. 5, 2015**

(65) **Prior Publication Data**

US 2016/0174785 A1 Jun. 23, 2016

Related U.S. Application Data

(63) Continuation of application No. 14/822,211, filed on
Aug. 10, 2015, now Pat. No. 9,888,817.

(60) Provisional application No. 62/093,189, filed on Dec.
17, 2014.

(51) **Int. Cl.**

A47L 5/22 (2006.01)
A47L 9/12 (2006.01)
A47L 9/16 (2006.01)
A47L 5/30 (2006.01)
A47L 9/24 (2006.01)

(52) **U.S. Cl.**

CPC *A47L 5/225* (2013.01); *A47L 5/30*
(2013.01); *A47L 9/12* (2013.01); *A47L 9/1608*
(2013.01); *A47L 9/1683* (2013.01); *A47L*
9/1691 (2013.01); *A47L 9/248* (2013.01)

(58) **Field of Classification Search**

CPC ... *A47L 5/225*; *A47L 5/30*; *A47L 9/12*; *A47L*
9/1608; *A47L 9/1683*; *A47L 9/1691*;
A47L 9/248

See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

911,258 A 2/1909 Neumann
1,600,762 A 9/1926 Hawley
1,797,812 A 3/1931 Waring
1,898,608 A 2/1933 Alexander
1,937,765 A 12/1933 Leathers

(Continued)

FOREIGN PATENT DOCUMENTS

AU 112778 4/1940
CA 1077412 A1 5/1980

(Continued)

OTHER PUBLICATIONS

English machine translation of CN101108081A published on Jan.
23, 2008.

(Continued)

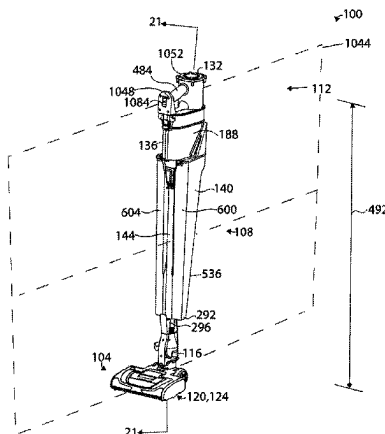
Primary Examiner — Robert Scruggs

(74) *Attorney, Agent, or Firm* — Philip C. Mendes da
Costa; Bereskin & Parr LLP/S.E.N.C.R.L., s.r.l.

(57) **ABSTRACT**

A surface cleaning apparatus comprises a surface cleaning
head, an upright section moveably mounted to the surface
cleaning head between a plurality of reclined floor cleaning
positions and an upright storage position and a portable
vacuum cleaner unit detachably mounted to the upright
section. The portable vacuum cleaner unit has a suction
motor and the remainder of the surface cleaning apparatus
from which the portable vacuum cleaner unit is detached
also has a suction motor.

18 Claims, 130 Drawing Sheets



(56)

References Cited

U.S. PATENT DOCUMENTS

2,015,464	A	9/1935	Saint Jacques	5,363,535	A	11/1994	Rench et al.
2,152,114	A	3/1939	Van Tongeren	5,481,780	A	1/1996	Daneshvar
2,542,634	A	2/1951	Davis et al.	5,515,573	A	5/1996	Frey
2,678,110	A	5/1954	Madsen	5,599,365	A	2/1997	Alday et al.
2,731,102	A	1/1956	James	D380,033	S	6/1997	Masterson et al.
2,811,219	A	10/1957	Wenzl	5,709,007	A	1/1998	Chiang
2,846,024	A	8/1958	Bremi	5,755,096	A	5/1998	Holleyman
2,913,111	A	11/1959	Rogers	5,815,878	A	10/1998	Murakami et al.
2,917,131	A	12/1959	Evans	5,815,881	A	10/1998	Sjogreen
2,937,713	A	5/1960	Stephenson et al.	5,858,038	A	1/1999	Dyson et al.
2,942,691	A	6/1960	Dillon	5,858,043	A	1/1999	Geise
2,942,692	A	6/1960	Benz	5,893,938	A	4/1999	Dyson et al.
2,946,451	A	7/1960	Culleton	5,935,279	A	8/1999	Kilstroem
2,952,330	A	9/1960	Winslow	5,950,274	A	9/1999	Kilstrom
2,981,369	A	4/1961	Yellott et al.	5,970,572	A	10/1999	Homas
3,032,954	A	5/1962	Racklyeft	6,071,095	A	6/2000	Verkaar
3,085,221	A	4/1963	Kelly	6,071,321	A	6/2000	Trapp et al.
3,130,157	A	4/1964	Kelsall et al.	6,080,022	A	6/2000	Shaberman et al.
3,200,568	A	8/1965	McNeil	6,122,796	A	9/2000	Downham
3,204,772	A	9/1965	Ruxton				A47L 5/00 15/328
3,217,469	A	11/1965	Eckert	6,210,469	B1	4/2001	Tokar
3,269,097	A	8/1966	German	6,221,134	B1	4/2001	Conrad et al.
3,320,727	A	5/1967	Farley et al.	6,228,260	B1	5/2001	Conrad et al.
3,372,532	A	3/1968	Campbell	6,231,645	B1	5/2001	Conrad et al.
3,426,513	A	2/1969	Bauer	6,251,296	B1	6/2001	Conrad et al.
3,518,815	A	7/1970	Peterson et al.	6,260,234	B1	7/2001	Wright et al.
3,530,649	A	9/1970	Porsch et al.	6,345,408	B1	2/2002	Nagai et al.
3,543,325	A	12/1970	Hamrick et al.	6,406,505	B1	6/2002	Oh et al.
3,561,824	A	2/1971	Homan	6,434,785	B1	8/2002	Vandenbelt et al.
3,582,616	A	6/1971	Wrob	6,440,197	B1	8/2002	Conrad et al.
3,675,401	A	7/1972	Cordes	6,502,278	B2	1/2003	Oh et al.
3,684,093	A	8/1972	Kono	6,519,810	B2	2/2003	Kim
3,822,533	A	7/1974	Oranje	6,531,066	B1	3/2003	Saunders et al.
3,898,068	A	8/1975	McNeil et al.	6,553,612	B1	4/2003	Dyson et al.
3,933,450	A	1/1976	Percevaut	6,553,613	B2	4/2003	Onishi et al.
3,988,132	A	10/1976	Oranje	6,560,818	B1	5/2003	Hasko
3,988,133	A	10/1976	Schady	6,581,239	B1	6/2003	Dyson et al.
4,097,381	A	6/1978	Ritzler	6,599,338	B2	7/2003	Oh et al.
4,187,088	A	2/1980	Hodgson	6,599,350	B1	7/2003	Rockwell et al.
4,218,805	A	8/1980	Brazier	6,613,316	B2	9/2003	Sun et al.
4,236,903	A	12/1980	Malmsten	6,623,539	B2	9/2003	Lee et al.
4,307,485	A	12/1981	Dessig	6,625,845	B2	9/2003	Matsumoto et al.
4,373,228	A	2/1983	Dyson	6,640,385	B2	11/2003	Oh et al.
4,382,804	A	5/1983	Mellor	6,648,934	B2	11/2003	Choi et al.
4,409,008	A	10/1983	Solymes	6,712,868	B2	3/2004	Murphy et al.
4,486,207	A	12/1984	Baillie	6,732,403	B2	5/2004	Moore et al.
4,494,270	A	1/1985	Ritzau et al.	6,746,500	B1	6/2004	Park et al.
4,523,936	A	6/1985	Disanza, Jr.	6,766,558	B1	7/2004	Matsumoto et al.
4,678,588	A	7/1987	Shortt	6,782,583	B2	8/2004	Oh
4,700,429	A	10/1987	Martin et al.	6,782,585	B1	8/2004	Conrad et al.
4,744,958	A	5/1988	Pircon	6,810,558	B2	11/2004	Lee
4,778,494	A	10/1988	Patterson	6,818,036	B1	11/2004	Seaman
4,803,753	A	2/1989	Palmer	6,833,015	B2	12/2004	Oh et al.
4,826,515	A	5/1989	Dyson	6,868,578	B1	3/2005	Kasper
D303,173	S	8/1989	Masakata et al.	6,874,197	B1	4/2005	Conrad
4,853,008	A	8/1989	Dyson	6,896,719	B2	5/2005	Coates et al.
4,853,011	A	8/1989	Dyson	6,929,516	B2	8/2005	Brochu et al.
4,853,111	A	8/1989	MacArthur et al.	6,968,596	B2	11/2005	Oh et al.
4,905,342	A	3/1990	Ataka	6,976,885	B2	12/2005	Lord
4,944,780	A	7/1990	Usmani	7,113,847	B2	9/2006	Chmura et al.
4,980,945	A	1/1991	Bewley	7,128,770	B2	10/2006	Oh et al.
5,054,157	A	10/1991	Werner et al.	7,160,346	B2	1/2007	Park
5,078,761	A	1/1992	Dyson	7,162,770	B2	1/2007	Davidshofer
5,080,697	A	1/1992	Finke	7,175,682	B2	2/2007	Nakai et al.
5,090,976	A	2/1992	Dyson	7,198,656	B2	4/2007	Takemoto et al.
5,129,125	A	7/1992	Gamou et al.	7,222,393	B2	5/2007	Kaffenberger et al.
5,224,238	A	7/1993	Bartlett	7,272,872	B2	9/2007	Choi
5,230,722	A	7/1993	Yonkers	7,278,181	B2	10/2007	Harris et al.
5,254,019	A	10/1993	Noschese	7,341,611	B2	3/2008	Greene et al.
5,267,371	A	12/1993	Solerm et al.	7,354,468	B2	4/2008	Arnold et al.
5,287,591	A	2/1994	Rench et al.	7,370,387	B2	5/2008	Walker et al.
5,307,538	A	5/1994	Rench et al.	7,377,007	B2	5/2008	Best
5,309,600	A	5/1994	Weaver et al.	7,377,953	B2	5/2008	Oh
5,309,601	A	5/1994	Hampton et al.	7,386,915	B2	6/2008	Blocker et al.
5,347,679	A	9/1994	Saunders et al.	7,395,579	B2	7/2008	Oh
				7,426,768	B2	9/2008	Peterson et al.
				7,429,284	B2	9/2008	Oh
				7,448,363	B1	11/2008	Rasmussen et al.
				7,449,040	B2	11/2008	Conrad et al.

(56)	References Cited					
	U.S. PATENT DOCUMENTS					
	7,485,164 B2	2/2009	Jeong et al.	2006/0137309 A1	6/2006	Jeong et al.
	7,488,363 B2	2/2009	Jeong et al.	2006/0137314 A1	6/2006	Conrad et al.
	7,547,337 B2	6/2009	Oh	2006/0156508 A1	7/2006	Khalil
	7,547,338 B2	6/2009	Kim et al.	2006/0162298 A1	7/2006	Oh et al.
	7,563,298 B2	7/2009	Oh	2006/0162299 A1	7/2006	North
	7,565,853 B2	7/2009	Arnold et al.	2006/0168922 A1	8/2006	Oh
	7,588,616 B2	9/2009	Conrad et al.	2006/0168923 A1	8/2006	Lee et al.
	7,597,730 B2	10/2009	Yoo et al.	2006/0207055 A1	9/2006	Ivarsson et al.
	7,628,831 B2	12/2009	Gomiciaga-Pereda et al.	2006/0207231 A1	9/2006	Arnold
	7,691,161 B2	4/2010	Oh et al.	2006/0230715 A1*	10/2006	Oh A47L 9/1658
	7,717,973 B2	5/2010	Oh et al.			55/337
	7,740,676 B2	6/2010	Burnham et al.	2006/0230723 A1	10/2006	Kim et al.
	7,770,256 B1	8/2010	Fester	2006/0230724 A1	10/2006	Han et al.
	7,776,120 B2	8/2010	Conrad	2006/0236663 A1	10/2006	Oh
	7,779,506 B2	8/2010	Kang et al.	2006/0254226 A1	11/2006	Jeon
	7,803,207 B2	9/2010	Conrad	2006/0278081 A1	12/2006	Han et al.
	7,805,804 B2	10/2010	Loebig	2006/0288516 A1	12/2006	Sawalski
	7,811,349 B2	10/2010	Nguyen	2007/0067944 A1	3/2007	Kitamura
	7,867,308 B2	1/2011	Conrad	2007/0077810 A1	4/2007	Gogel
	7,882,593 B2	2/2011	Beskow et al.	2007/0079473 A1	4/2007	Min
	7,922,794 B2	4/2011	Morphy	2007/0079585 A1	4/2007	Oh et al.
	7,931,716 B2	4/2011	Oakham	2007/0095028 A1	5/2007	Kim
	7,938,871 B2	5/2011	Lloyd	2007/0095029 A1	5/2007	Min
	7,958,598 B2	6/2011	Yun et al.	2007/0136984 A1	6/2007	Hsu
	7,979,959 B2	7/2011	Courtney	2007/0209334 A1	9/2007	Conrad
	7,996,956 B2	8/2011	Wood et al.	2007/0209335 A1	9/2007	Conrad
	8,021,453 B2	9/2011	Howes	2007/0271724 A1	11/2007	Hakan et al.
	8,062,398 B2	11/2011	Luo et al.	2007/0289089 A1	12/2007	Yacobi
	8,100,999 B2	1/2012	Ashbee et al.	2007/0289266 A1	12/2007	Oh
	8,101,001 B2	1/2012	Qian	2008/0040883 A1	2/2008	Beskow et al.
	8,117,712 B2	2/2012	Dyson et al.	2008/0047091 A1	2/2008	Nguyen
	8,146,201 B2	4/2012	Conrad	2008/0134460 A1	6/2008	Conrad
	8,151,407 B2	4/2012	Conrad	2008/0134462 A1	6/2008	Jansen et al.
	8,152,877 B2	4/2012	Greene	2008/0178416 A1	7/2008	Conrad
	8,156,609 B2	4/2012	Milne et al.	2008/0178420 A1	7/2008	Conrad
	8,161,599 B2	4/2012	Griffith et al.	2008/0190080 A1	8/2008	Oh et al.
	8,225,456 B2	7/2012	Håkan et al.	2008/0196194 A1	8/2008	Conrad
	8,484,799 B2	7/2013	Conrad	2008/0196745 A1	8/2008	Conrad
	8,673,487 B2	3/2014	Churchill	2008/0301903 A1	12/2008	Cunningham et al.
	9,192,269 B2	11/2015	Conrad	2009/0044372 A1	2/2009	Knopow et al.
	9,675,218 B2	6/2017	Kim et al.	2009/0100633 A1	4/2009	Bates et al.
	2002/0011050 A1	1/2002	Hansen et al.	2009/0113659 A1	5/2009	Jeon
	2002/0011053 A1	1/2002	Oh	2009/0144932 A1	6/2009	Yoo
	2002/0062531 A1	5/2002	Oh	2009/0165431 A1	7/2009	Oh
	2002/0088208 A1	7/2002	Lukac et al.	2009/0205160 A1	8/2009	Conrad
	2002/0112315 A1	8/2002	Conrad	2009/0205161 A1	8/2009	Conrad
	2002/0134059 A1	9/2002	Oh	2009/0205298 A1	8/2009	Hyun et al.
	2002/0134238 A1	9/2002	Conrad et al.	2009/0209666 A1	8/2009	Hellberg et al.
	2002/0178535 A1	12/2002	Oh et al.	2009/0265877 A1	10/2009	Dyson et al.
	2002/0178698 A1	12/2002	Oh et al.	2009/0282639 A1	11/2009	Dyson et al.
	2002/0178699 A1	12/2002	Oh	2009/0300874 A1	12/2009	Tran et al.
	2003/0037403 A1	2/2003	Lang	2009/0300875 A1	12/2009	Inge et al.
	2003/0046910 A1	3/2003	Lee	2009/0307564 A1	12/2009	Vedantham et al.
	2003/0066273 A1	4/2003	Choi et al.	2009/0307863 A1	12/2009	Milne et al.
	2003/0106180 A1	6/2003	Tsen	2009/0307864 A1	12/2009	Dyson
	2003/0159238 A1	8/2003	Oh	2009/0308254 A1	12/2009	Oakham
	2003/0159411 A1	8/2003	Hansen et al.	2009/0313958 A1	12/2009	Gomiciaga-Pereda et al.
	2003/0200736 A1	10/2003	Ni	2009/0313959 A1	12/2009	Gomiciaga-Pereda et al.
	2004/0010885 A1	1/2004	Hitzelberger et al.	2010/0083459 A1	4/2010	Beskow et al.
	2004/0025285 A1	2/2004	McCormick et al.	2010/0132319 A1	6/2010	Ashbee et al.
	2004/0045126 A1	3/2004	Parker et al.	2010/0154150 A1	6/2010	McLeod
	2004/0216264 A1	11/2004	Shaver et al.	2010/0175217 A1	7/2010	Conrad
	2005/0081321 A1	4/2005	Milligan et al.	2010/0212104 A1	8/2010	Conrad
	2005/0115409 A1	6/2005	Conrad	2010/0224073 A1	9/2010	Oh et al.
	2005/0132528 A1	6/2005	Yau	2010/0229321 A1	9/2010	Dyson et al.
	2005/0198769 A1	9/2005	Lee et al.	2010/0229324 A1	9/2010	Conrad
	2005/0198770 A1	9/2005	Jung et al.	2010/0229328 A1	9/2010	Conrad
	2005/0252179 A1	11/2005	Oh et al.	2010/0242210 A1	9/2010	Conrad
	2005/0252180 A1	11/2005	Oh et al.	2010/0243158 A1	9/2010	Conrad
	2006/0037172 A1	2/2006	Choi	2010/0293745 A1	11/2010	Coburn
	2006/0042206 A1	3/2006	Arnold et al.	2010/0299865 A1	12/2010	Conrad
	2006/0090290 A1	5/2006	Lau	2010/0299866 A1	12/2010	Conrad
	2006/0123590 A1	6/2006	Fester et al.	2011/0023261 A1	2/2011	Proffitt, II et al.
	2006/0137304 A1	6/2006	Jeong et al.	2011/0146024 A1	6/2011	Conrad
	2006/0137306 A1	6/2006	Jeong et al.	2011/0168332 A1	7/2011	Bowe et al.
				2011/0219576 A1	9/2011	Conrad
				2011/0289719 A1*	12/2011	Han A47L 5/225
						15/344
				2012/0023701 A1	2/2012	Lenkiewicz et al.

(56)

References Cited

U.S. PATENT DOCUMENTS

2012/0030896 A1 2/2012 Crouch et al.
 2012/0060322 A1 3/2012 Simonelli et al.
 2012/0079671 A1 4/2012 Stickney et al.
 2012/0216361 A1 8/2012 Millington et al.
 2012/0222245 A1 9/2012 Conrad
 2012/0222260 A1 9/2012 Conrad
 2012/0222262 A1 9/2012 Conrad
 2013/0160232 A1 6/2013 Peace
 2014/0137362 A1 5/2014 Smith
 2014/0137363 A1 5/2014 Wilson
 2014/0137364 A1 5/2014 Stickney et al.
 2014/0182080 A1 7/2014 Lee et al.
 2014/0208538 A1 7/2014 Visel et al.
 2014/0237956 A1 8/2014 Conrad
 2015/0135474 A1 5/2015 Gidwell
 2015/0230677 A1 8/2015 Andrikanish
 2015/0297050 A1 10/2015 Marsh et al.
 2016/0113460 A1 4/2016 Williams et al.

FOREIGN PATENT DOCUMENTS

CA 1218962 A 3/1987
 CA 2450450 A1 12/2004
 CA 2484587 A1 4/2005
 CA 2438079 C 8/2009
 CA 2658014 A1 9/2010
 CA 2659212 A1 9/2010
 CN 1336154 A 2/2002
 CN 1434688 A 8/2003
 CN 1493244 A 5/2004
 CN 1875846 A 12/2006
 CN 1875855 A 12/2006
 CN 1887437 A 1/2007
 CN 101061932 A 10/2007
 CN 101108081 A 1/2008
 CN 101108106 A 1/2008
 CN 101108110 A 1/2008
 CN 201290642 Y 8/2009
 CN 202739907 U 2/2013
 CN 202932850 U 5/2013
 CN 204363891 U 6/2015
 CN 105816104 A 8/2016
 CN 205671986 U 11/2016
 DE 875134 C 4/1953
 DE 9216071.9 U1 2/1993
 DE 4232382 C1 3/1994
 DE 10056935 C2 1/2003
 DE 69907201 T2 2/2004
 DE 60201666 T2 6/2006
 DE 60211663 T2 5/2007
 DE 102007011457 A1 10/2007
 DE 112010001135 T5 8/2012
 DE 102012211246 A1 1/2014
 EP 0489498 A1 6/1992
 EP 493950 B1 7/1992
 EP 1200196 B1 6/2005
 EP 1779761 A2 5/2007
 EP 1815777 A1 8/2007
 EP 1594386 B1 4/2009
 EP 1676516 B1 1/2010
 EP 2308360 A2 4/2011
 EP 1629758 A3 10/2013
 EP 2848173 A1 3/2015
 FR 2812531 B1 11/2004
 GB 700791 A 12/1953
 GB 1111074 A 4/1968
 GB 2035787 B 10/1982
 GB 2163703 B 1/1988
 GB 2268875 A 1/1994
 GB 2307849 A 6/1997
 GB 2282979 B 10/1997
 GB 2365324 B 7/2002
 GB 2440111 A 1/2008
 GB 2465781 A 6/2010
 GB 2441962 B 3/2011

GB 2466290 B 10/2012
 GB 2508035 5/2014
 JP 61131720 A 6/1986
 JP 2000140533 A 5/2000
 JP 2002085297 A 3/2002
 JP 2003135335 A 5/2003
 JP 2005040246 A 2/2005
 JP 2006102034 A 4/2006
 JP 2008206613 A 9/2008
 JP 2009261501 A 11/2009
 JP 2010081968 A 4/2010
 JP 2010178773 A 8/2010
 JP 2010220632 A 10/2010
 JP 2011189132 A 9/2011
 JP 2011189133 A 9/2011
 JP 2013086228 A 5/2013
 KR 1020010045598 A 6/2001
 KR 1020020067489 A 8/2002
 KR 1020020085478 A 11/2002
 KR 1020040050174 A 6/2004
 KR 1020060008365 A 1/2006
 KR 1020060118795 A 11/2006
 KR 1020060118800 A 11/2006
 KR 1020060118802 A 11/2006
 KR 1020060118803 A 11/2006
 KR 1020060122249 A 11/2006
 KR 1020060125952 A 12/2006
 KR 1020060125954 A 12/2006
 KR 1020100084127 A 7/2010
 WO 1980002561 A1 11/1980
 WO 9627446 A1 9/1996
 WO 9720492 A1 6/1997
 WO 9809121 A1 3/1998
 WO 9843721 A1 10/1998
 WO 01/07168 A1 2/2001
 WO 0147247 A2 6/2001
 WO 0147247 A3 11/2001
 WO 02/017766 A3 3/2002
 WO 2004069021 A1 8/2004
 WO 2006076363 A2 7/2006
 WO 2006076363 A3 12/2006
 WO 2006026414 A3 8/2007
 WO 2008009883 A1 1/2008
 WO 2008009888 A1 1/2008
 WO 2008009890 A1 1/2008
 WO 2008009891 A1 1/2008
 WO 2008035032 A2 3/2008
 WO 2008070973 A1 6/2008
 WO 2008088278 A2 7/2008
 WO 2008135708 A1 11/2008
 WO 2009026709 A1 3/2009
 WO 2010102396 A1 9/2010
 WO 2010142968 A1 12/2010
 WO 2010142969 A1 12/2010
 WO 2010142970 A1 12/2010
 WO 2010142971 A1 12/2010
 WO 2011054106 A1 5/2011
 WO 2012042240 A1 4/2012
 WO 2012117231 A1 9/2012
 WO 2015129387 A1 9/2015
 WO 2016065151 A1 4/2016
 WO 2017046557 A1 3/2017
 WO 2017046559 A1 3/2017
 WO 2017046560 A1 3/2017

OTHER PUBLICATIONS

English machine translation of CN101108106A published on Jan. 23, 2008.
 English machine translation of CN101108110A published on Jan. 23, 2008.
 English machine translation of CN1336154A published on Feb. 20, 2002.
 English machine translation of CN1434688A published on Aug. 6, 2003.
 English machine translation of CN1875846A published on Dec. 13, 2006.

(56)

References Cited

OTHER PUBLICATIONS

English machine translation of CN1875855A published on Dec. 13, 2006.

English machine translation of CN201290642Y published on Aug. 19, 2009.

English machine translation of DE10056935C2 published on Jan. 16, 2003.

English machine translation of DE102007011457A1 published on Oct. 25, 2007.

English machine translation of DE102012211246A1 published on Jan. 2, 2014.

English machine translation of DE112010001135T5 published on Aug. 2, 2012.

English machine translation of DE60201666T2 published on Jun. 1, 2006.

English machine translation of DE60211663T2 published on May 10, 2007.

English machine translation of DE69907201T2 published on Feb. 5, 2004.

English machine translation of EP1815777A1 published on Aug. 8, 2007.

English machine translation of JP2003135335A published on May 13, 2003.

English machine translation of JP2005040246A published on Feb. 17, 2005.

English machine translation of JP2009261501A published on Nov. 12, 2009.

English machine translation of JP2010081968A published on Apr. 15, 2010.

English machine translation of KR1020010045598A published on Jun. 5, 2001.

English machine translation of KR1020020067489A published on Aug. 22, 2002.

English machine translation of KR1020020085478A published on Nov. 16, 2002.

English machine translation of KR1020040050174A published on Jun. 16, 2004.

English machine translation of KR1020060008365A published on Jan. 26, 2006.

English machine translation of KR1020060118795A published on Nov. 24, 2006.

English machine translation of KR1020060118800A published on Nov. 24, 2006.

English machine translation of KR1020060118802A published on Nov. 24, 2006.

English machine translation of KR1020060118803A published on Nov. 24, 2006.

English machine translation of KR1020060122249A published on Nov. 30, 2006.

English machine translation of KR1020060125952A published on Dec. 7, 2006.

English machine translation of KR1020060125954A published on Dec. 7, 2006.

English machine translation of KR1020100084127A published on Jul. 23, 2010.

English machine translation of CN204363891U published on Jun. 3, 2015.

English machine translation of JP2008206613A published on Sep. 11, 2008.

English machine translation of JP2002085297A published on Mar. 26, 2002.

English machine translation of WO2015129387A1 published on Sep. 3, 2015.

English machine translation of CN202739907U published on Feb. 20, 2013.

English machine translation of CN205671986U published on Nov. 9, 2016.

English machine translation of CN105816104A published on Aug. 3, 2016.

English machine translation of JP2013086228A published on May 13, 2013.

English machine translation of JP2006102034A published on Apr. 20, 2006.

Office Action dated Jul. 7, 2010, for Canadian Patent Application No. 2,675,714.

The Office Action received in connection to the corresponding US Patent Application No. 200880126486.6 dated Mar. 23, 2012.

The Office Action received in connection to the related Chinese Patent Application No. 00813438.3 dated Jul. 11, 2003.

Combined Search and Examination Report under Sections 17 & 18(3) received in connection to the corresponding GB Patent Application No. 1522195.5 dated Jun. 16, 2016.

Combined Search and Examination Report under Sections 17 & 18(3) received in connection to the corresponding GB Patent Application No. 1706875.0 dated May 25, 2017.

European Communication pursuant to Article 94(3) on European Patent Application No. 04078261.7, dated Apr. 24, 2012.

European Communication pursuant to Article 94(3) on European Patent Application No. 04078261.7, dated Feb. 26, 2010.

International Preliminary Examination Report on International application No. PCT/CA2015/051332, dated Mar. 7, 2016.

International Preliminary Report on Patentability in International Application No. PCT/CA2015/051332 dated Jun. 29, 2017.

International Search Report and Written Opinion received in connection to International patent application No. PCT/CA2017/050436, dated Jul. 21, 2017.

International Search Report and Written Opinion received in connection to International patent application No. PCT/CA2017/050014, dated Apr. 5, 2017.

International Preliminary Report on Patentability, dated Sep. 16, 2008 for International application No. PCT/CA2007/000380.

Supplementary European Search Report, dated Jun. 16, 2009, as received on the corresponding EP application No. 07719394.4.

Handbook of Air Pollution Prevention and Control, pp. 397-404, 2002.

International Preliminary Examination Report on International application No. PCT/CA00/00873, dated Oct. 26, 2001.

International Search Report and Written Opinion received in connection to International patent application No. PCT/CA2007/002211, dated Apr. 21, 2008.

International Search Report and Written Opinion received in connection to international patent application No. PCT/CA2015/050661, dated Oct. 19, 2015.

Euro-Pro Shark Cordless Hand Vac Owner's Manual, published in 2002.

International Search Report and Written Opinion received in connection to international patent application No. PCT/CA2014/000133, dated May 26, 2014.

Instruction manual: Makita Cordless Cleaner, Handy Vac II, Model 4071D; dated at least as early as 1993.

* cited by examiner

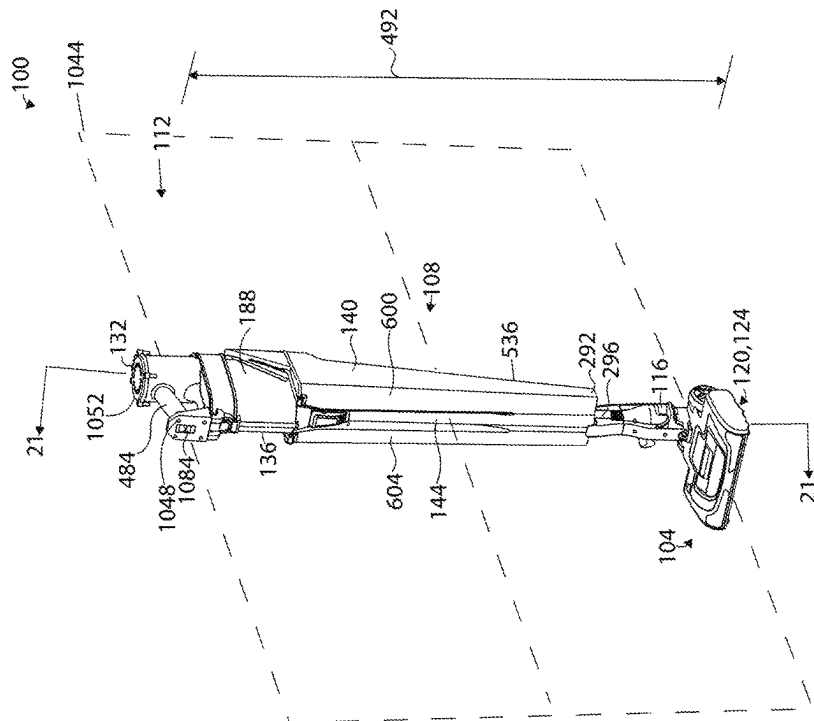


FIG. 1

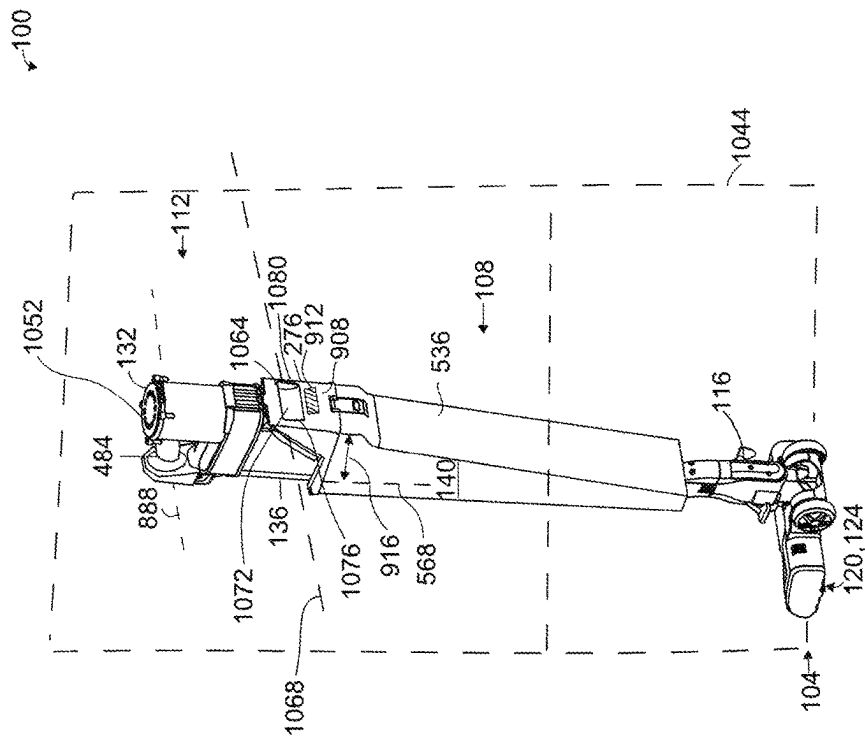


FIG. 2

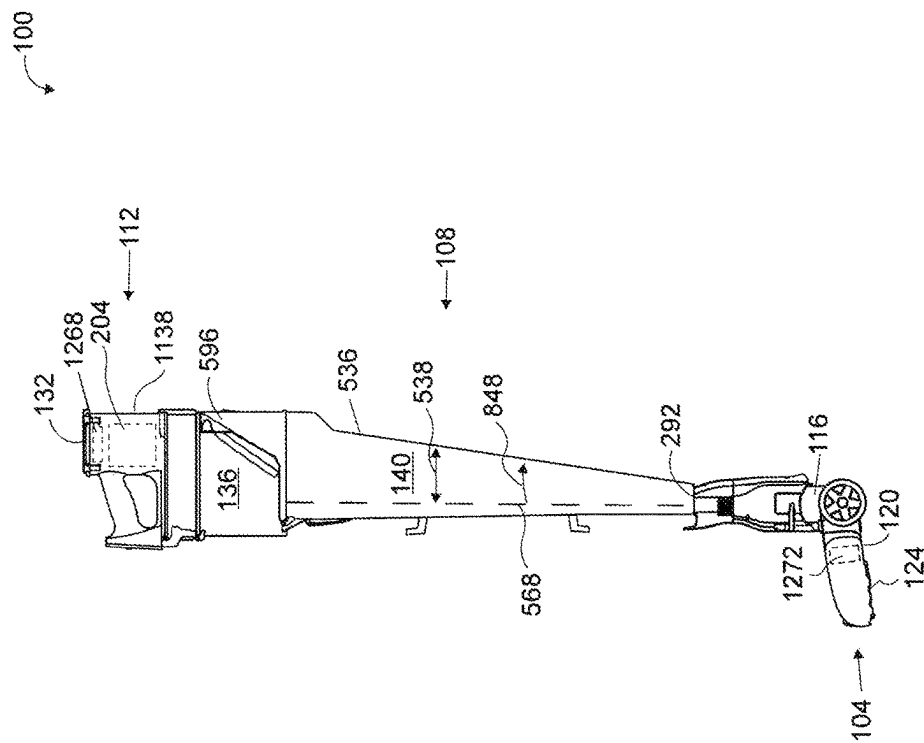


FIG. 3

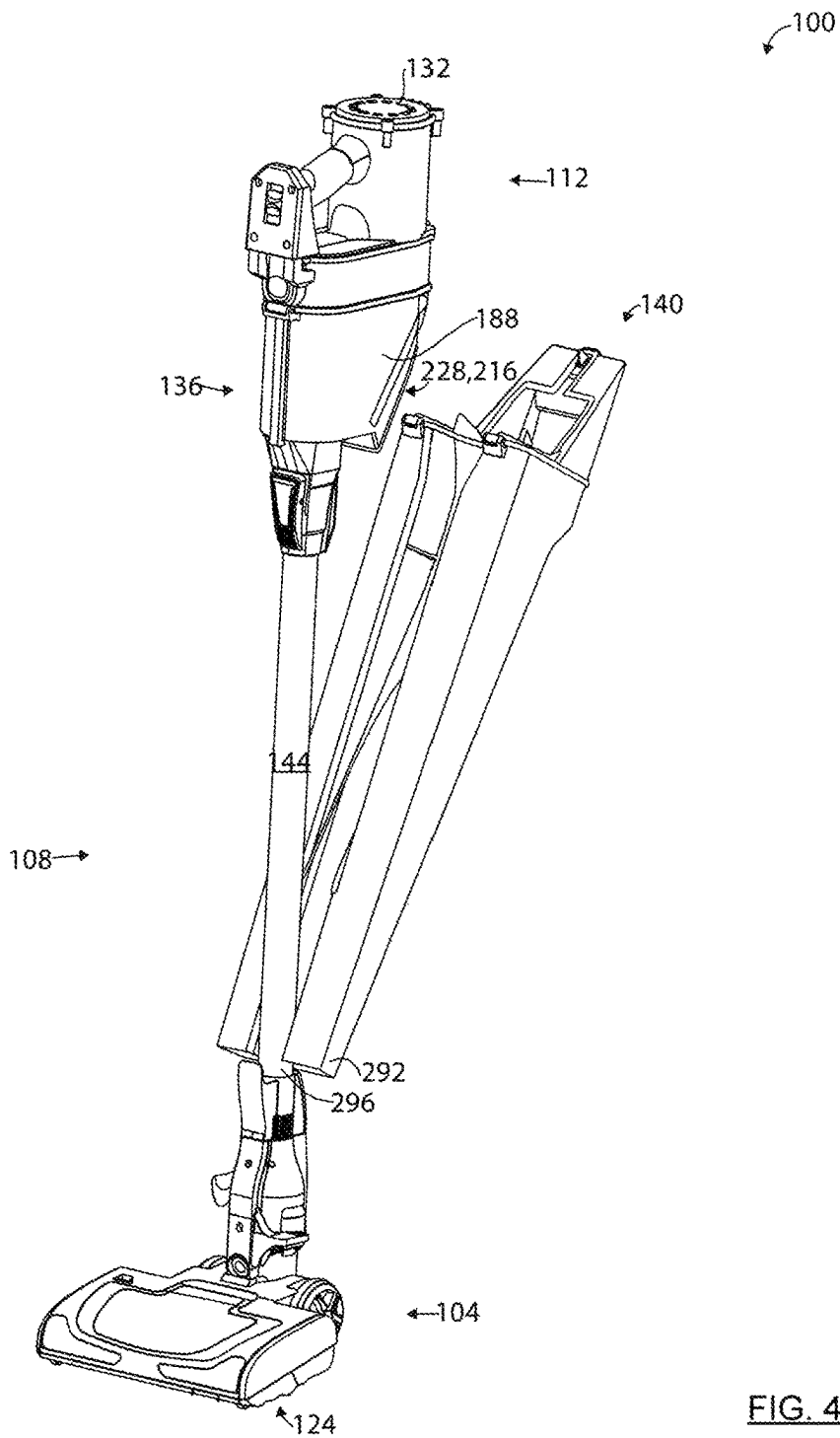


FIG. 4

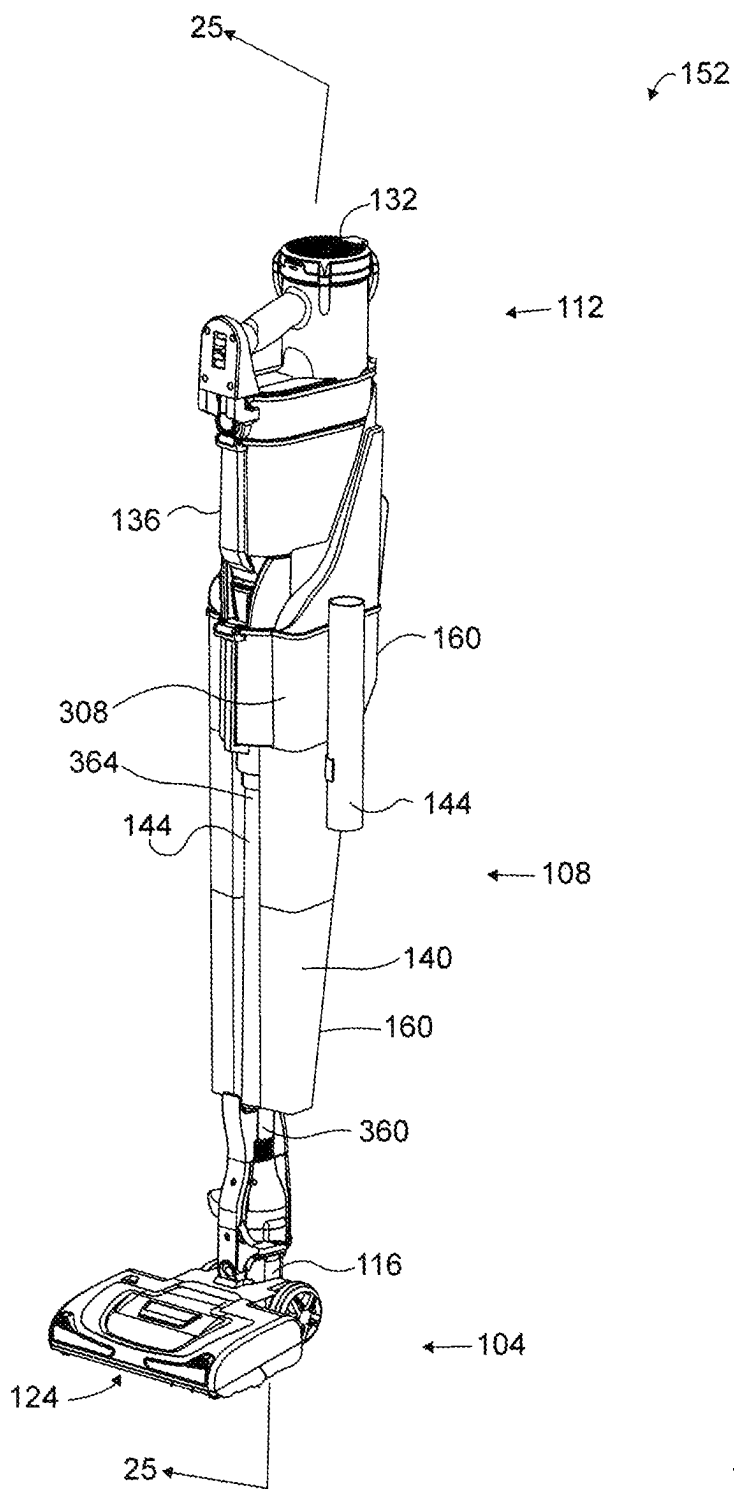


FIG. 5

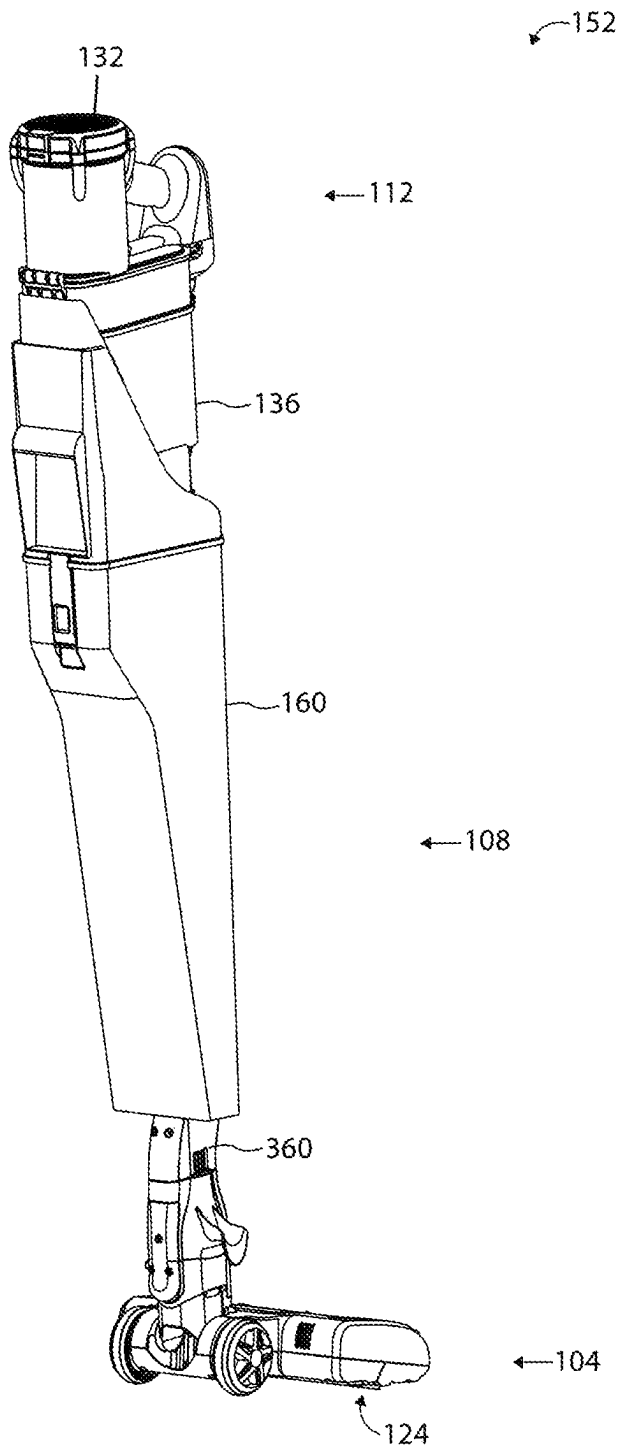


FIG. 6

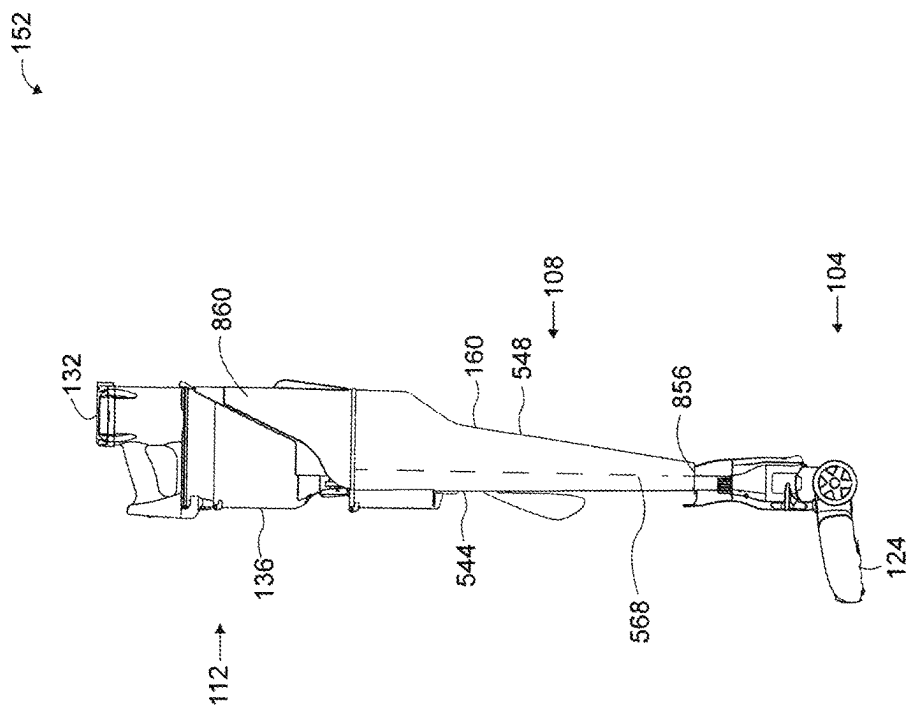


FIG. 7

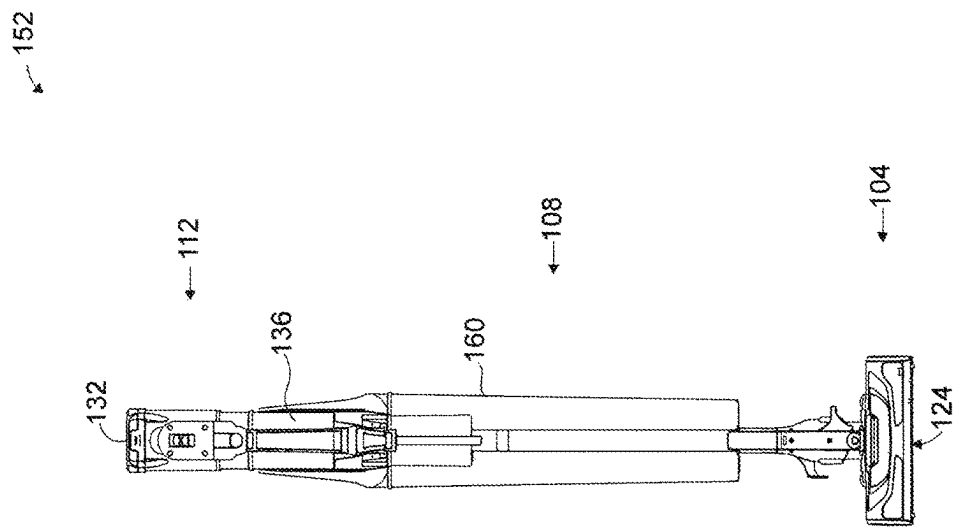


FIG. 8

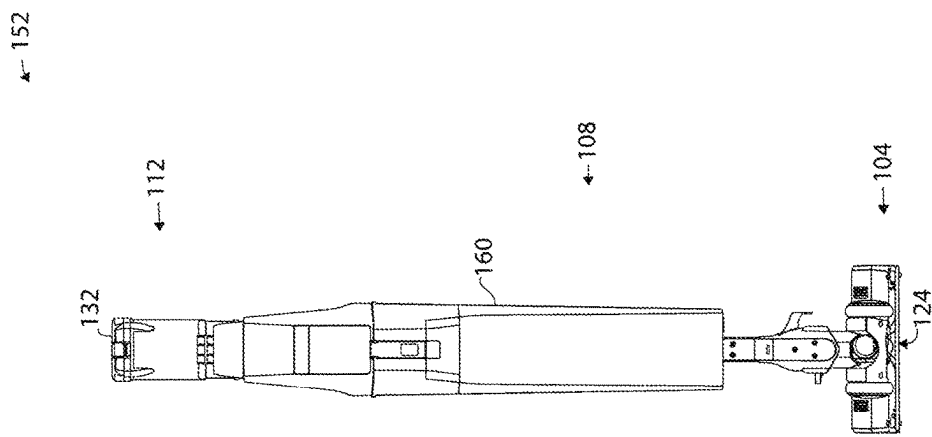


FIG. 9

152

104

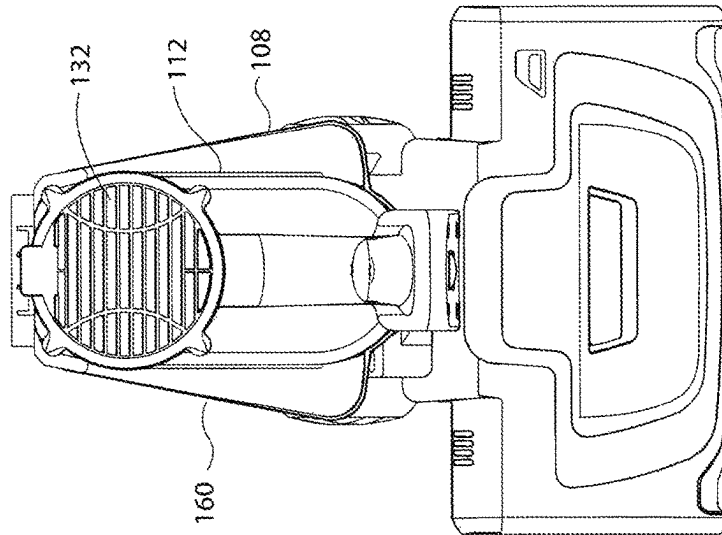
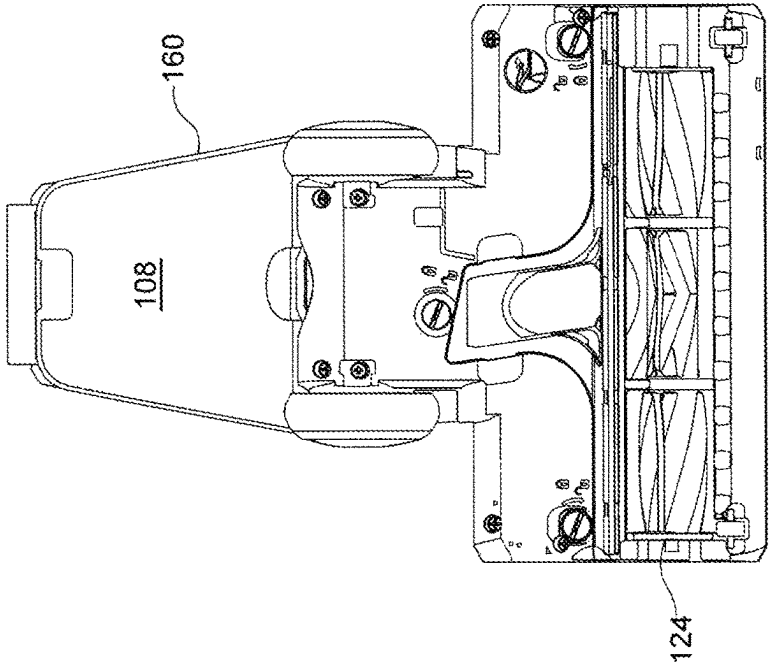


FIG. 10

152



104

FIG. 11

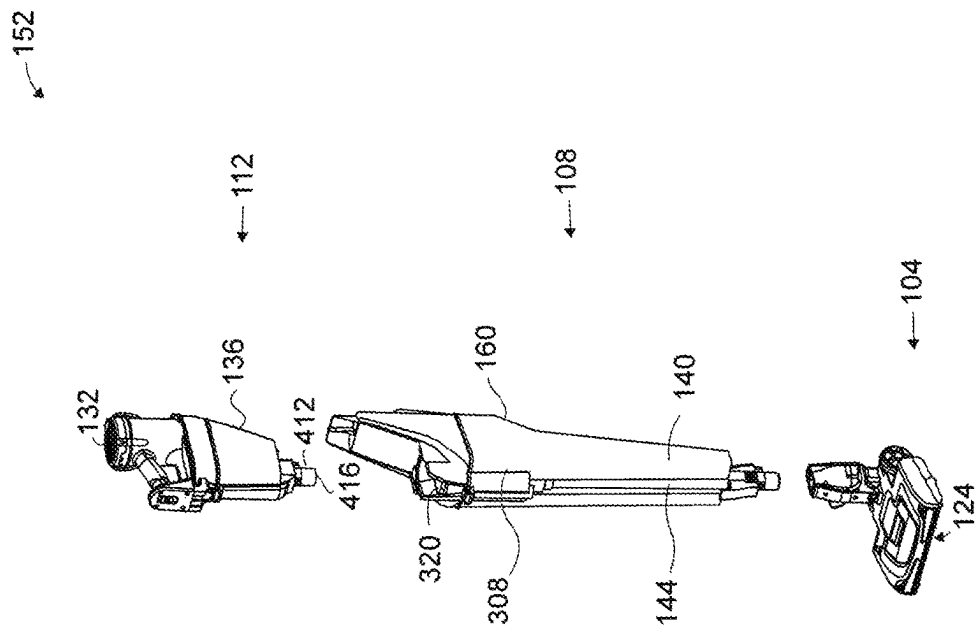


FIG. 12

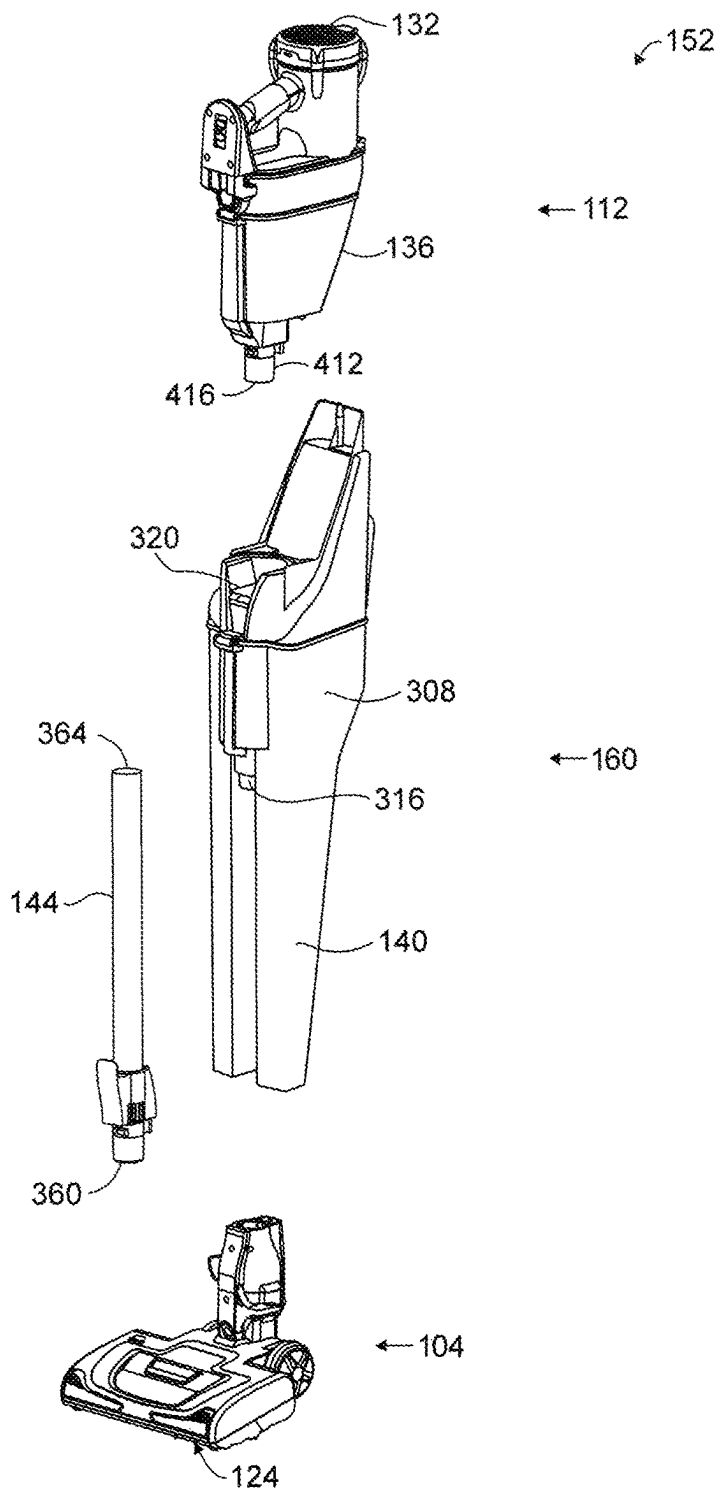


FIG. 12a

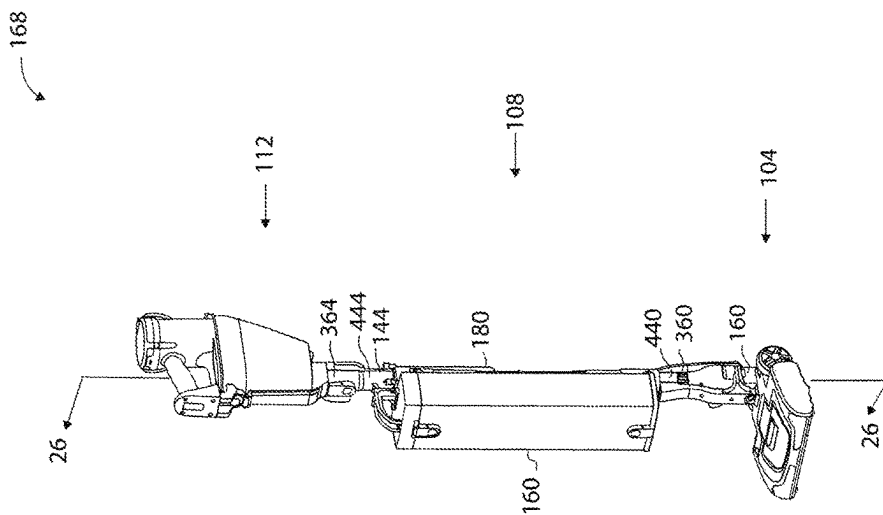


FIG. 13

168

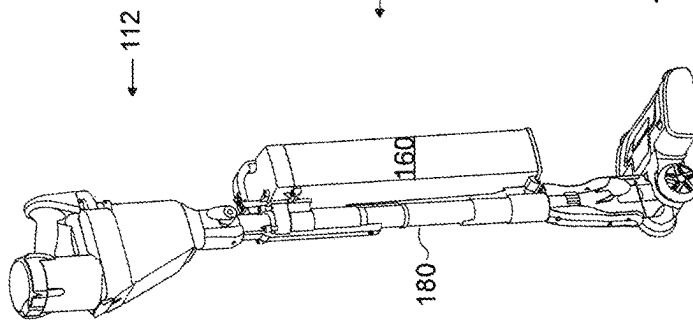
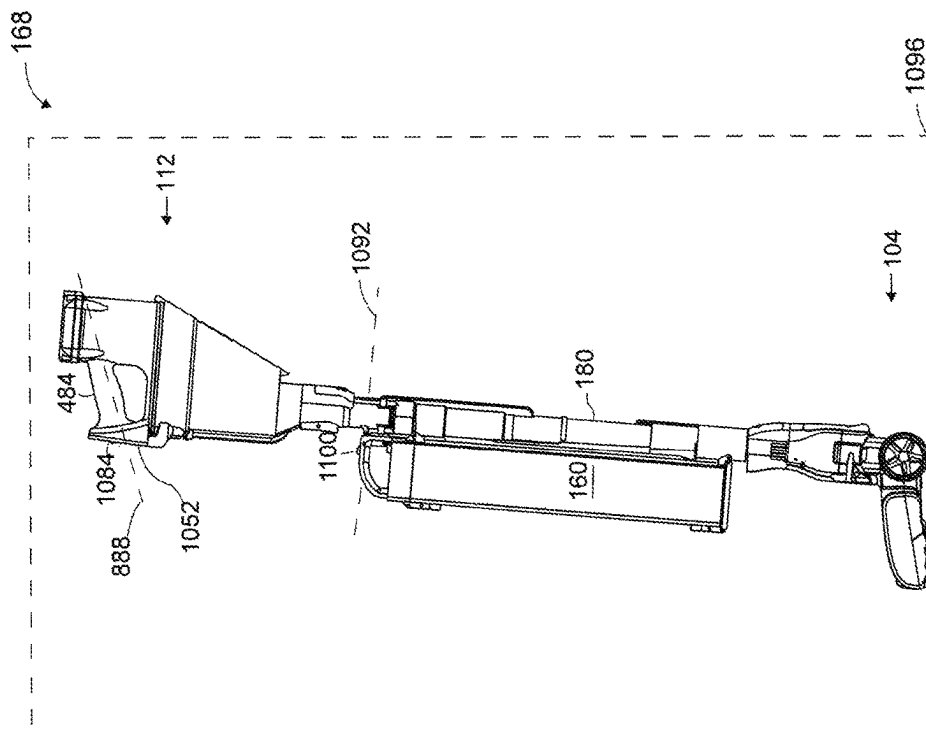


FIG. 14



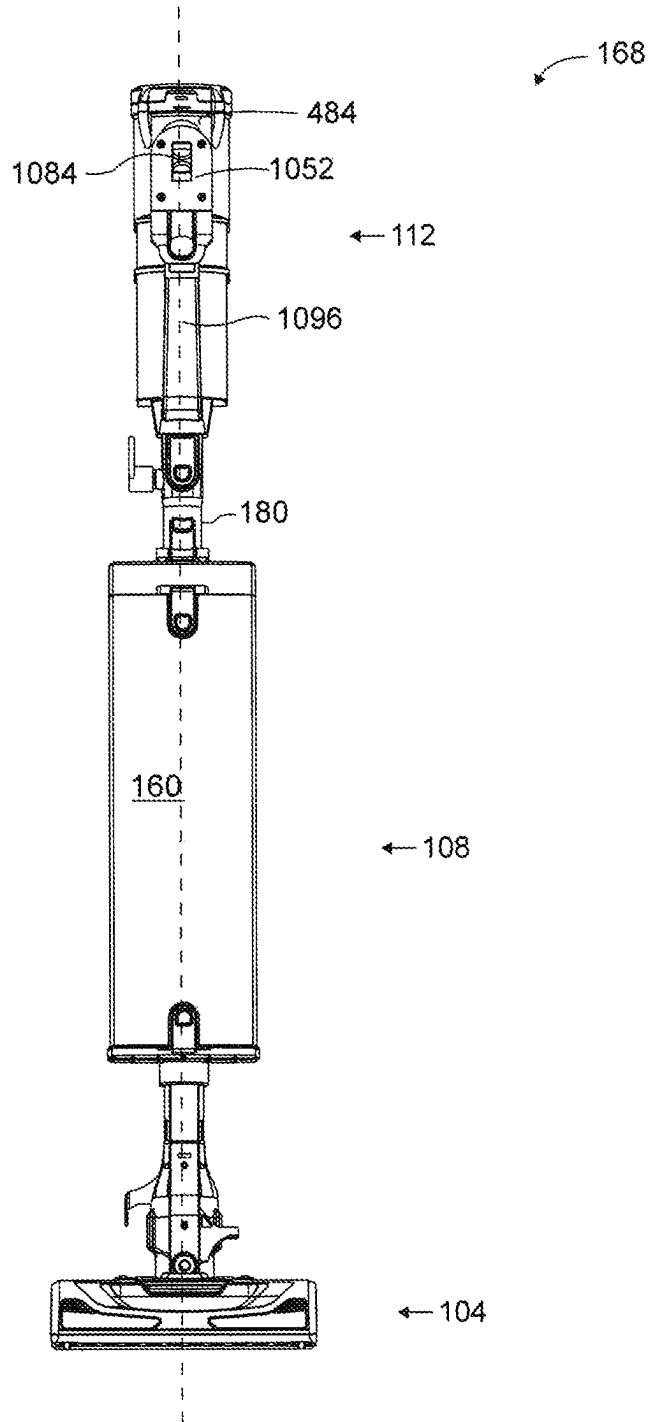


FIG. 16

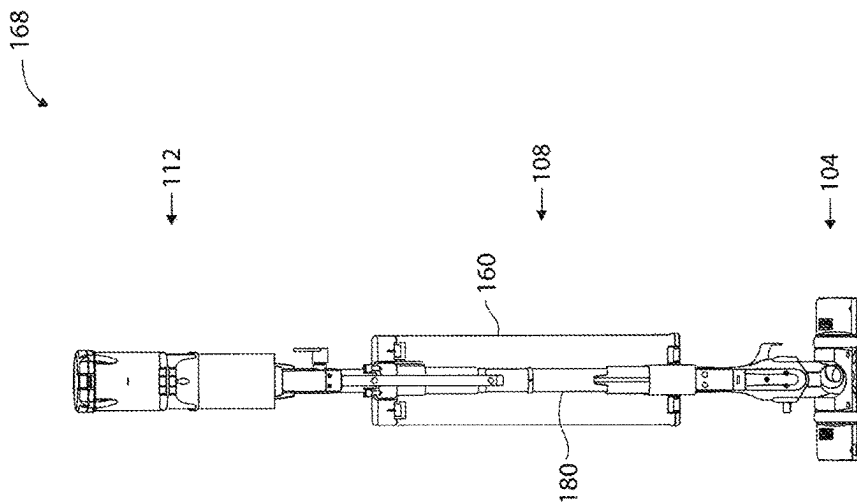


FIG. 17

168

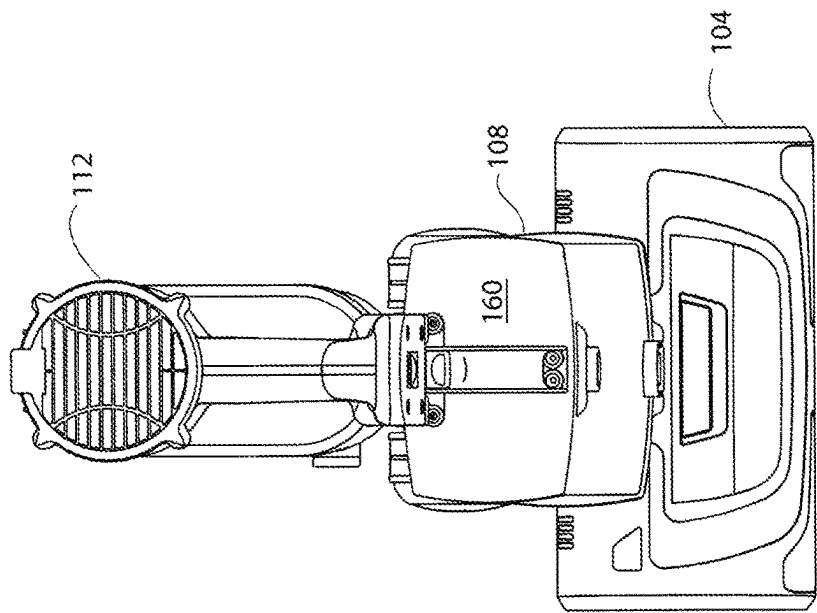


FIG. 18

168

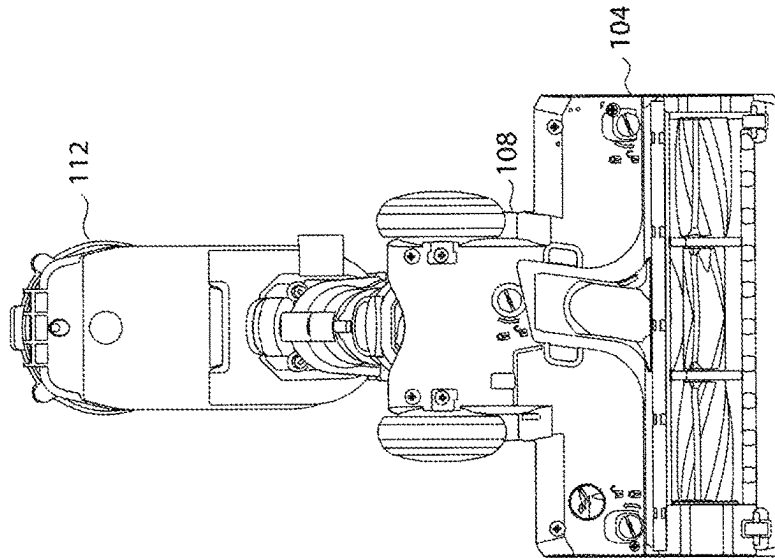


FIG. 19

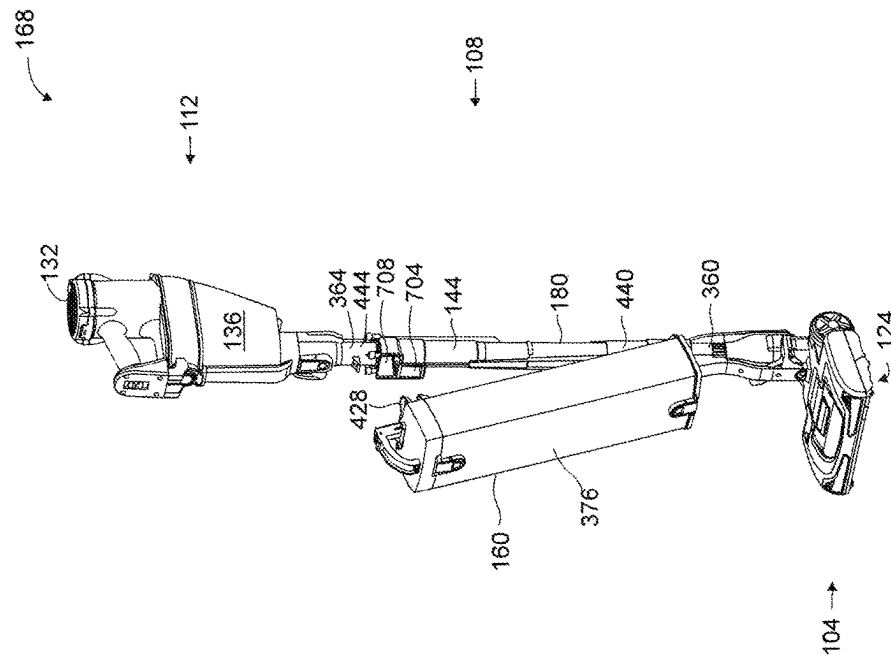


FIG. 20

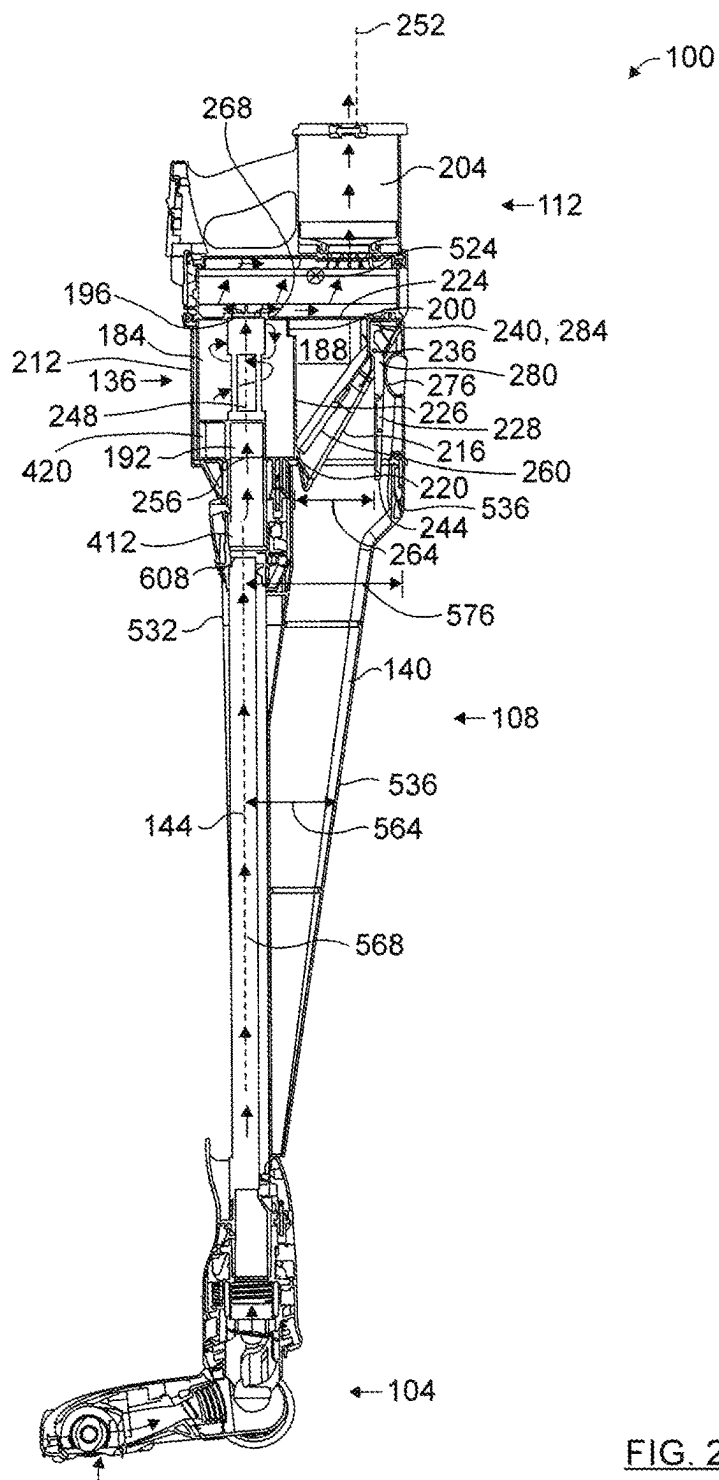


FIG. 21

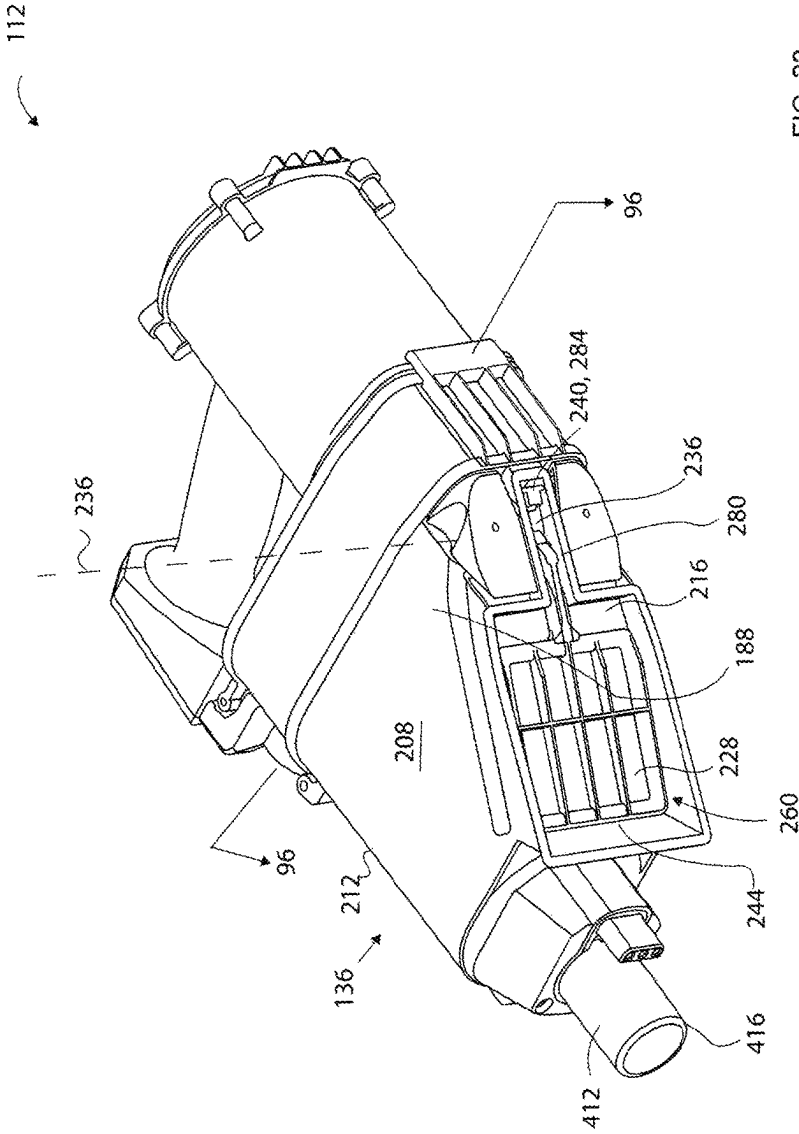


FIG. 22

136

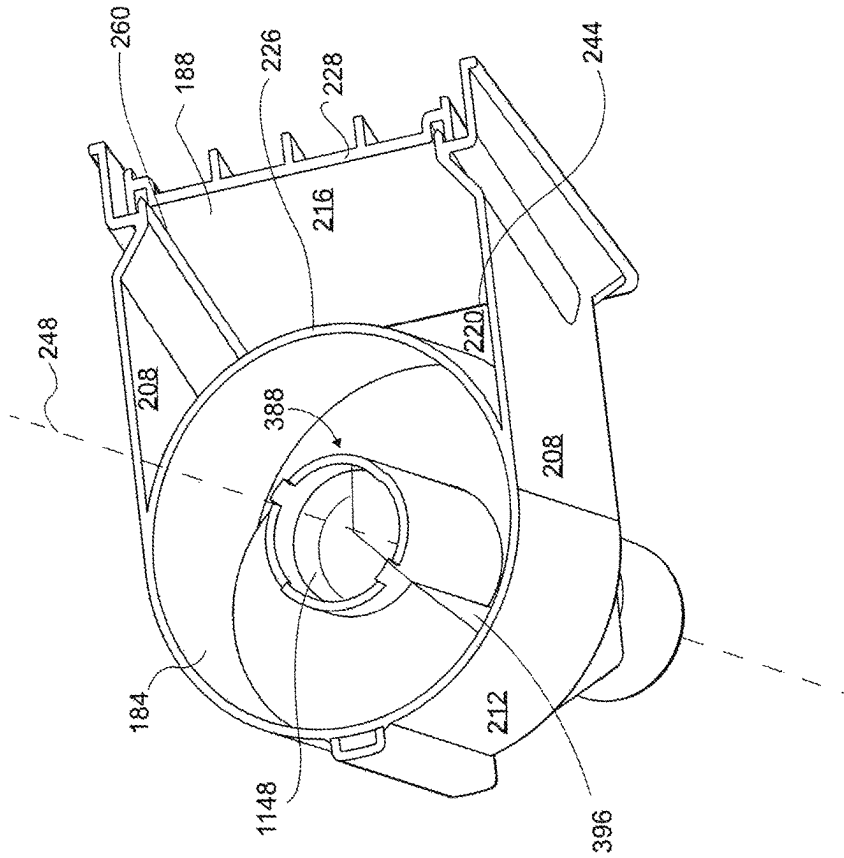


FIG. 23

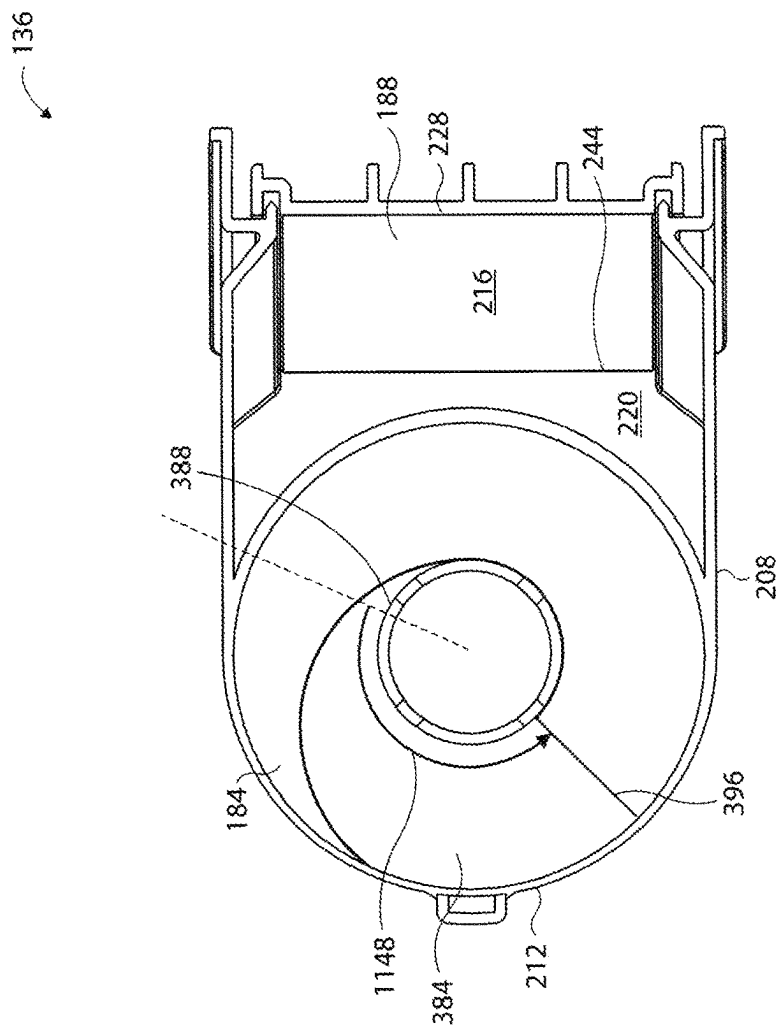


FIG. 23a

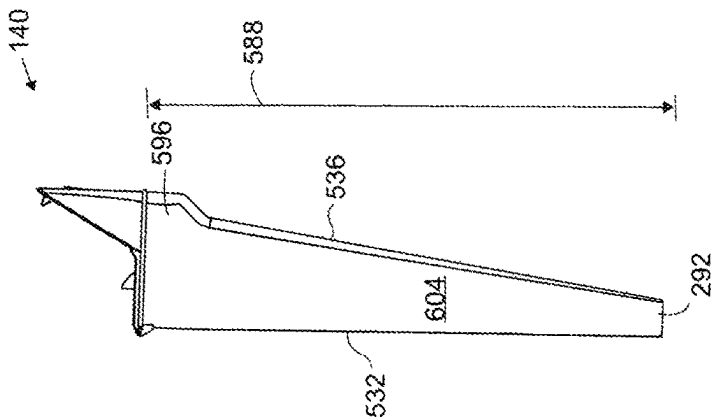


FIG. 46

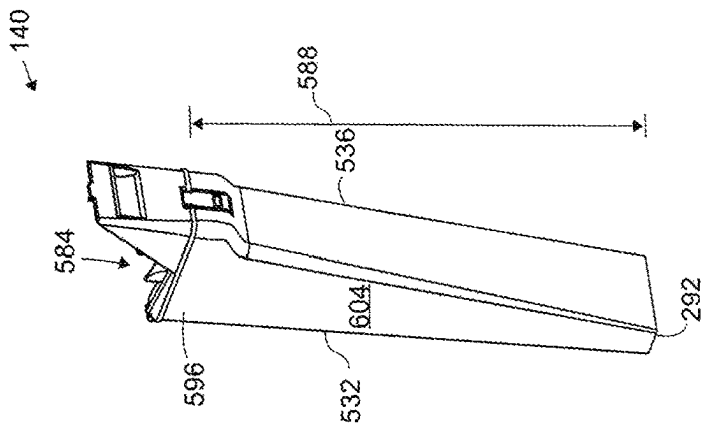


FIG. 45

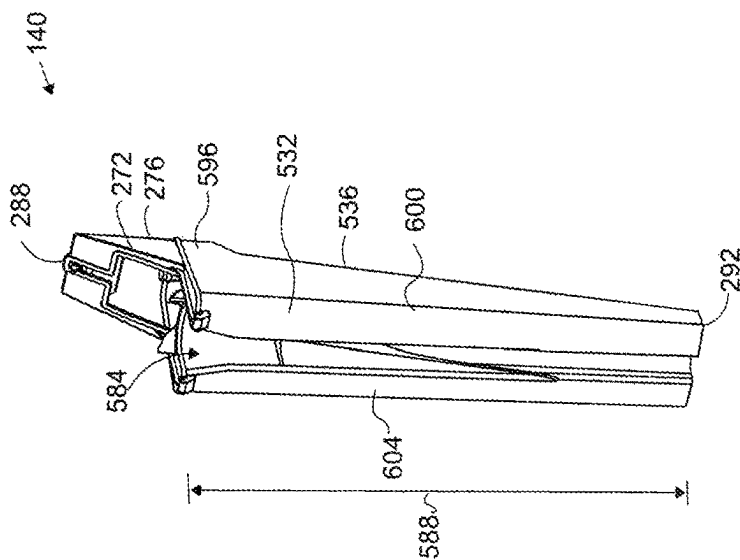


FIG. 24

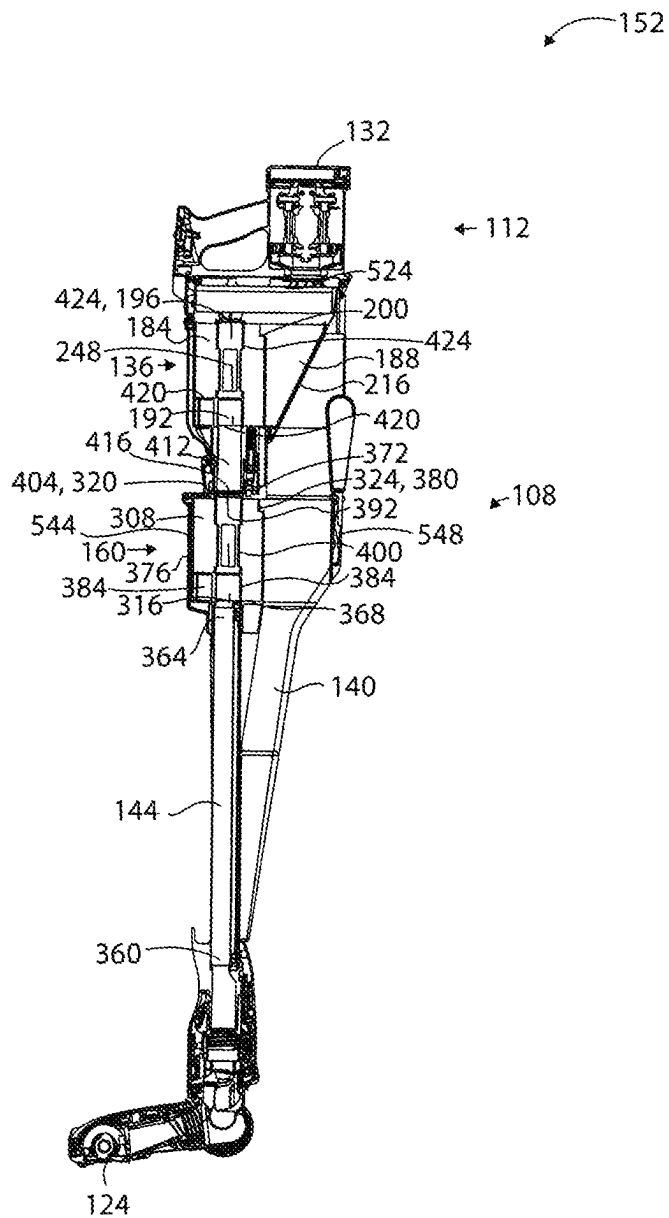
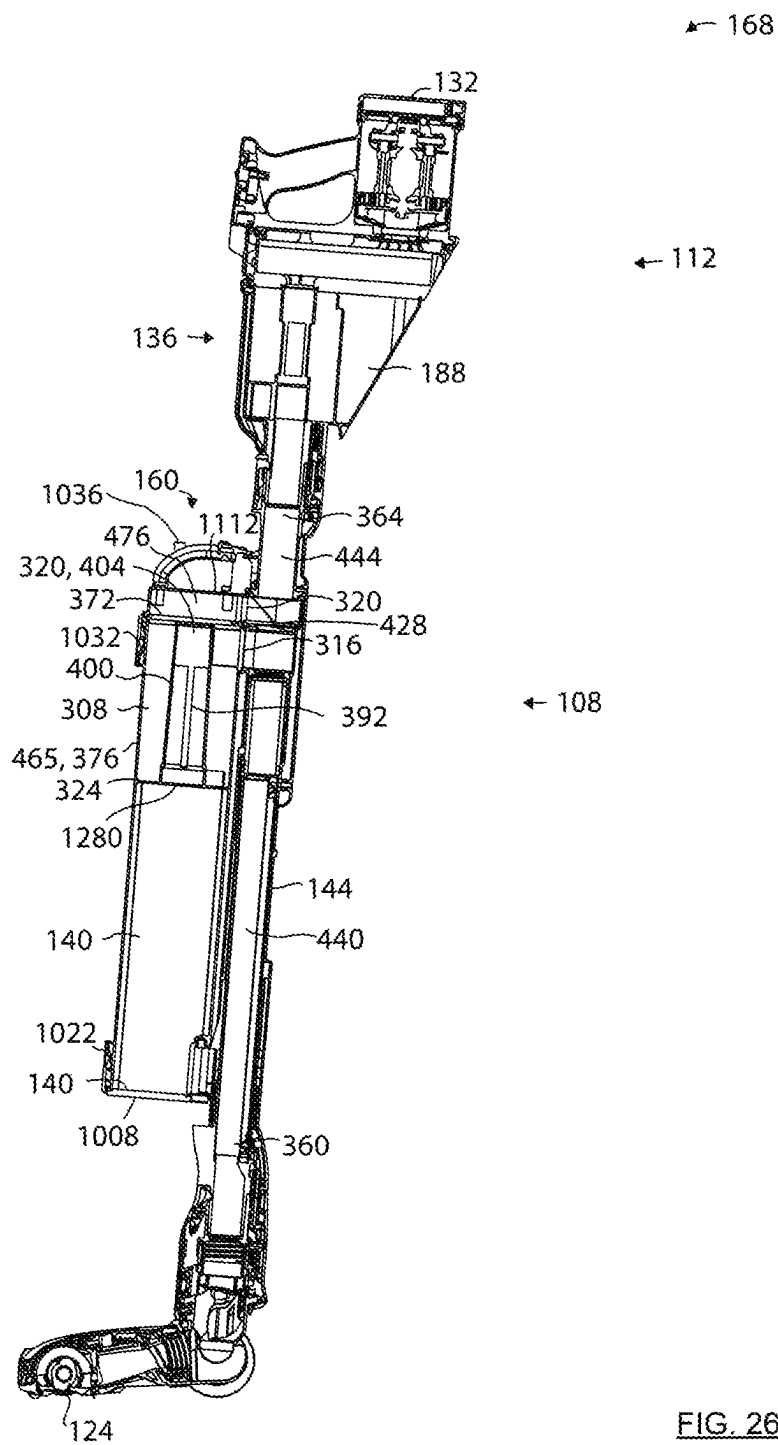


FIG. 25



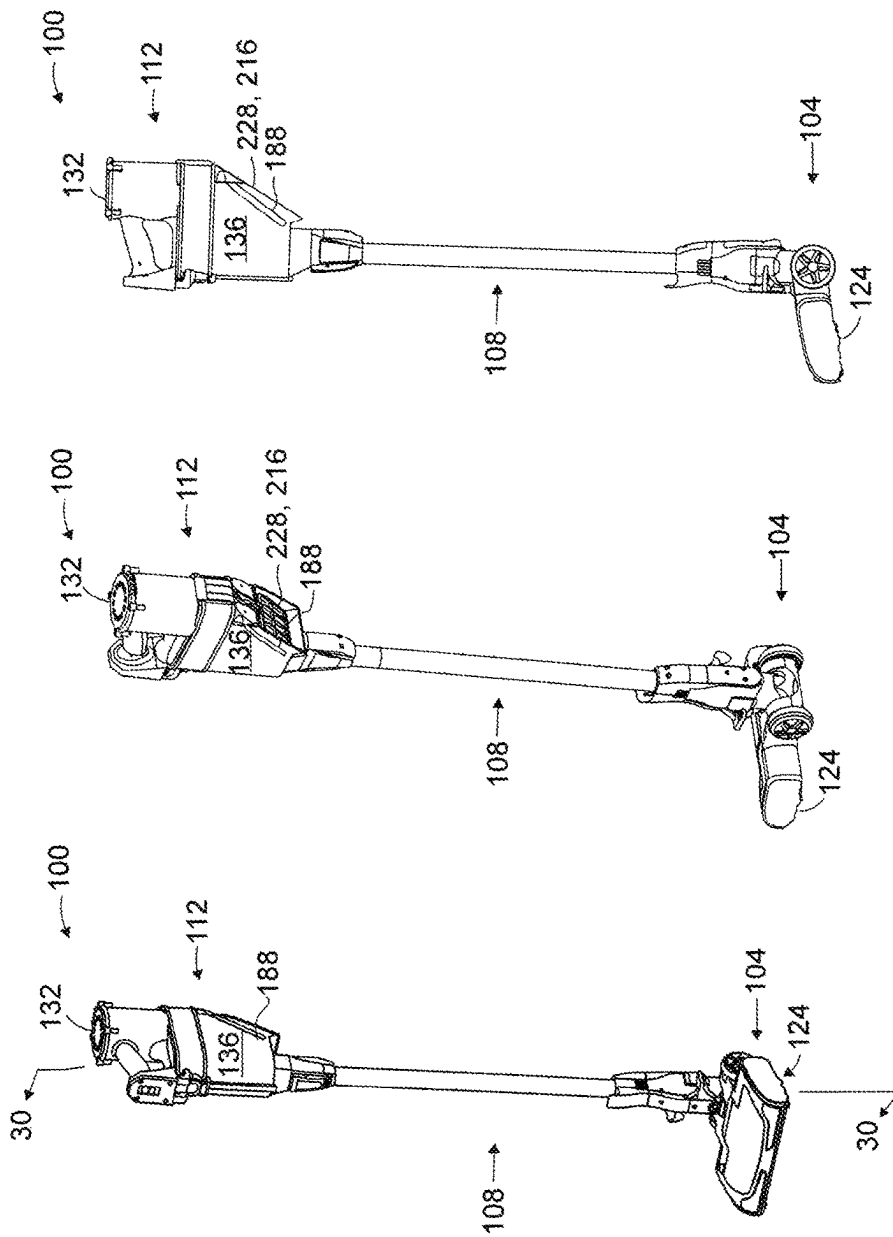


FIG. 29

FIG. 28

FIG. 27

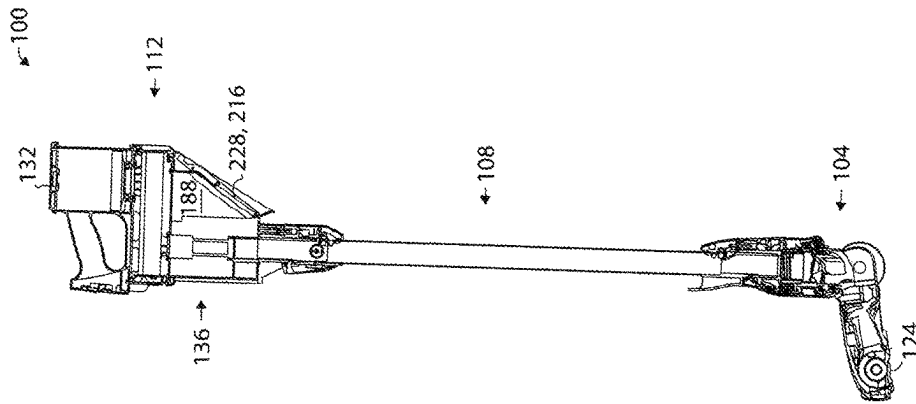


FIG. 30

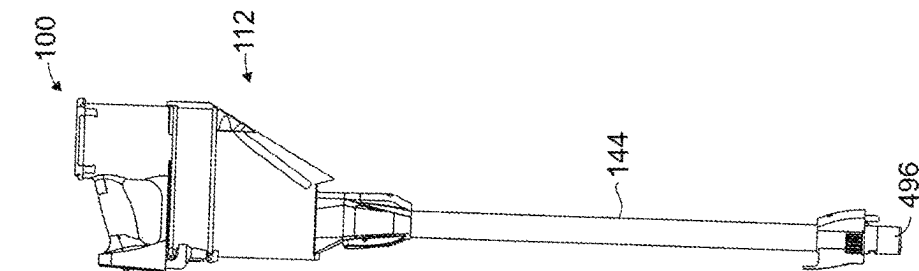


FIG. 31

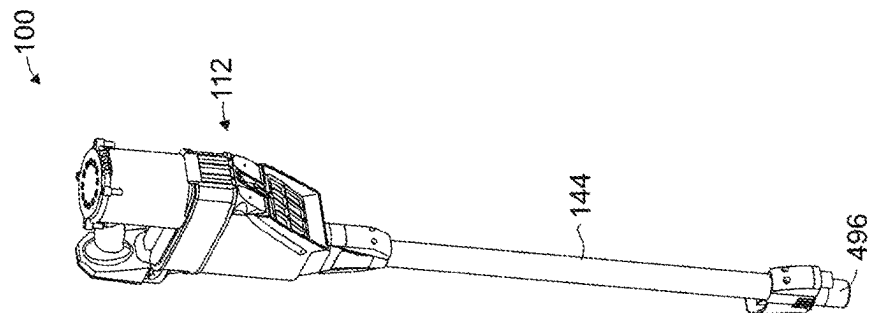


FIG. 32

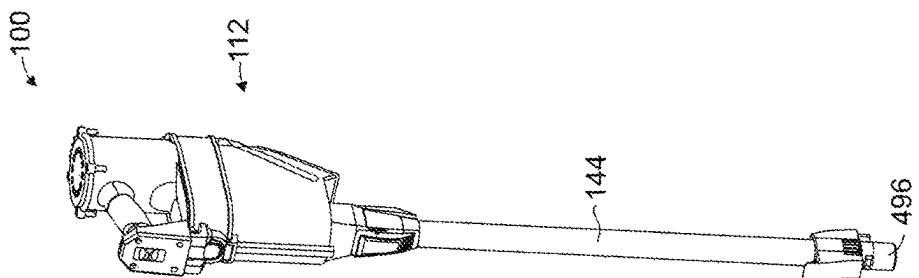


FIG. 33

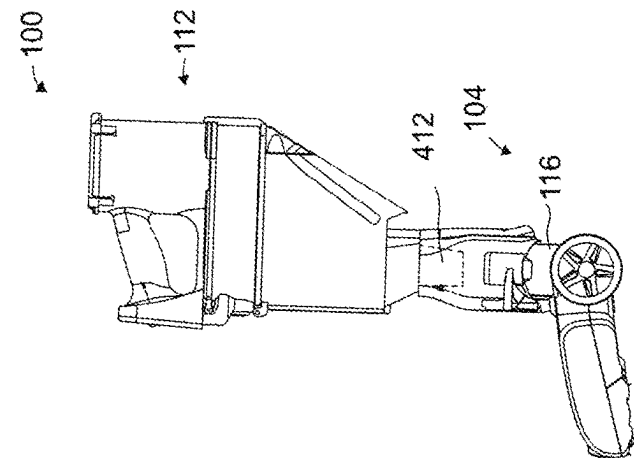


FIG. 34

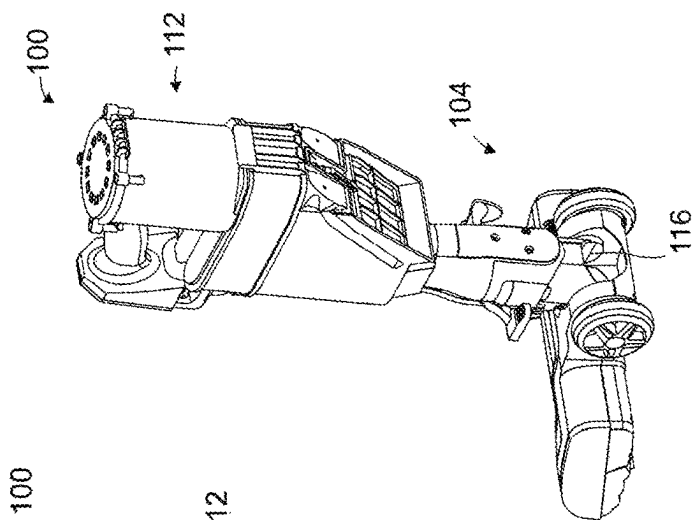


FIG. 35

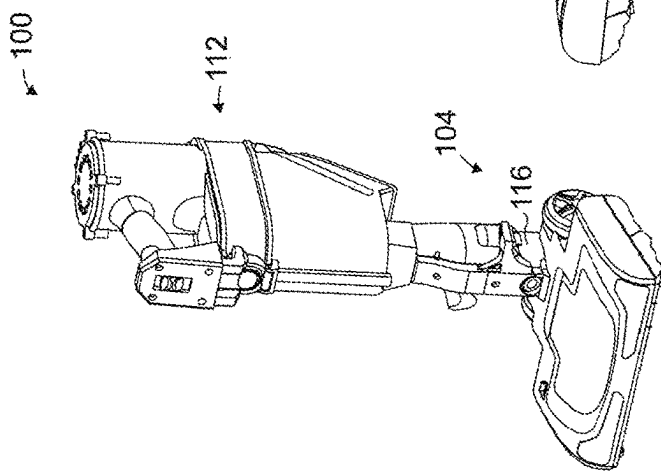


FIG. 36

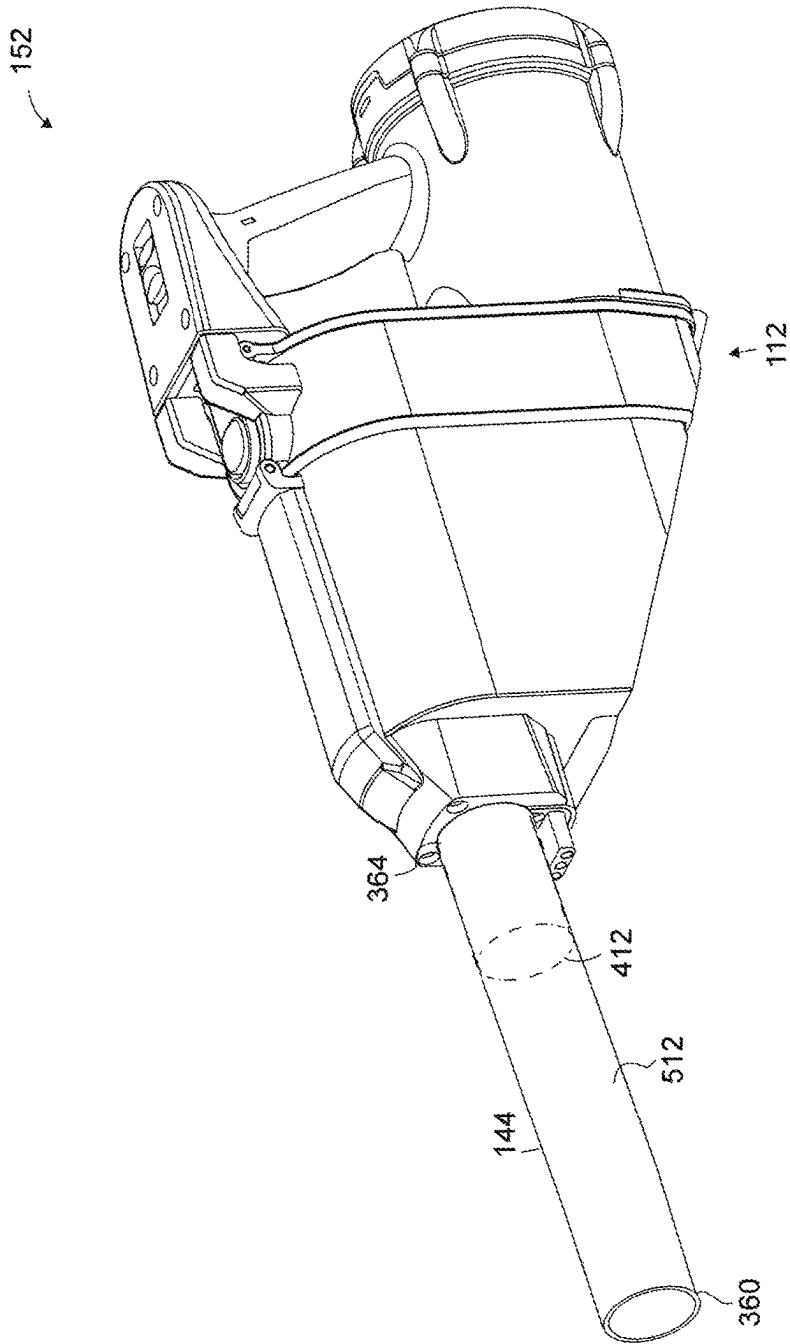


FIG. 36a

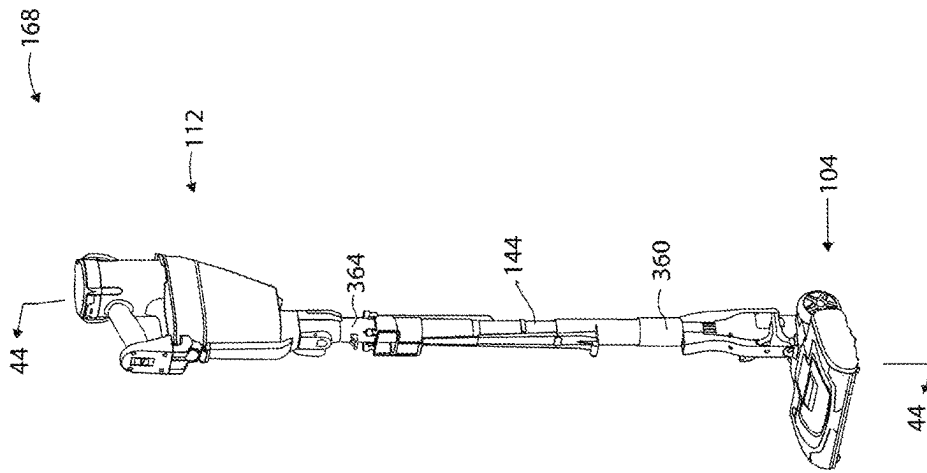


FIG. 37

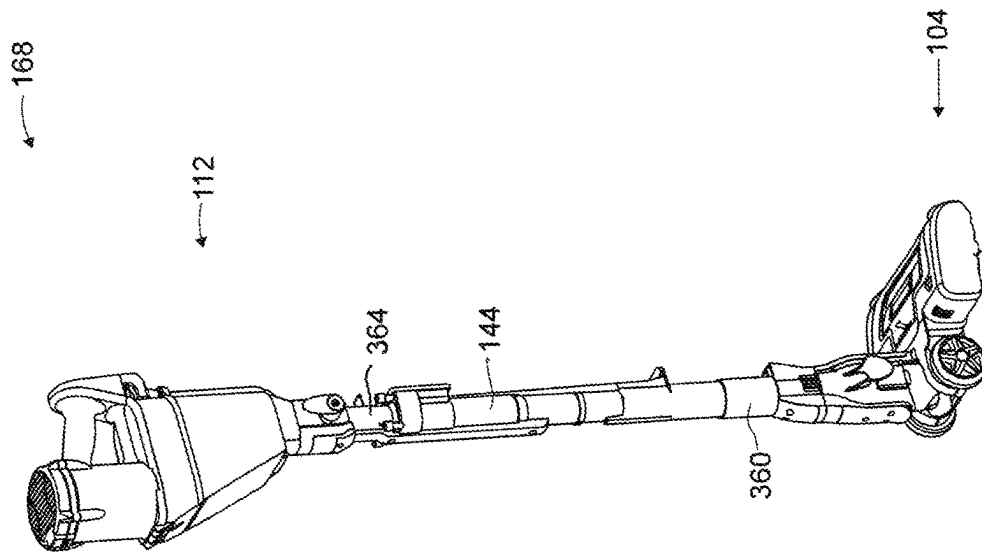


FIG. 38

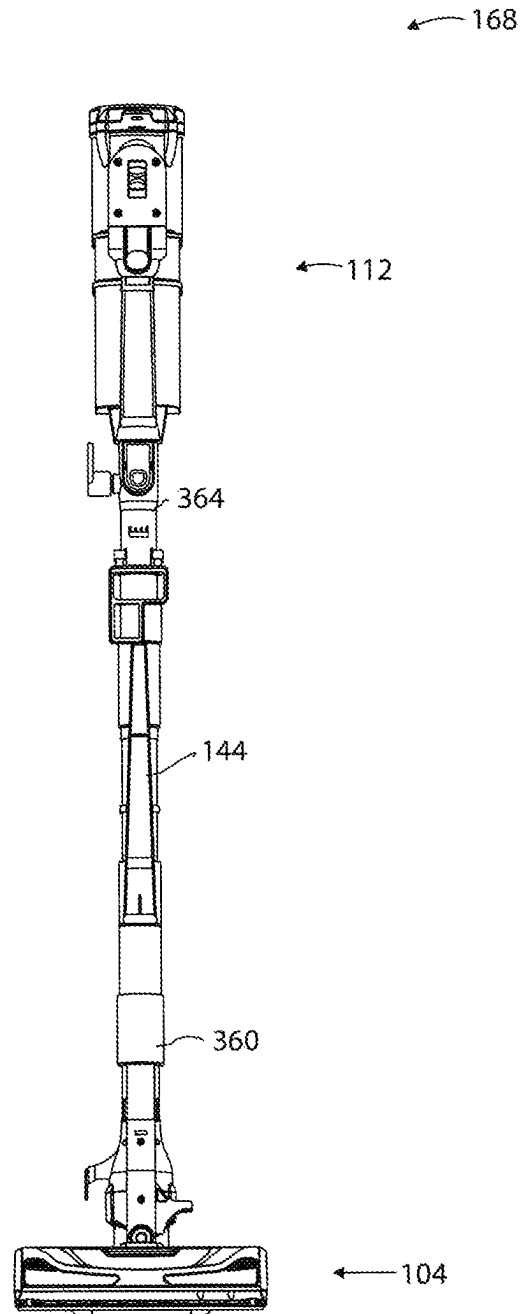


FIG. 39

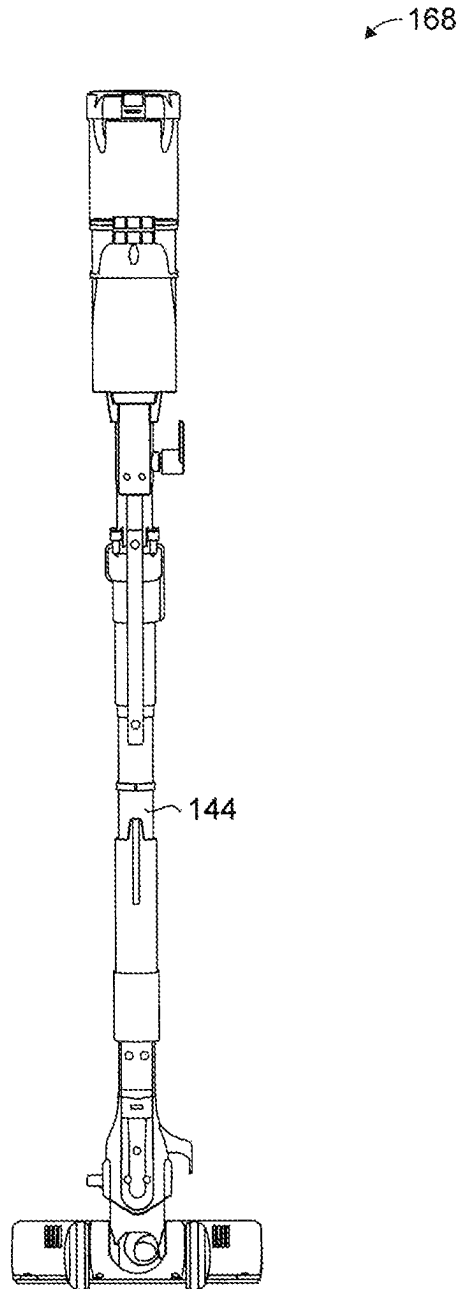


FIG. 40

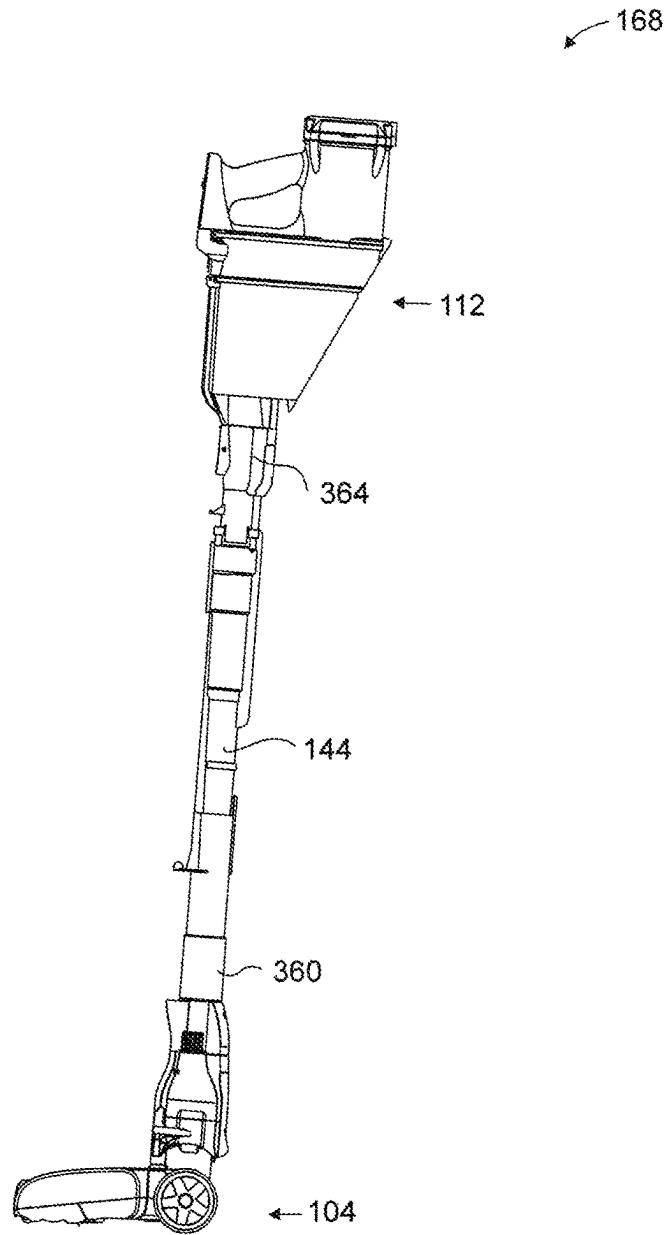


FIG. 41

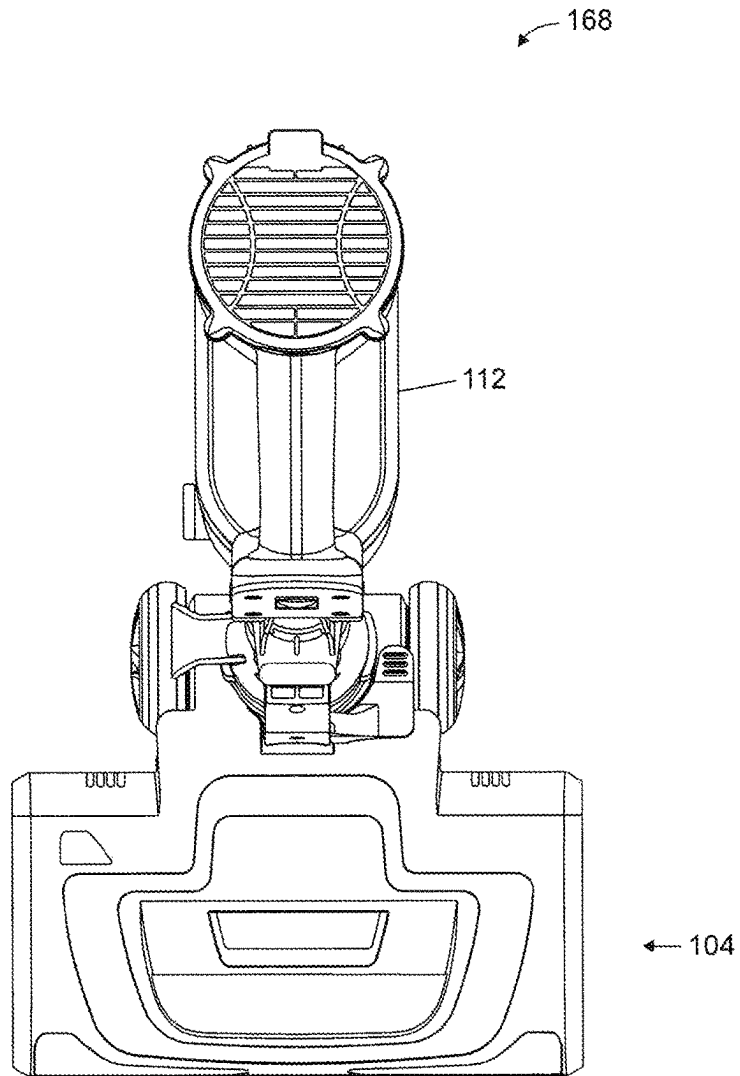


FIG. 42

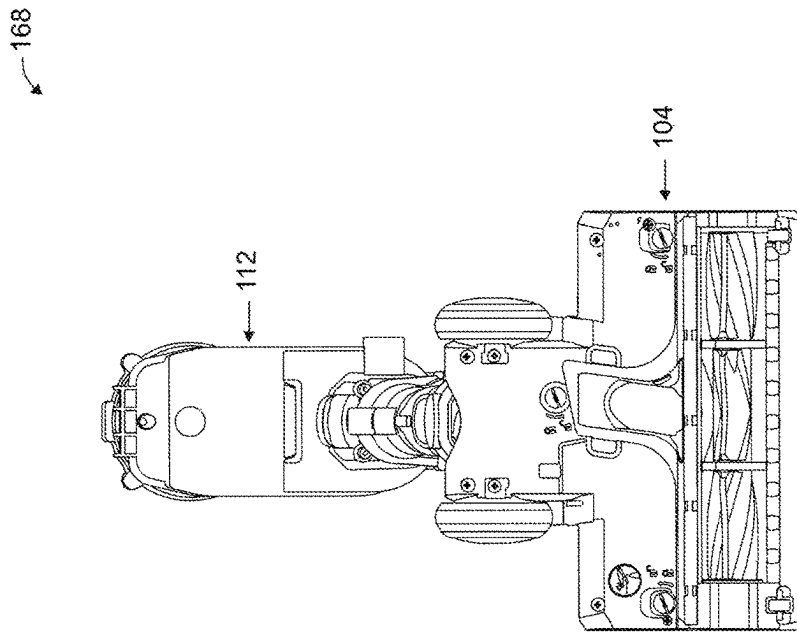


FIG. 43

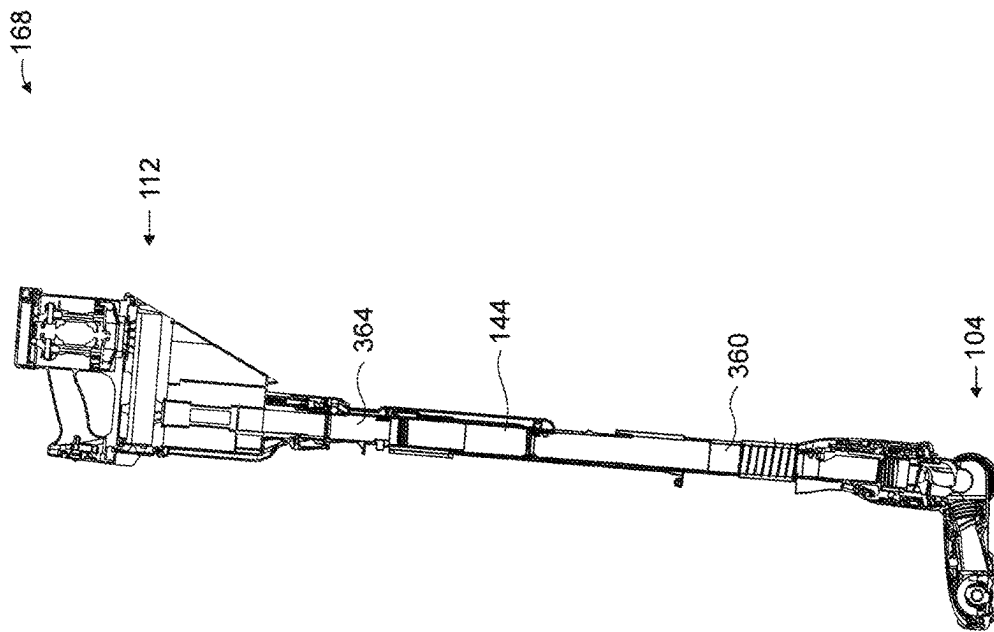


FIG. 44

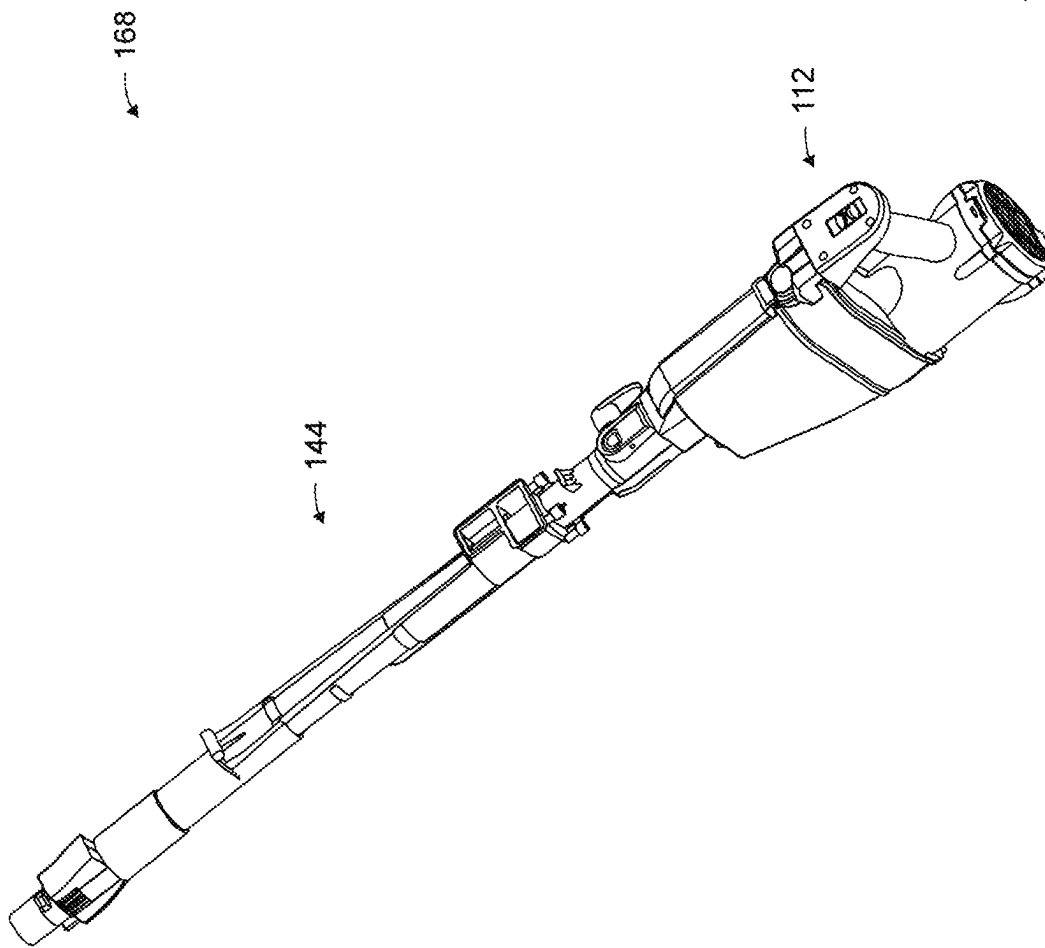


FIG. 44a

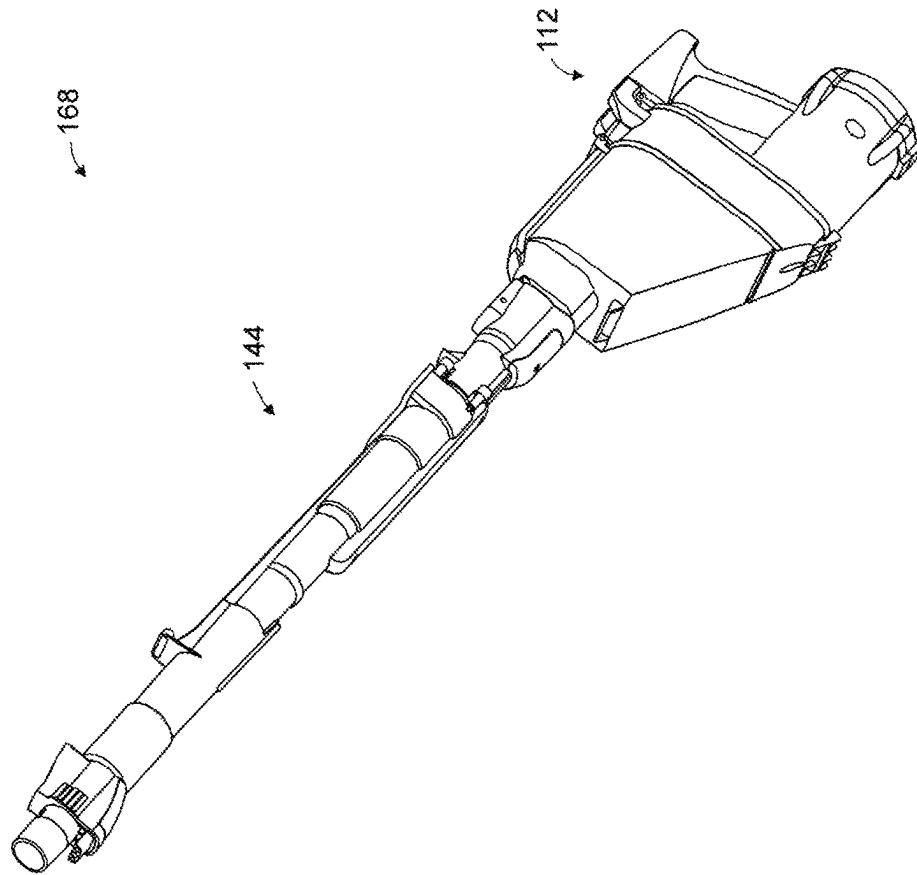


FIG. 44b

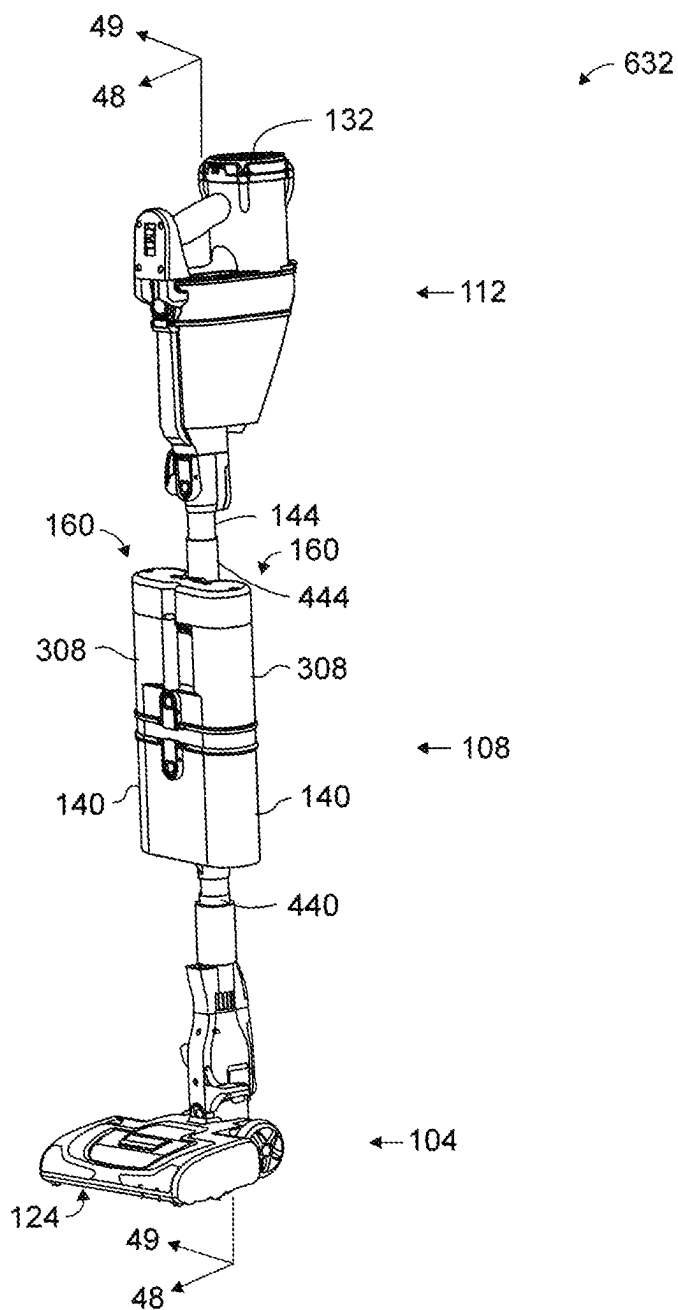


FIG. 47

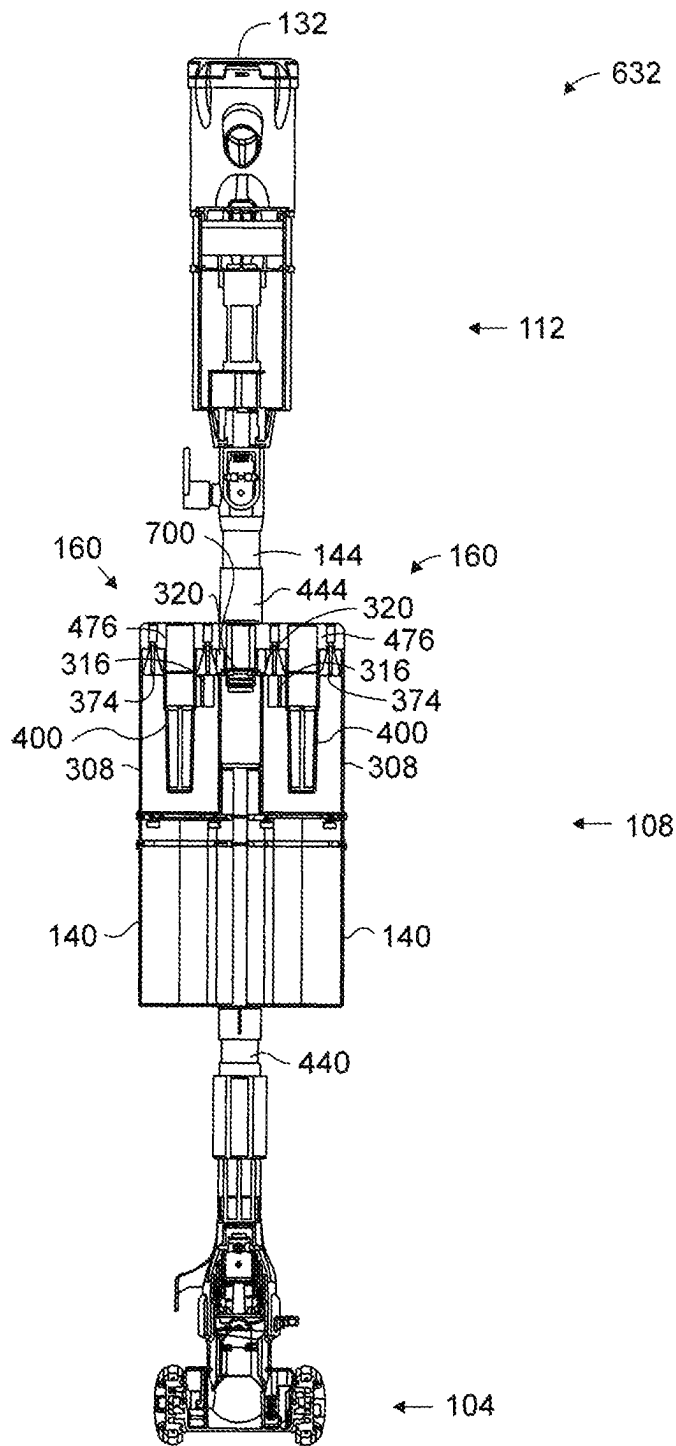


FIG. 48

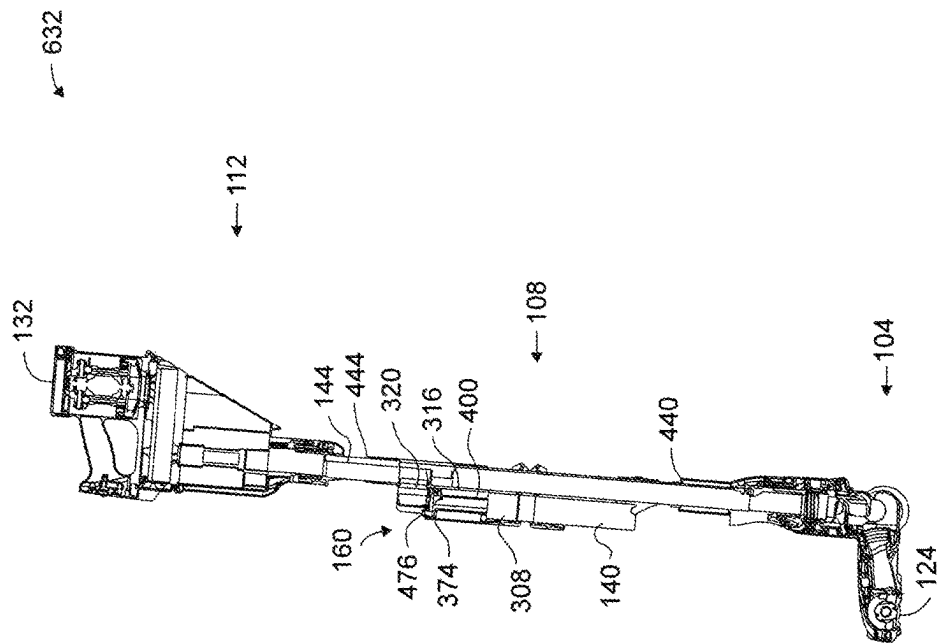


FIG. 49

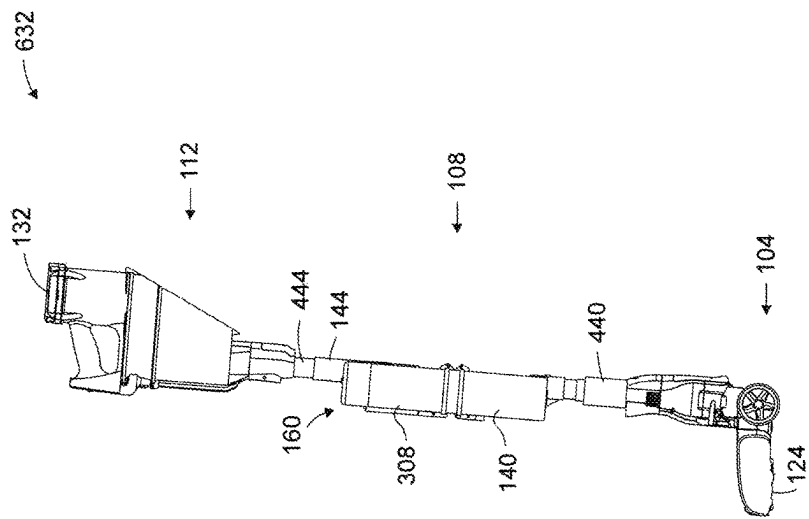


FIG. 50

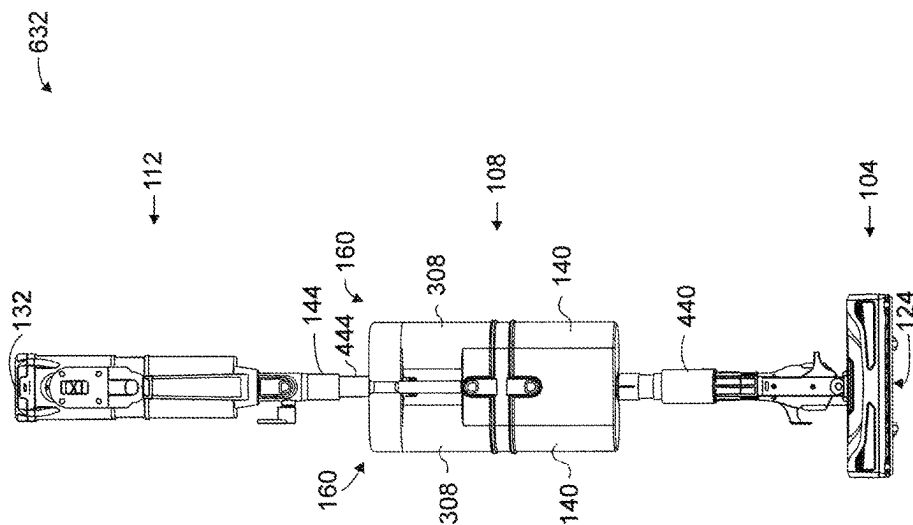


FIG. 51

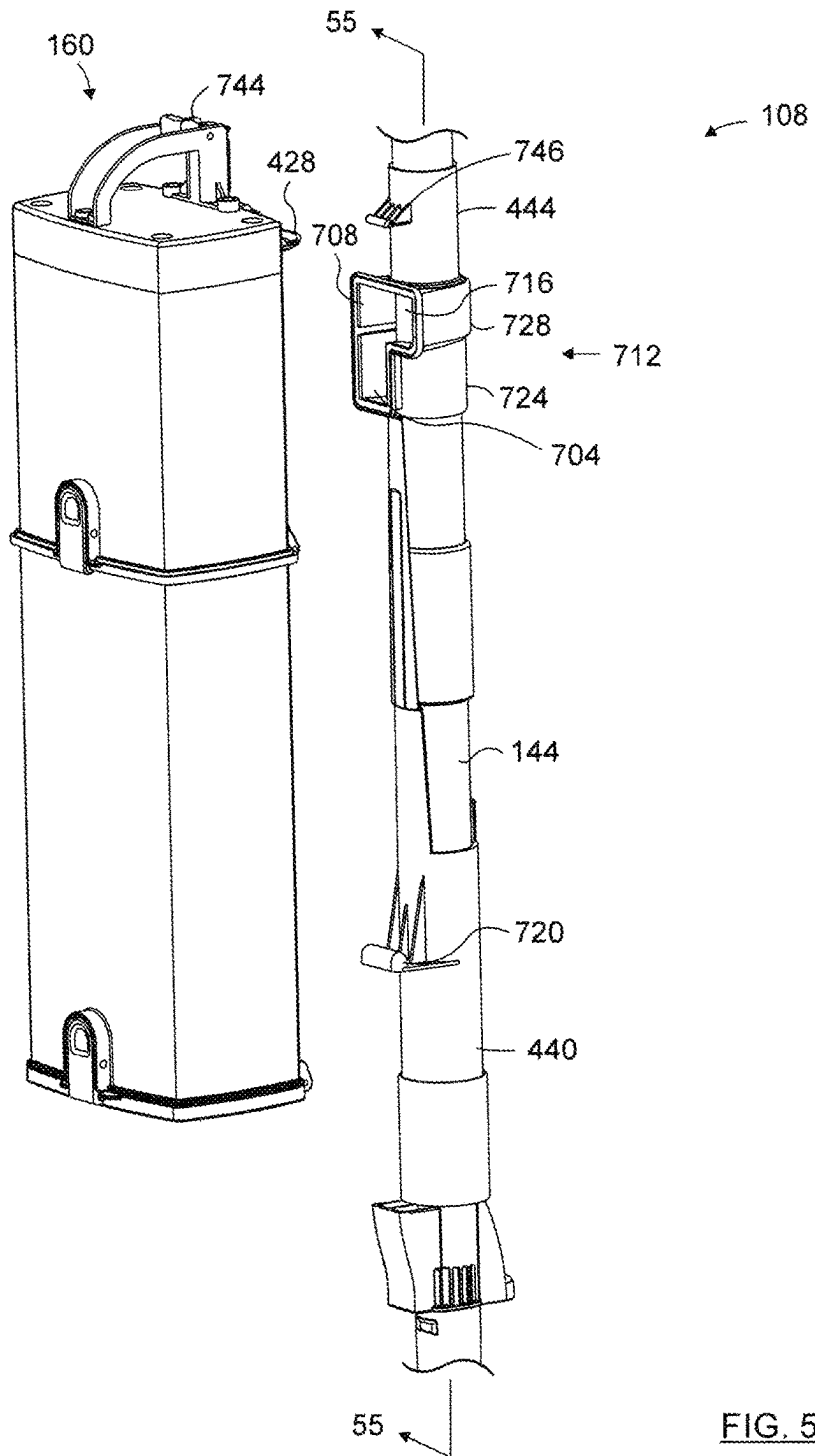


FIG. 52

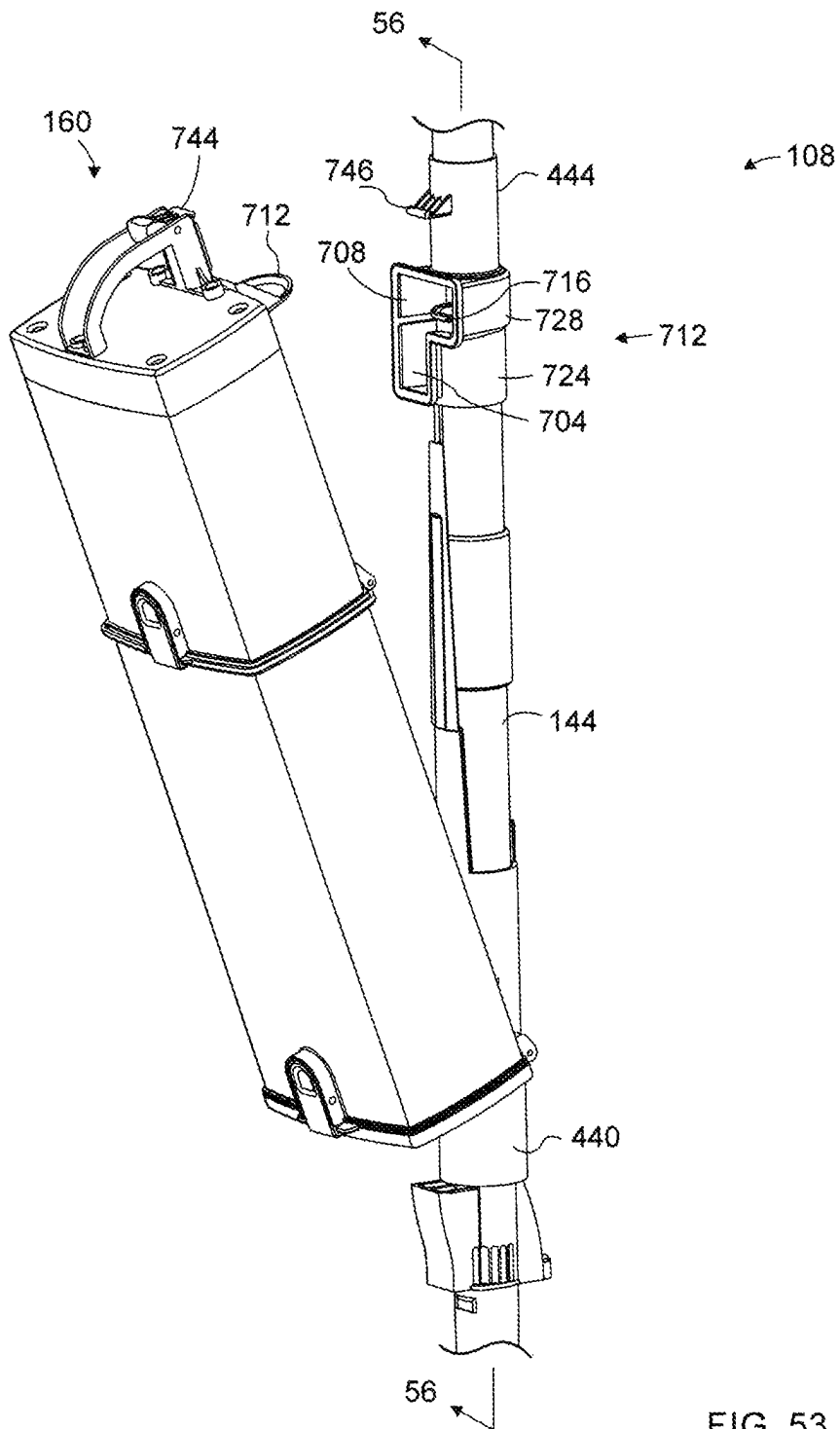


FIG. 53

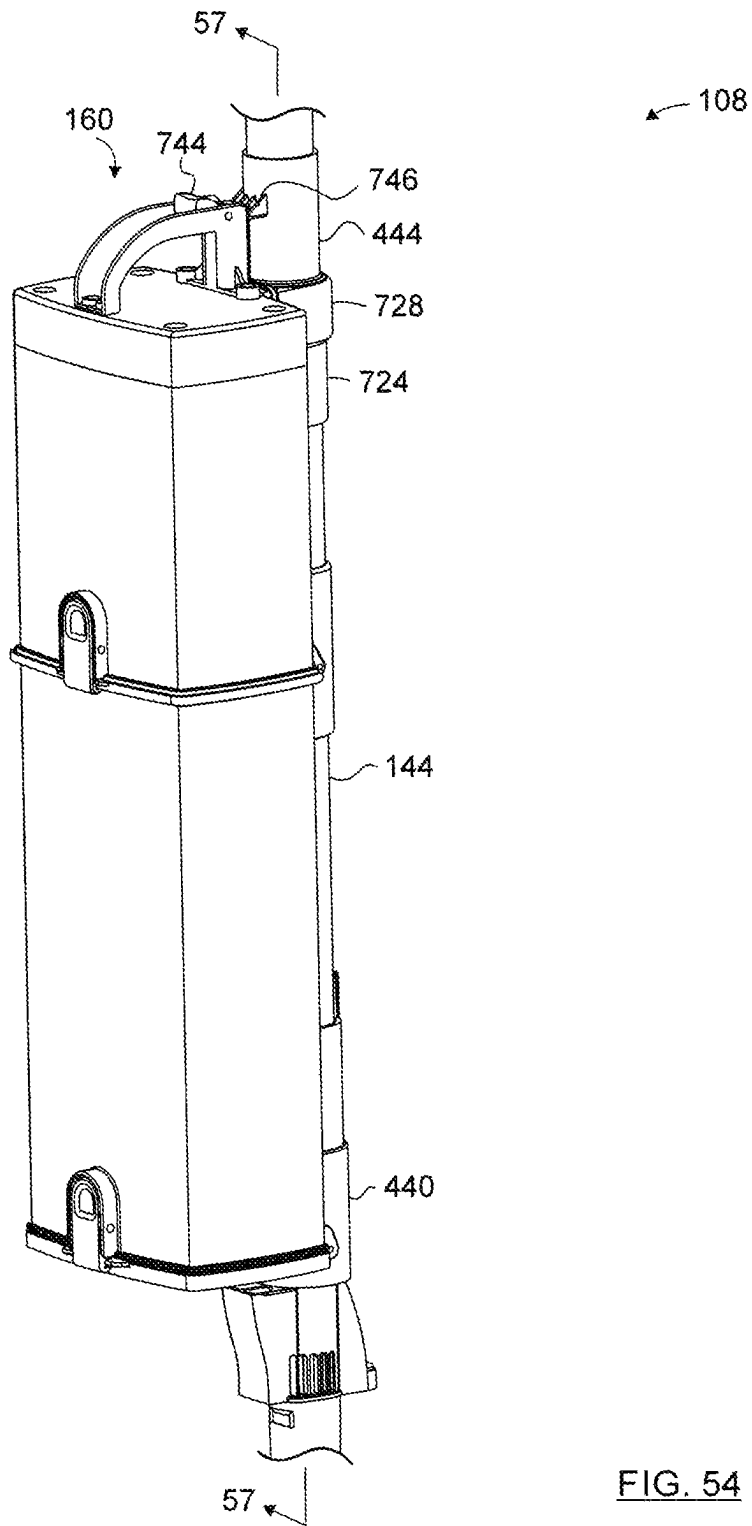


FIG. 54

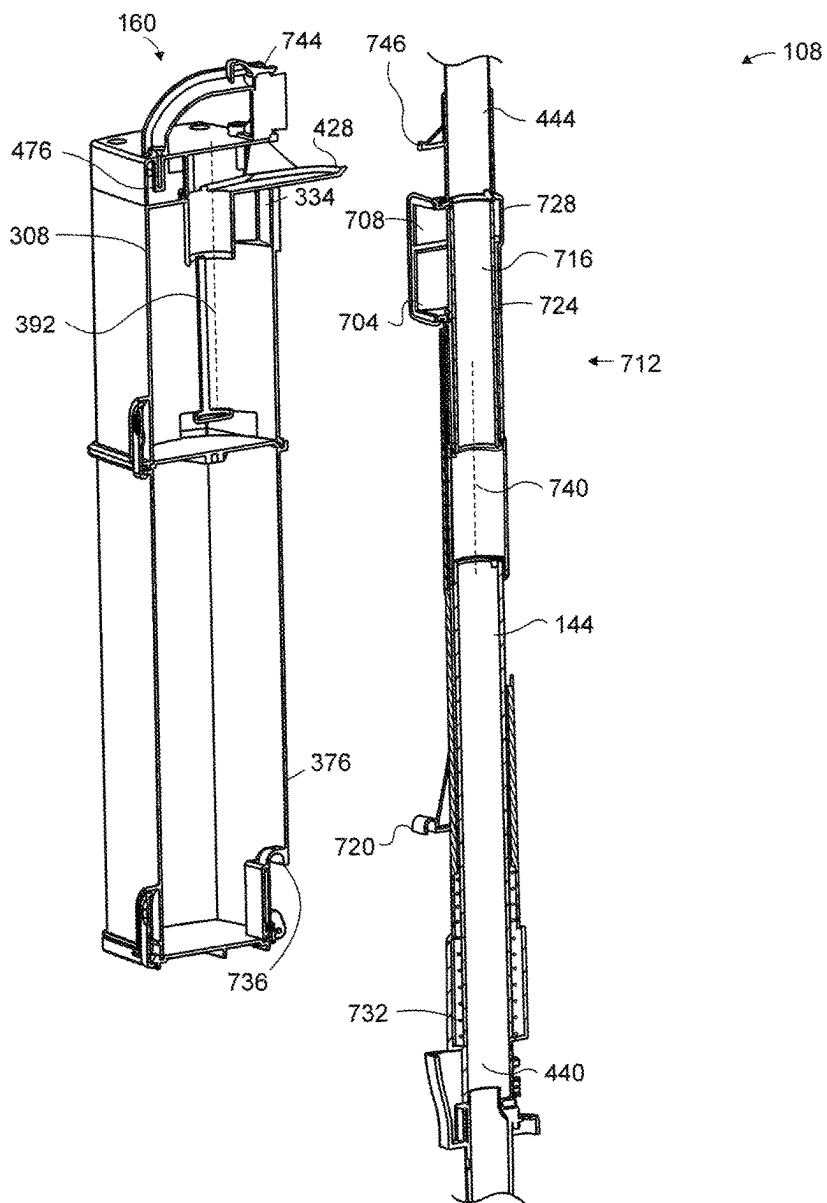


FIG. 55

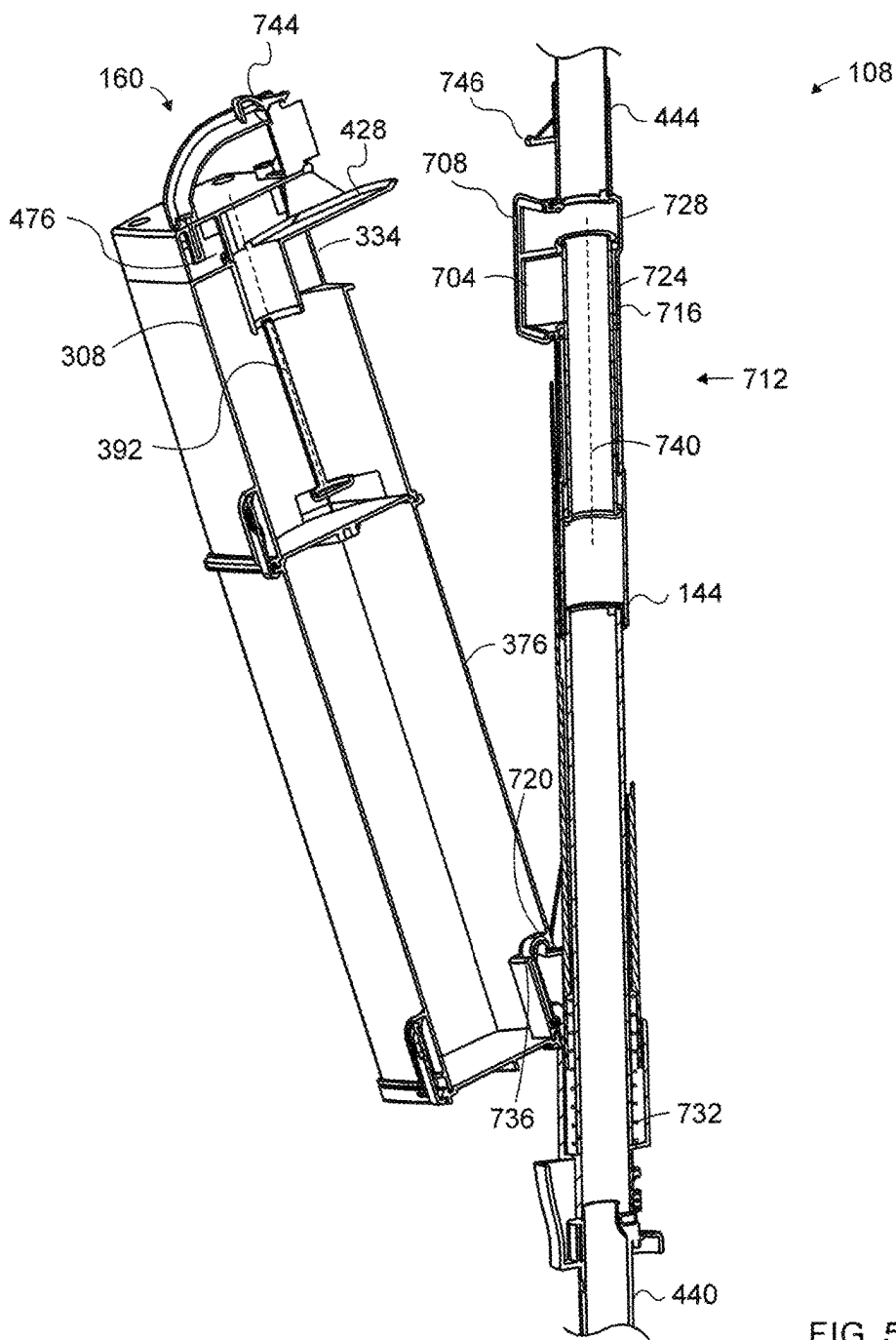


FIG. 56

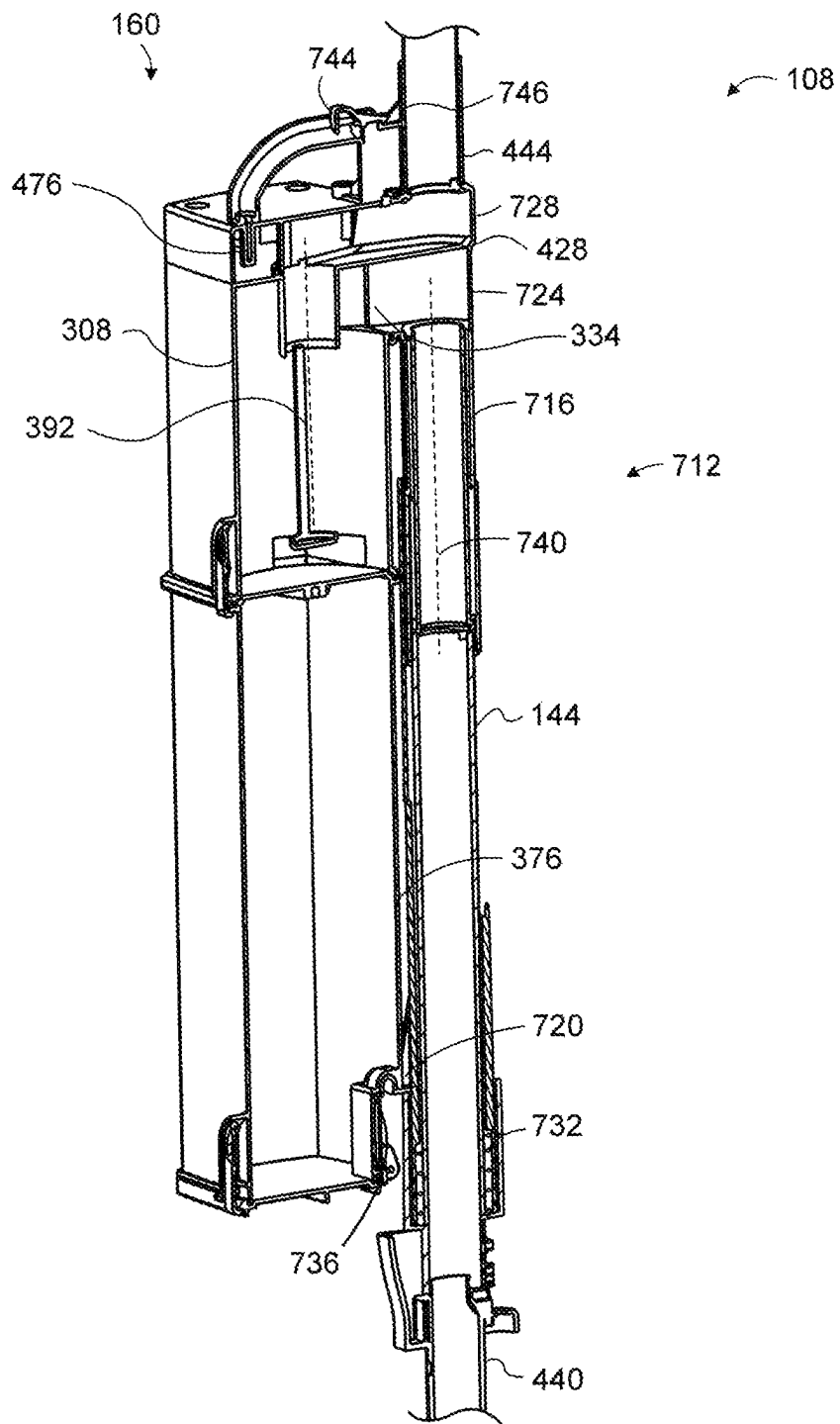


FIG. 57

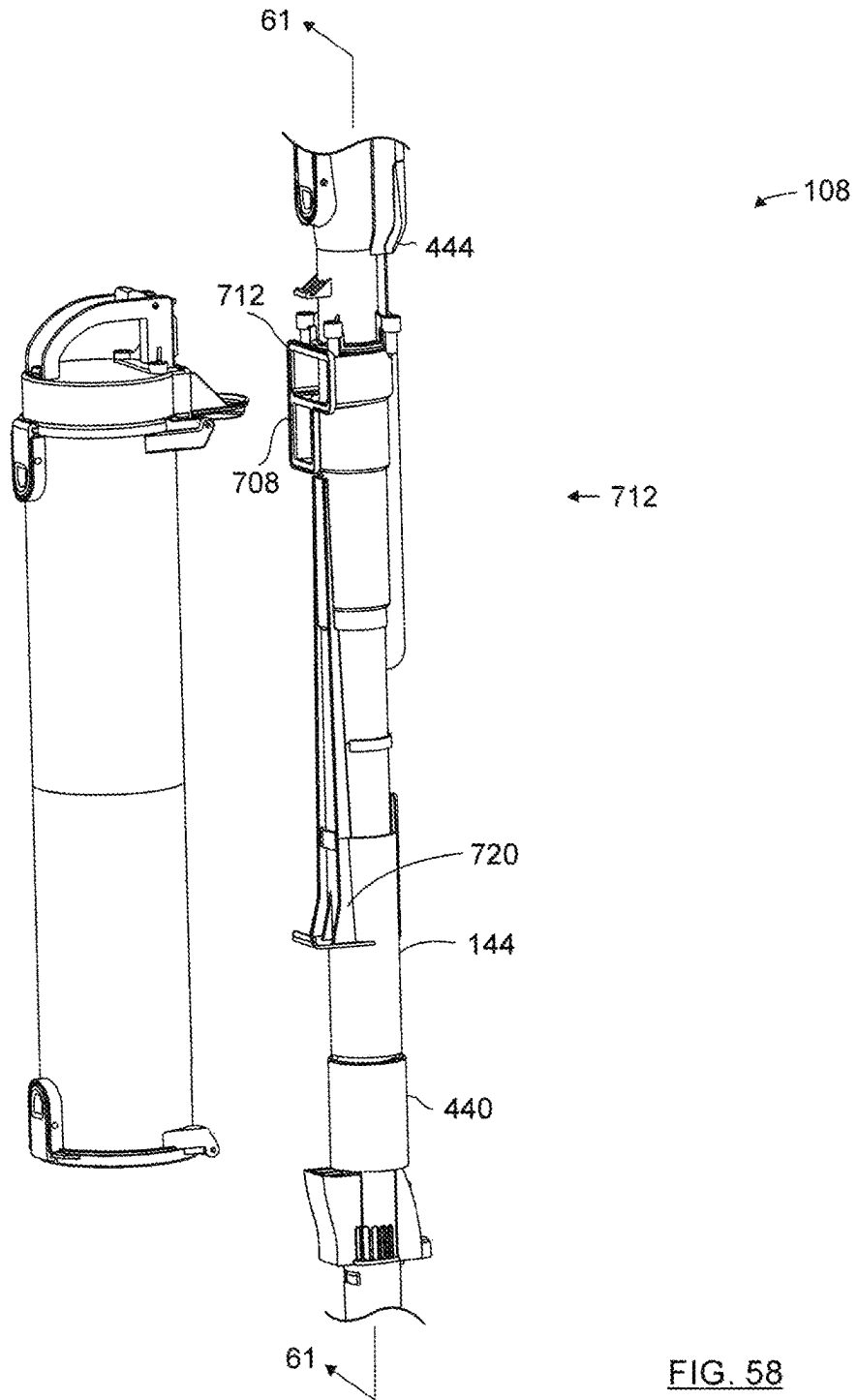


FIG. 58

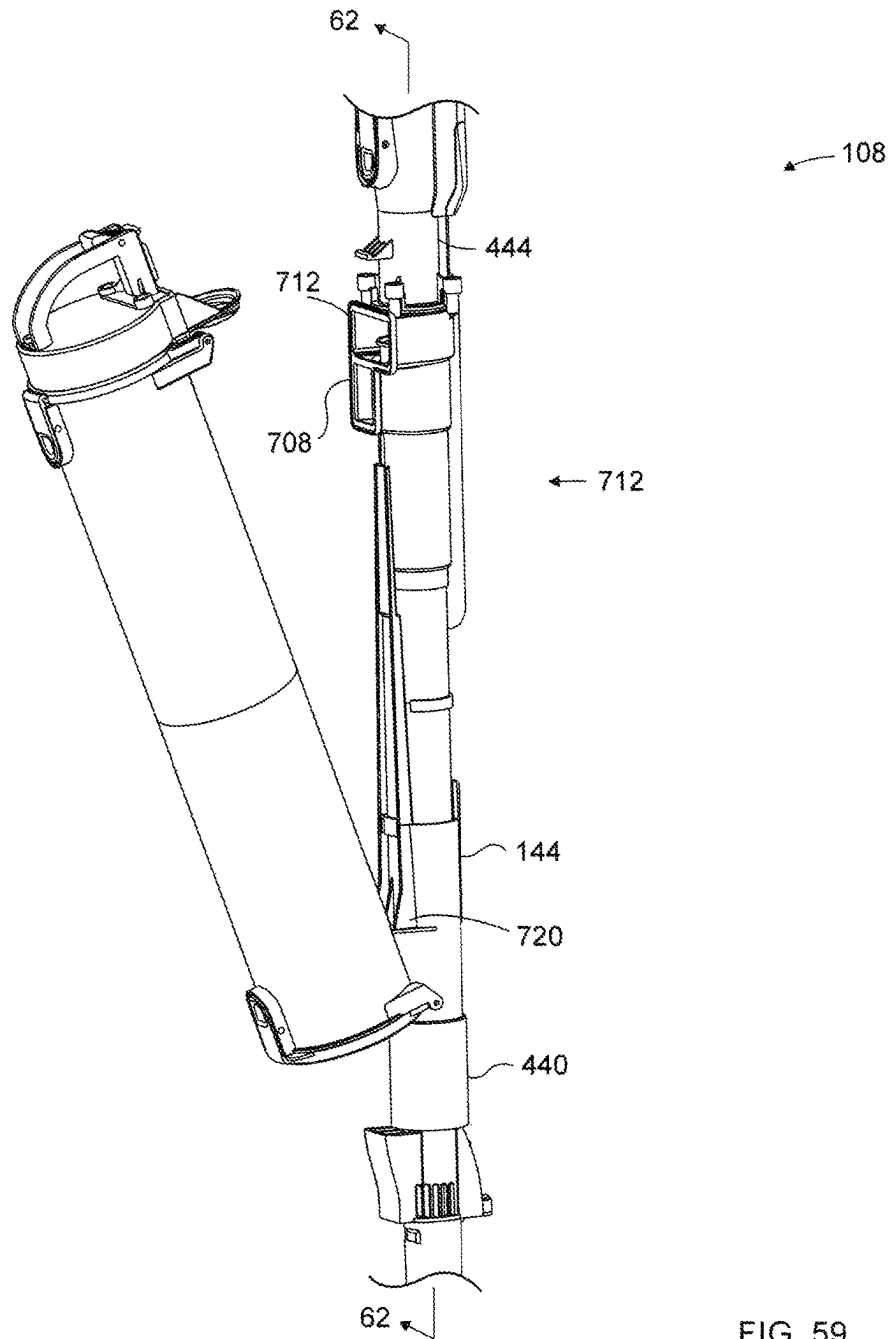


FIG. 59

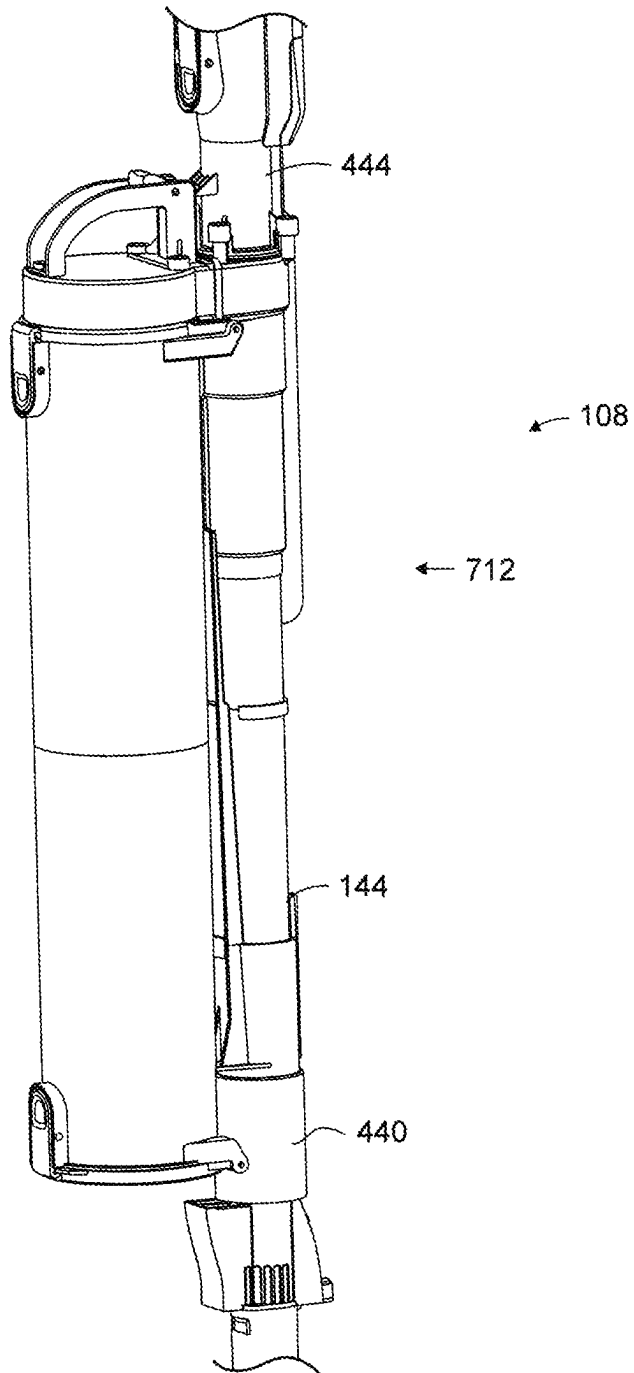


FIG. 60

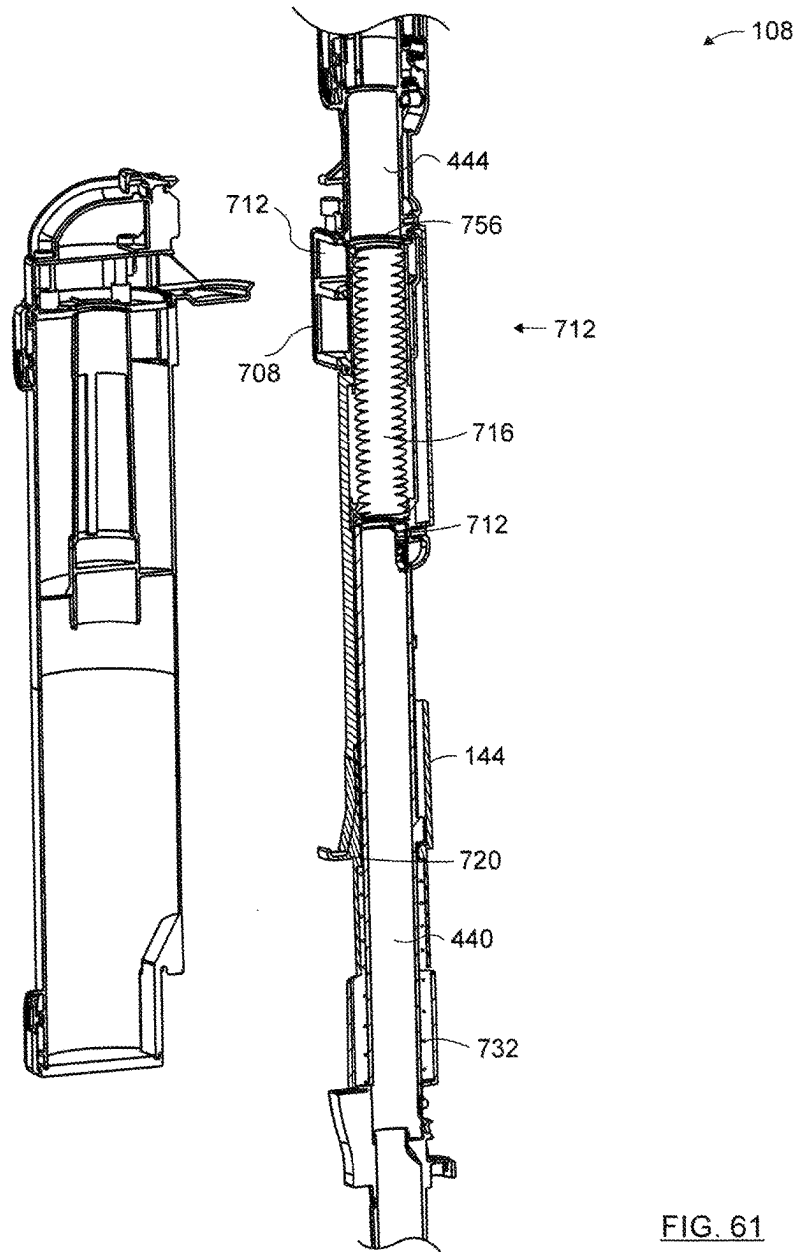


FIG. 61

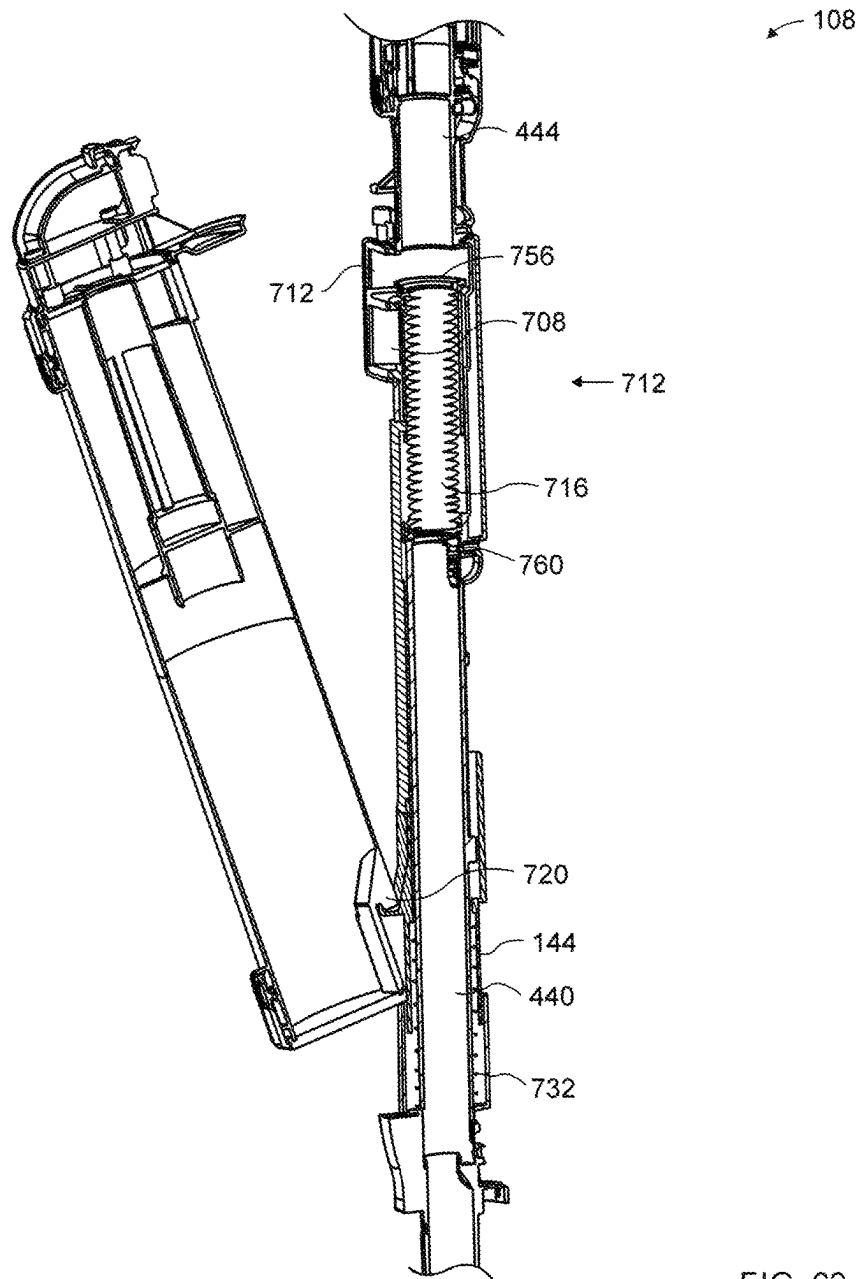


FIG. 62

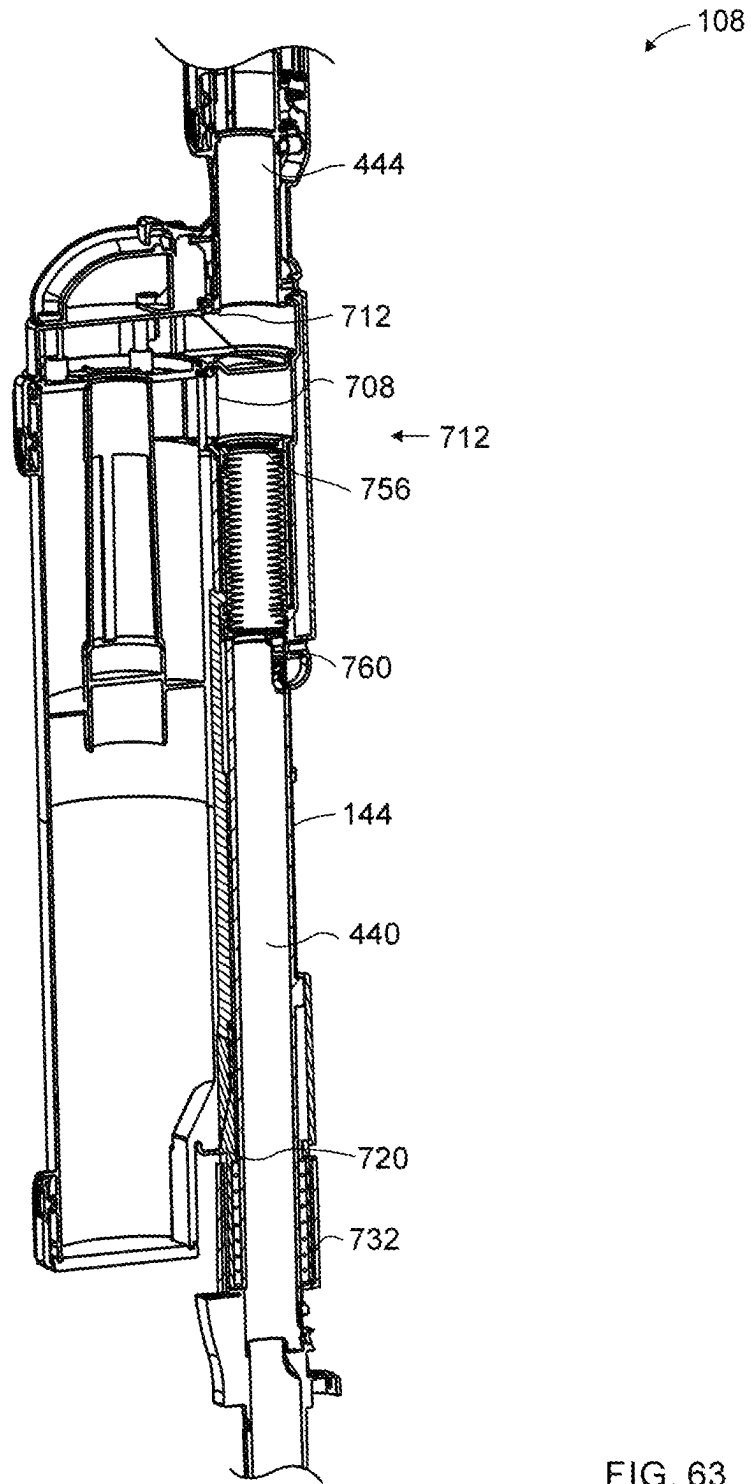


FIG. 63

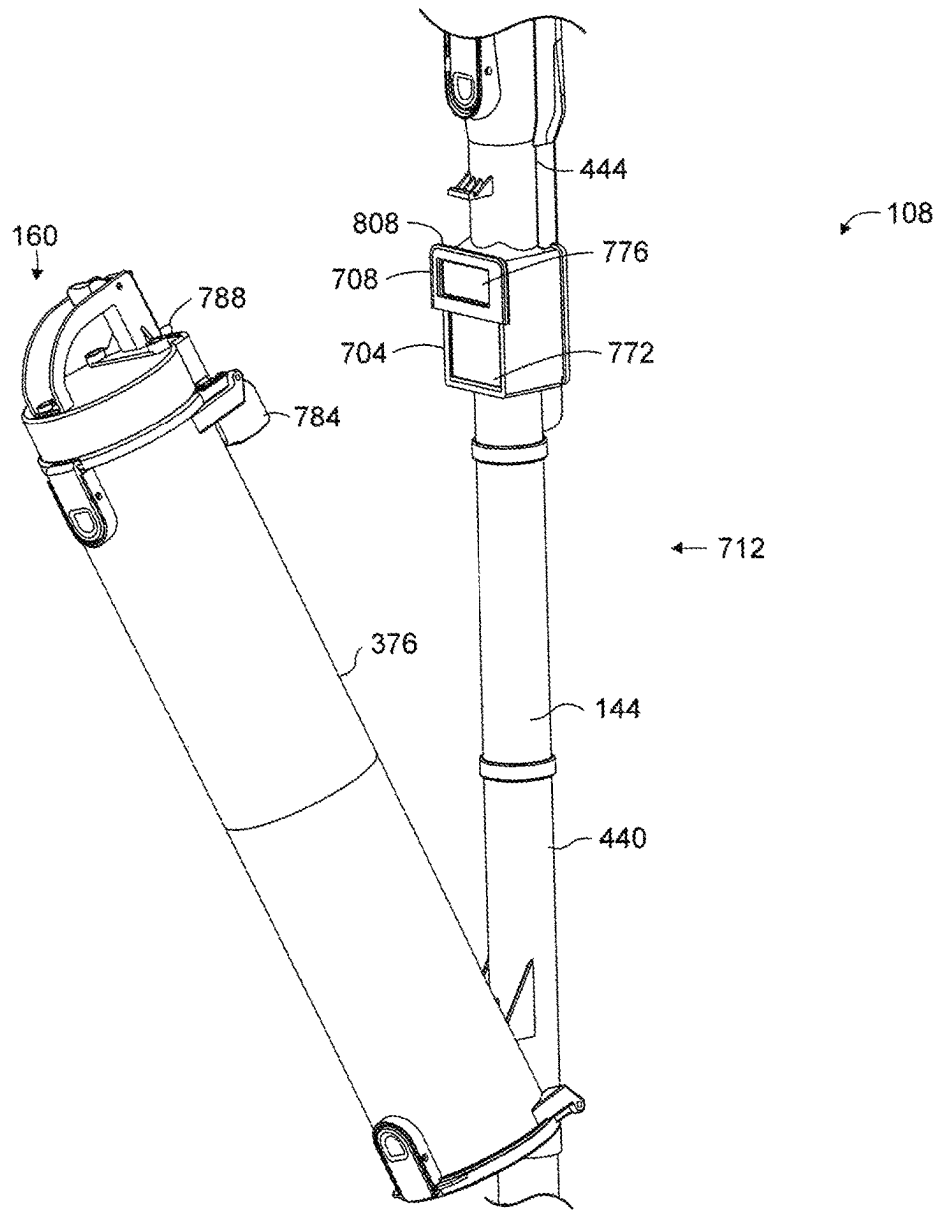


FIG. 64

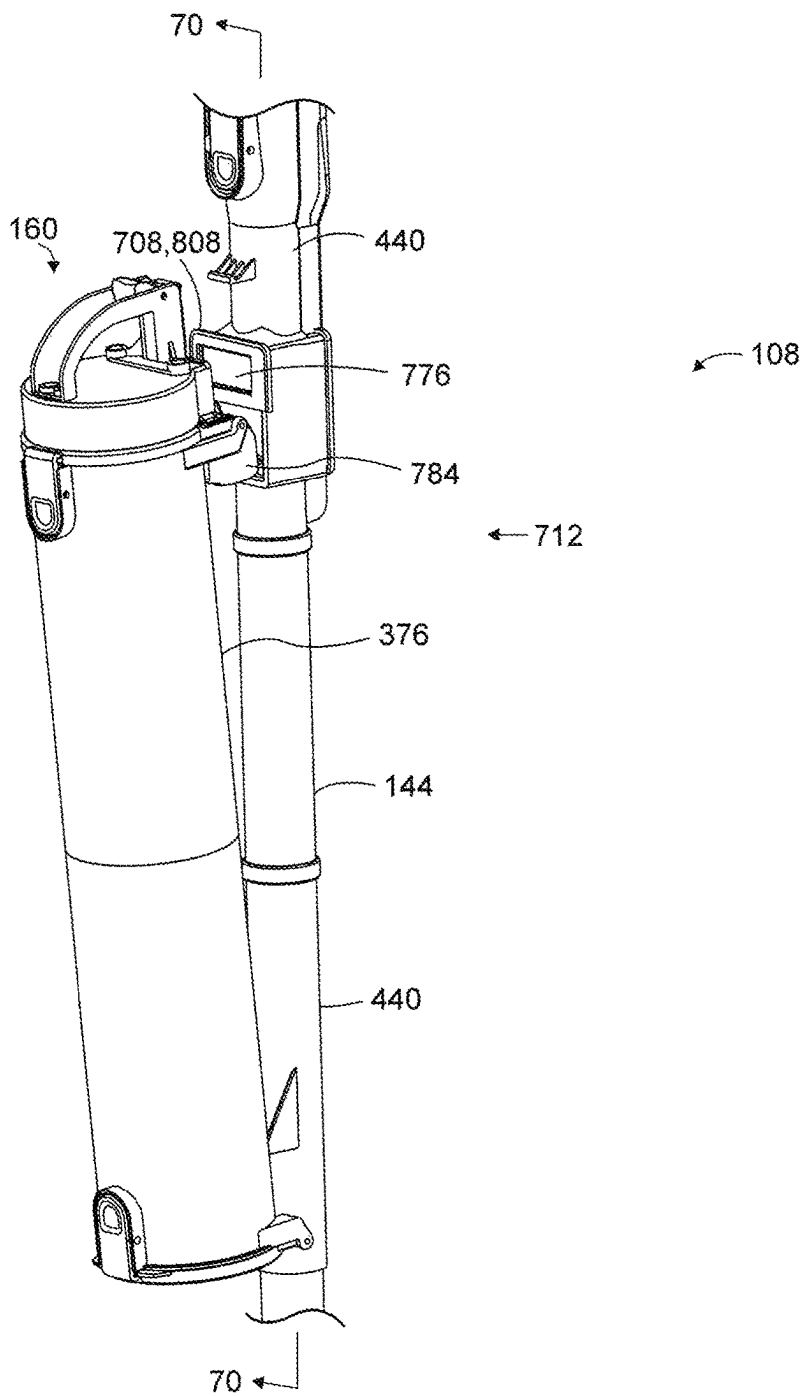


FIG. 65

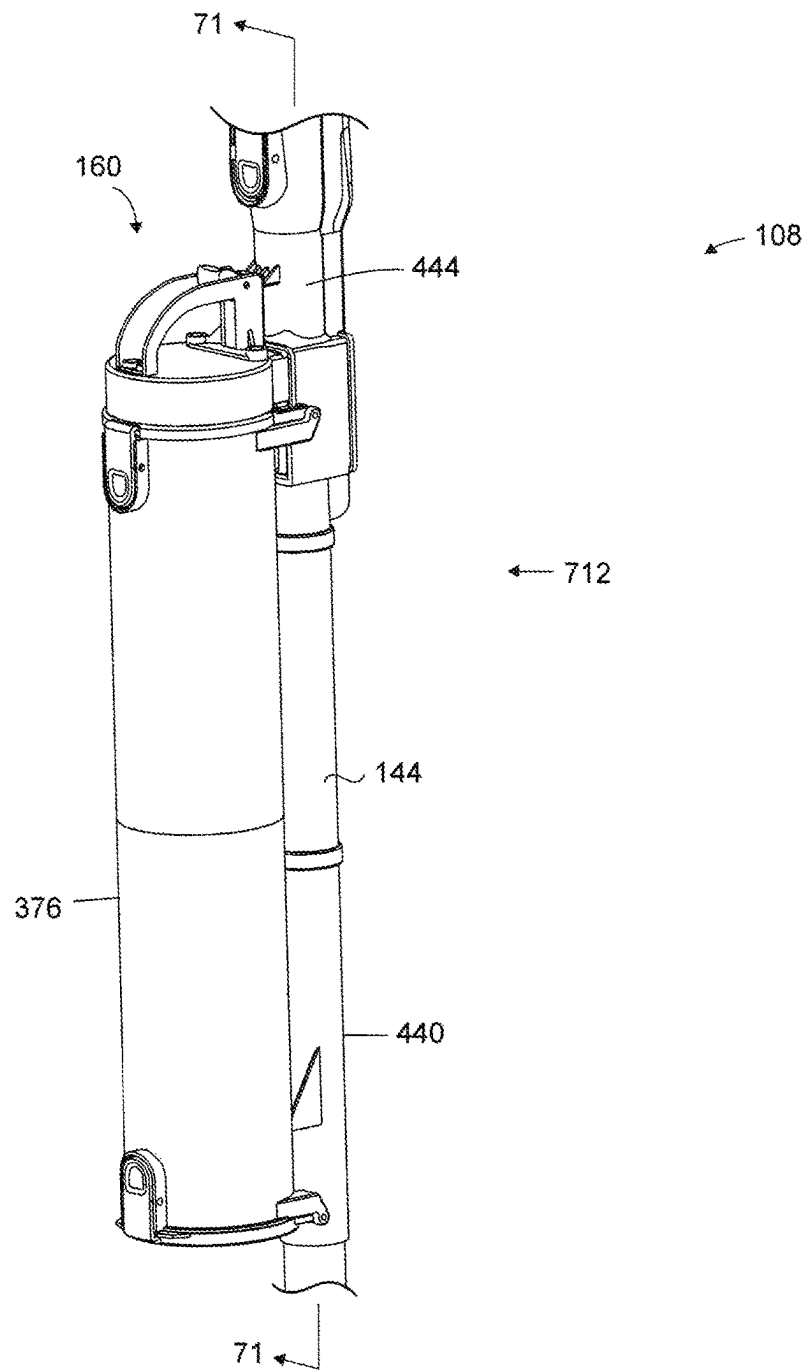


FIG. 66

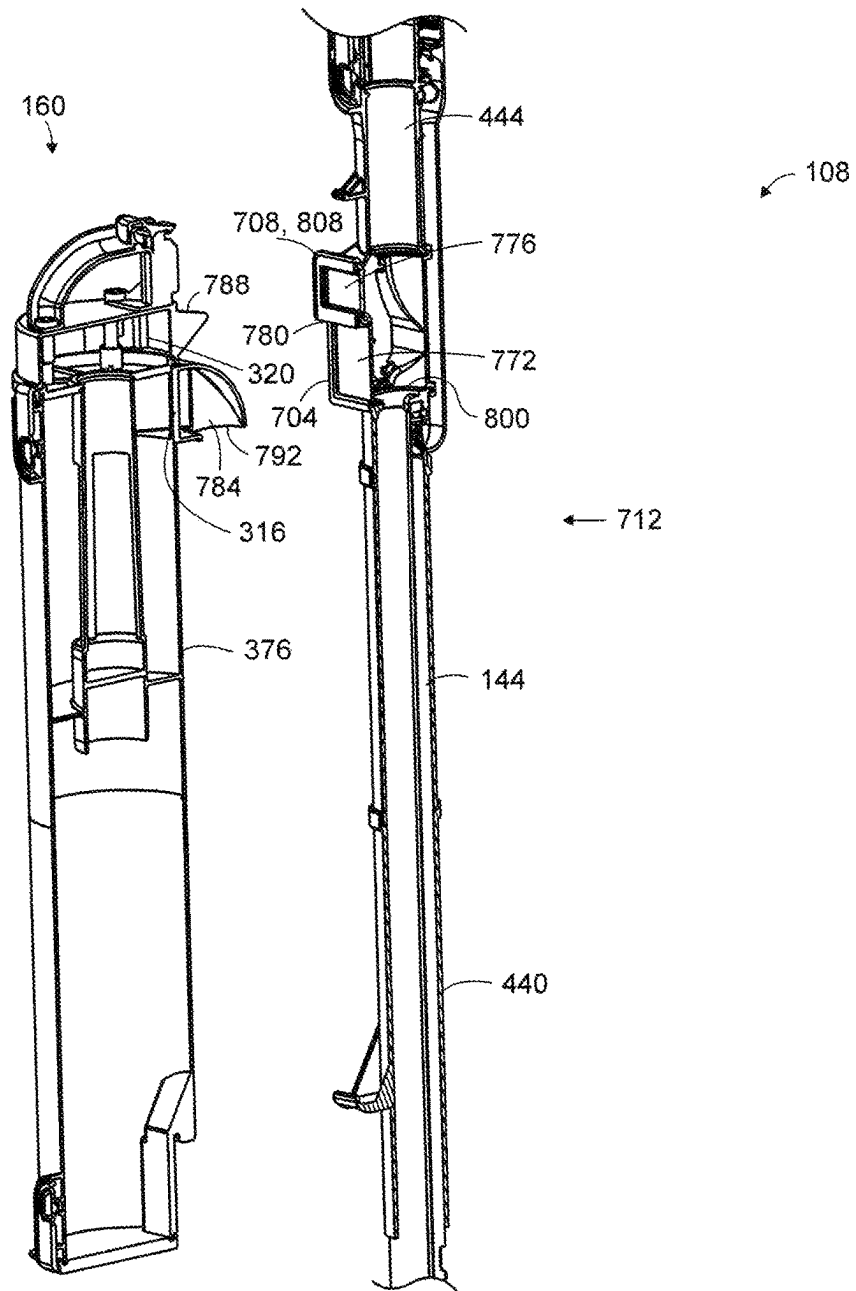


FIG. 67

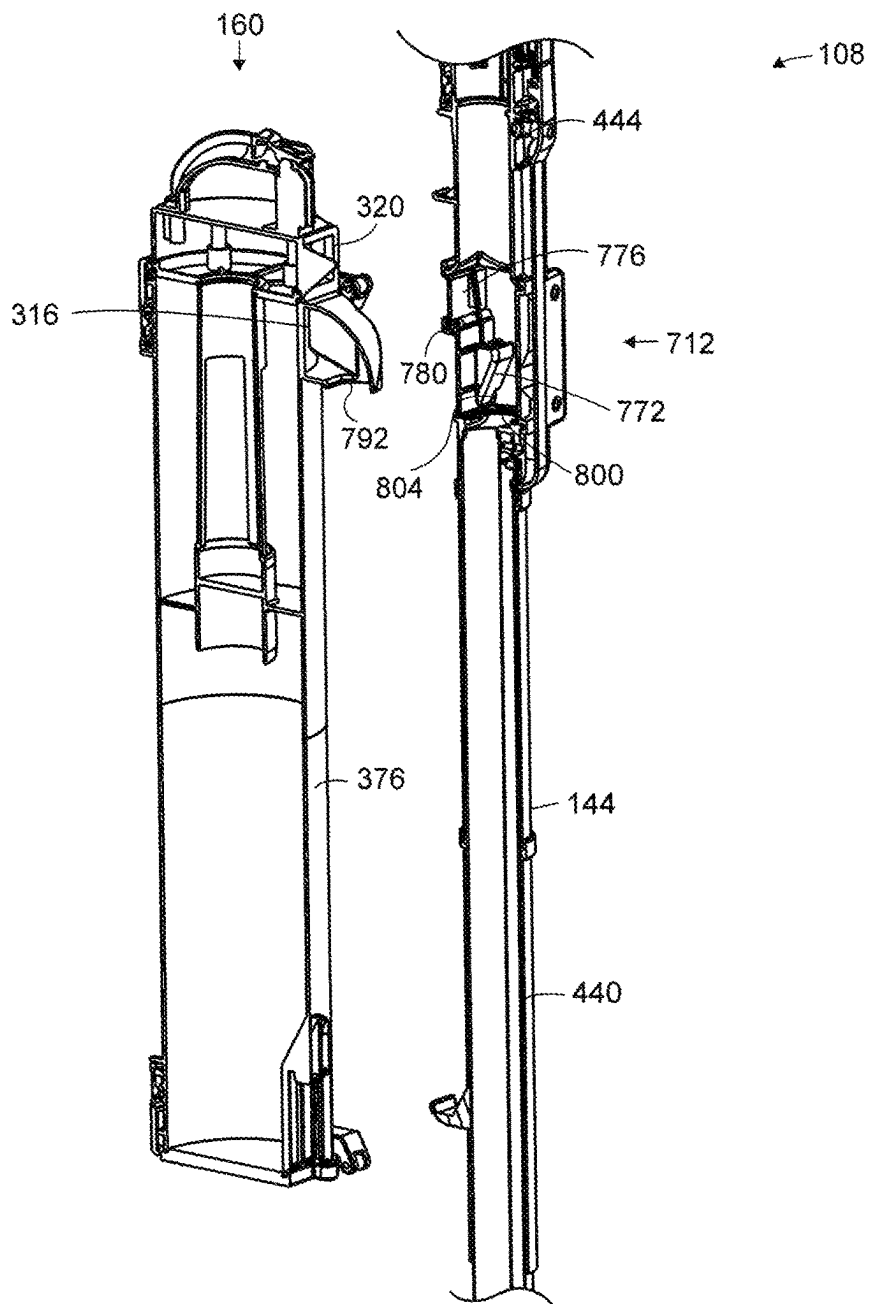


FIG. 68

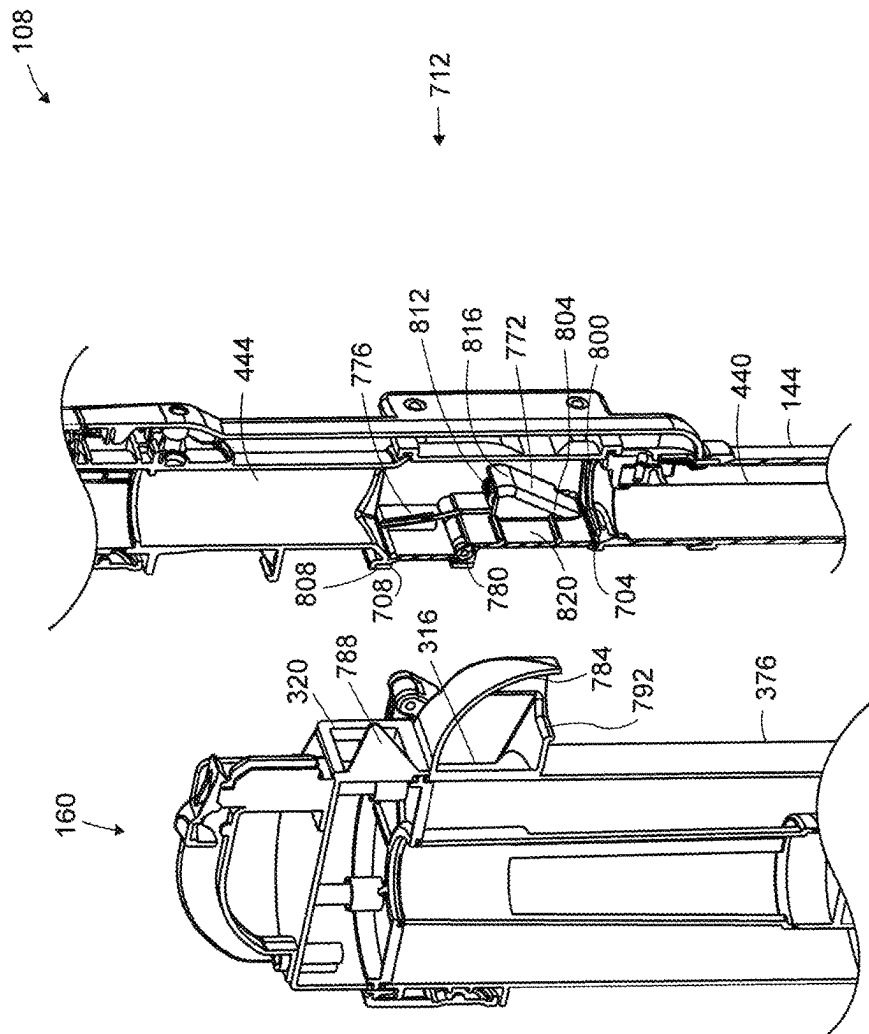


FIG. 69

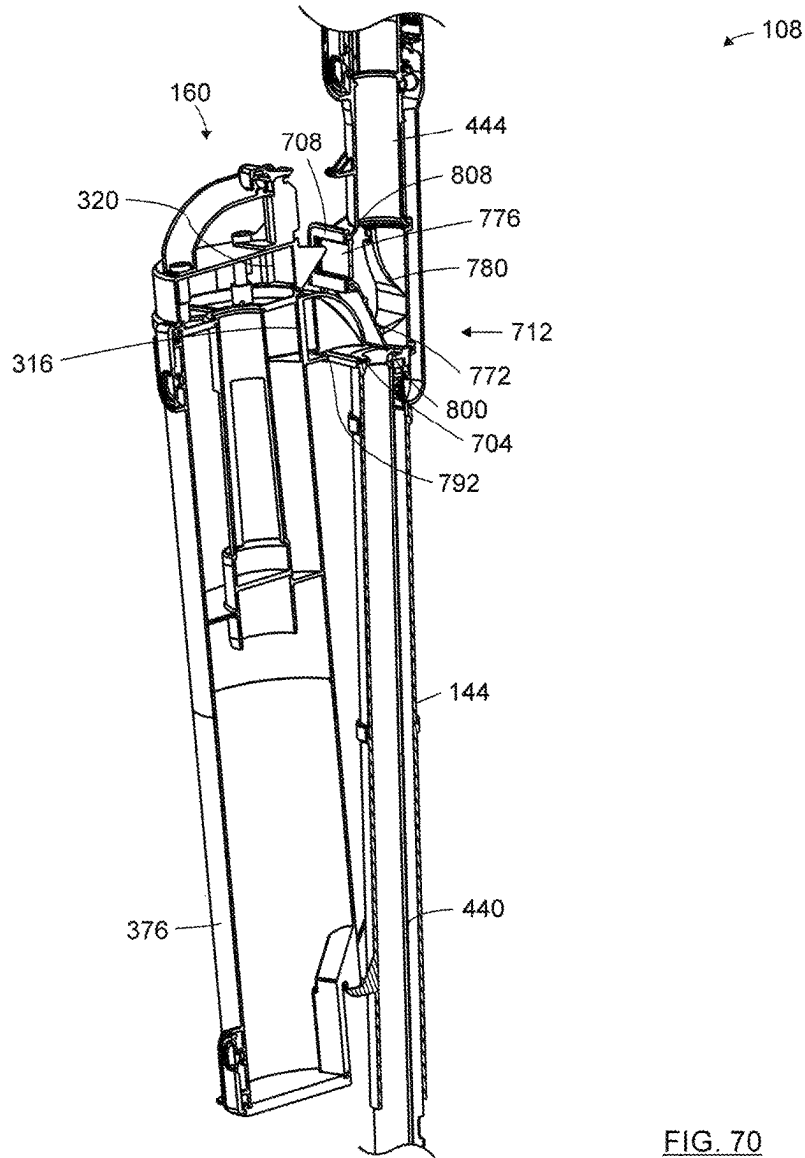


FIG. 70

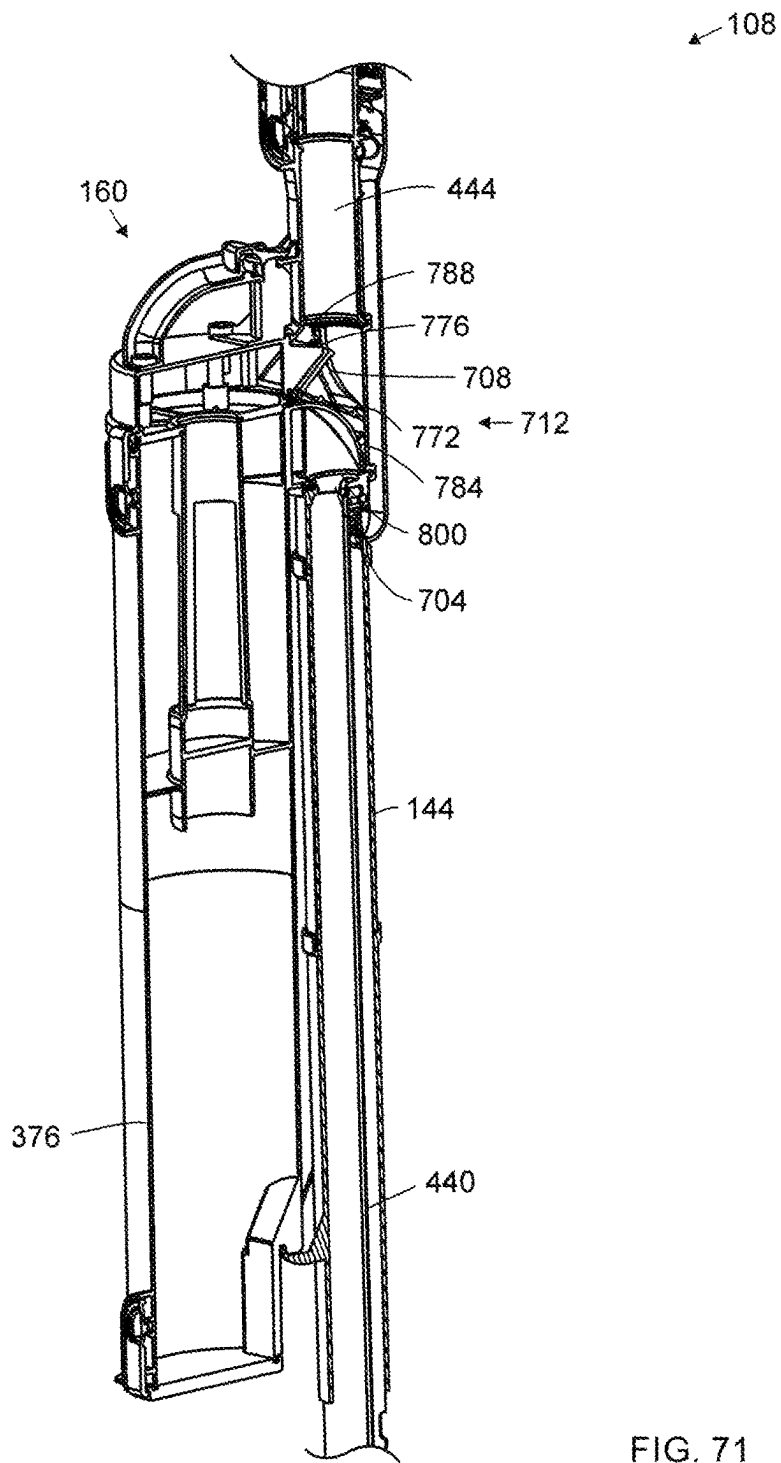


FIG. 71

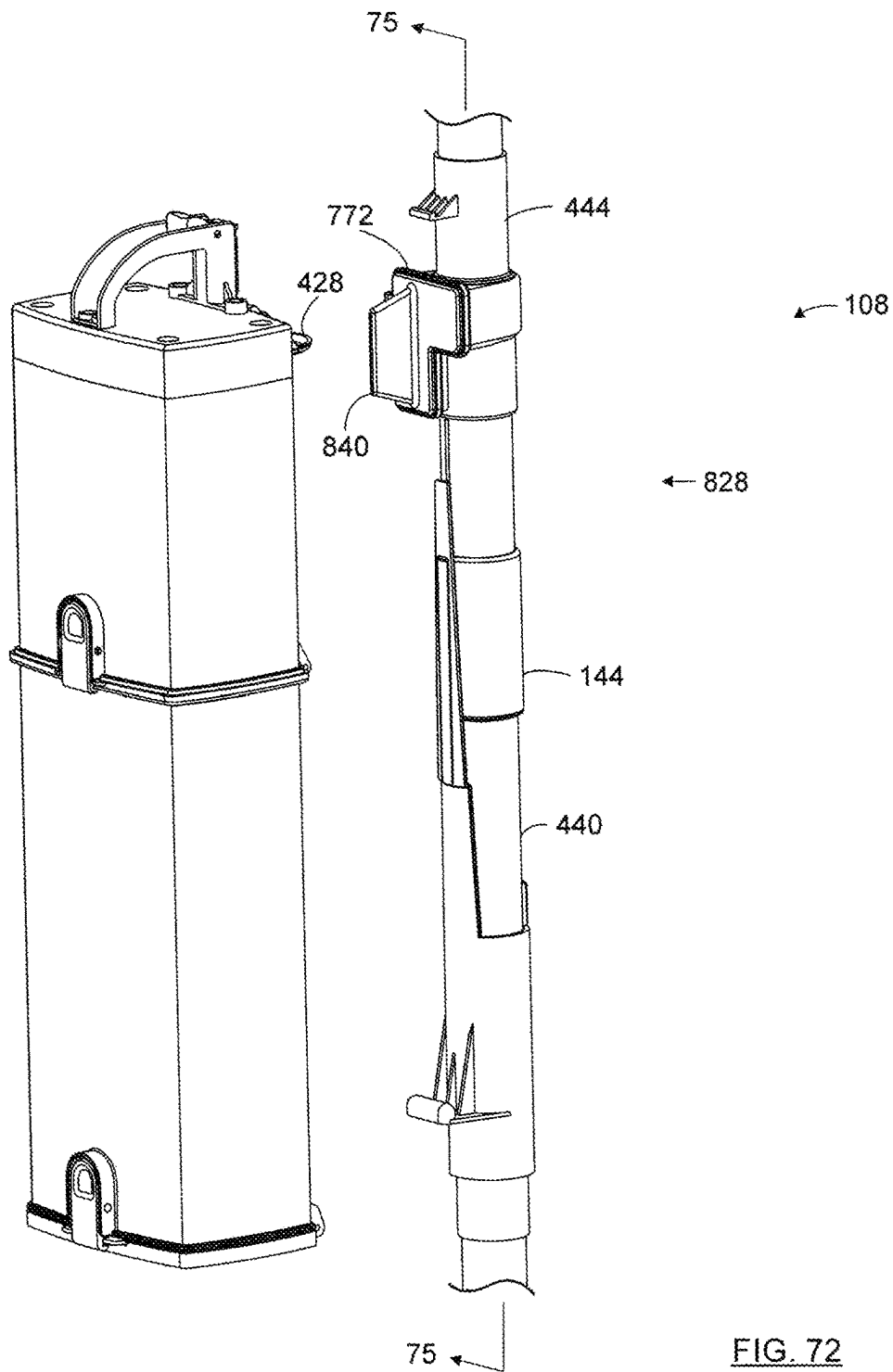


FIG. 72

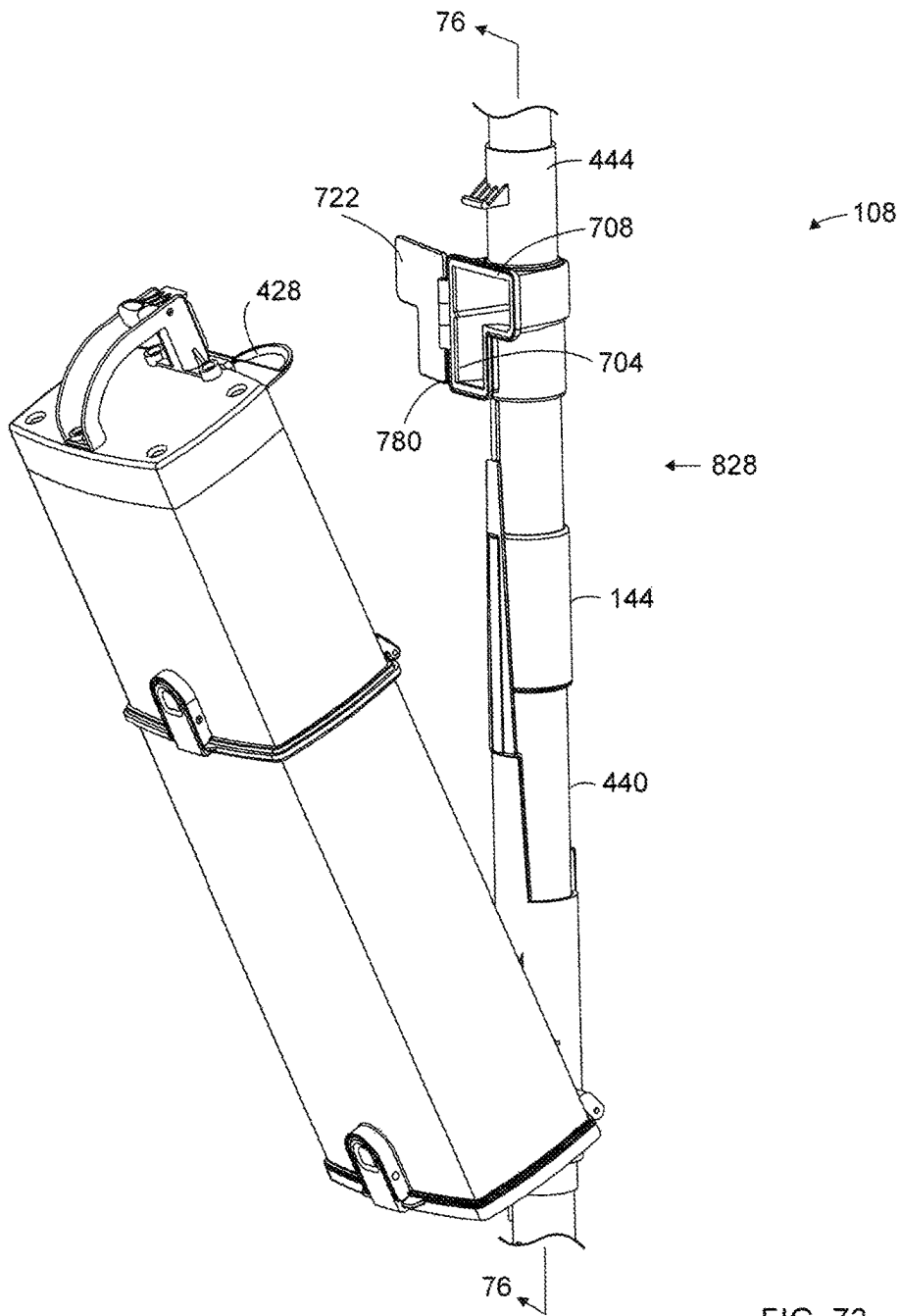


FIG. 73

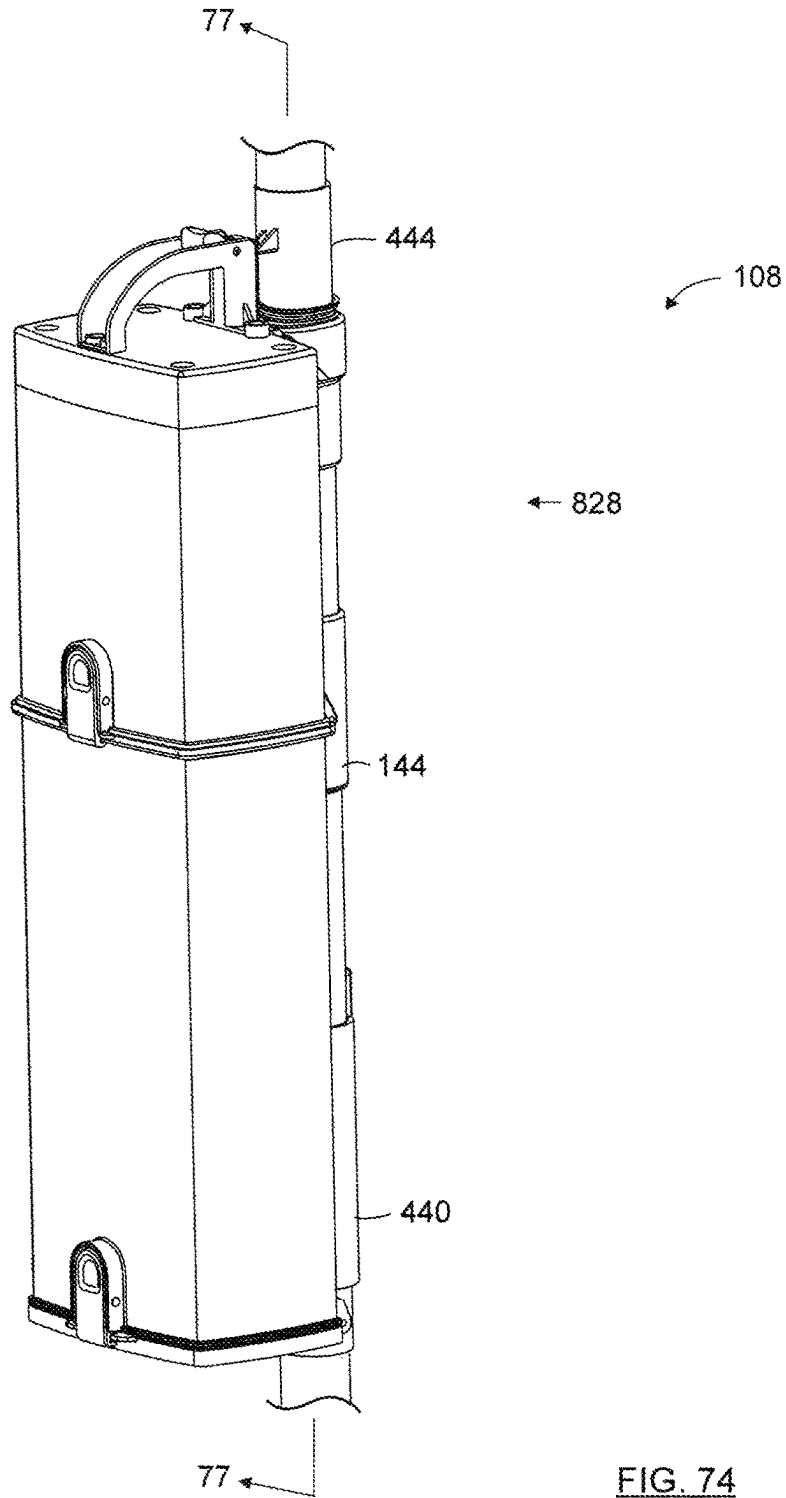


FIG. 74

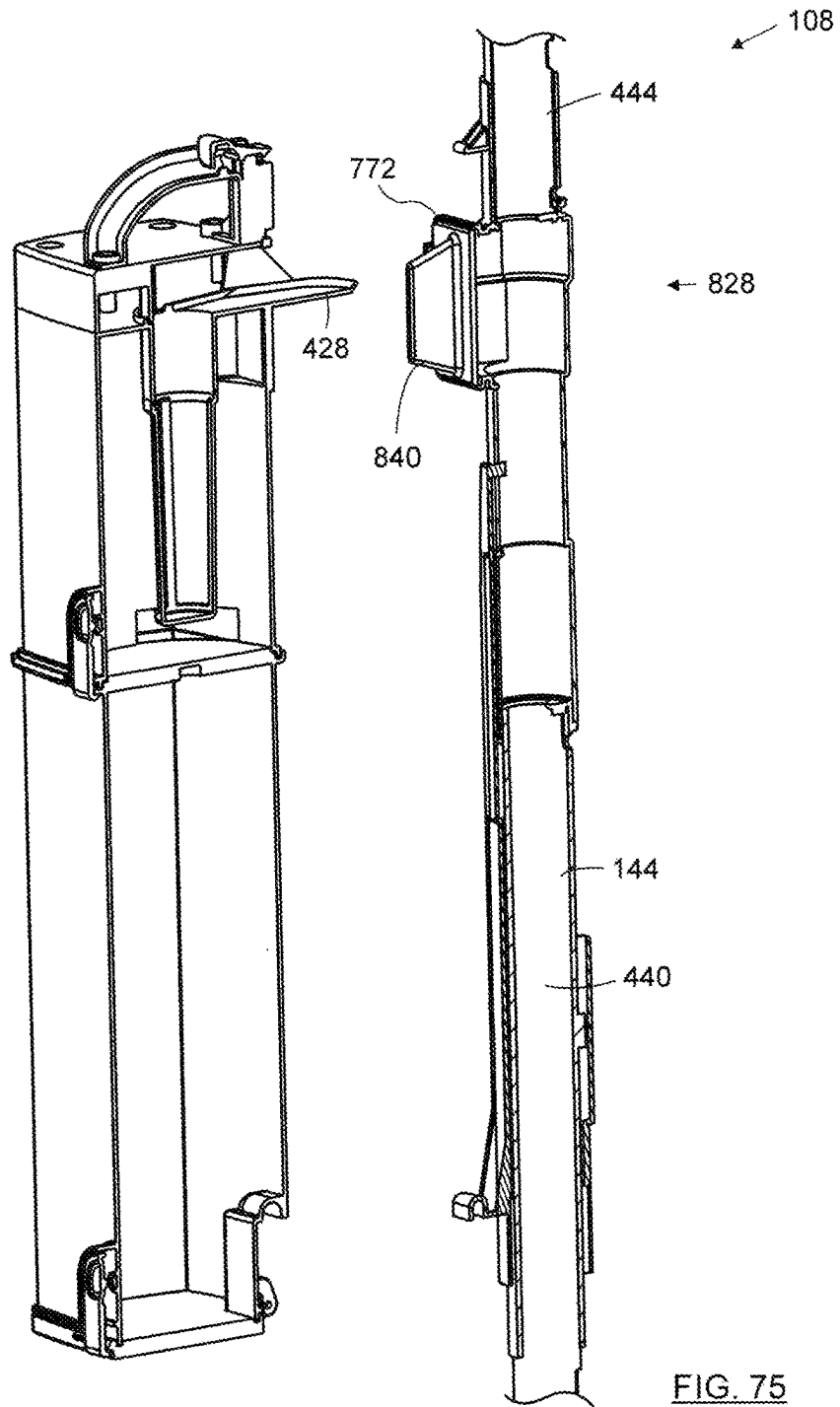


FIG. 75

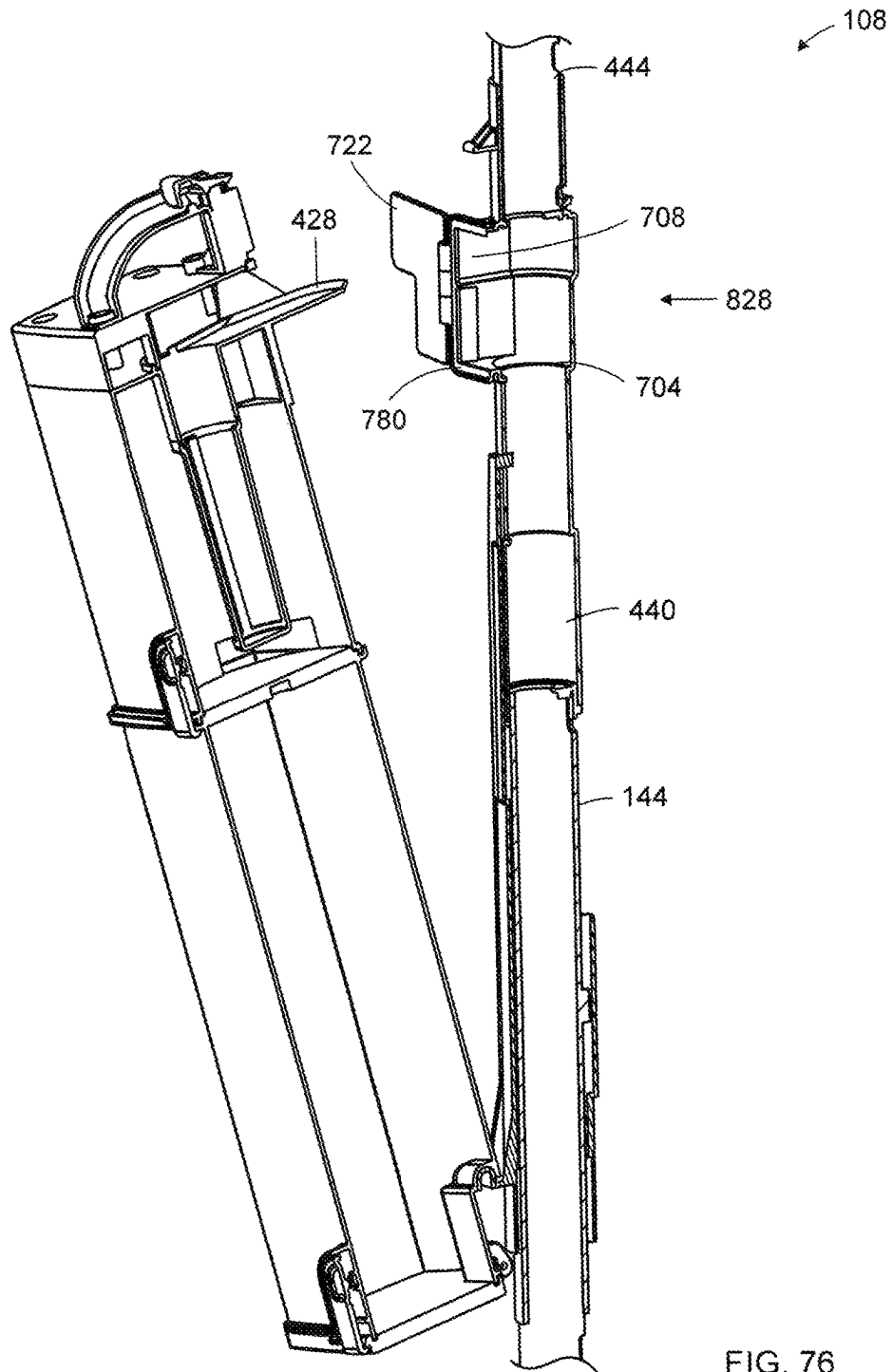


FIG. 76

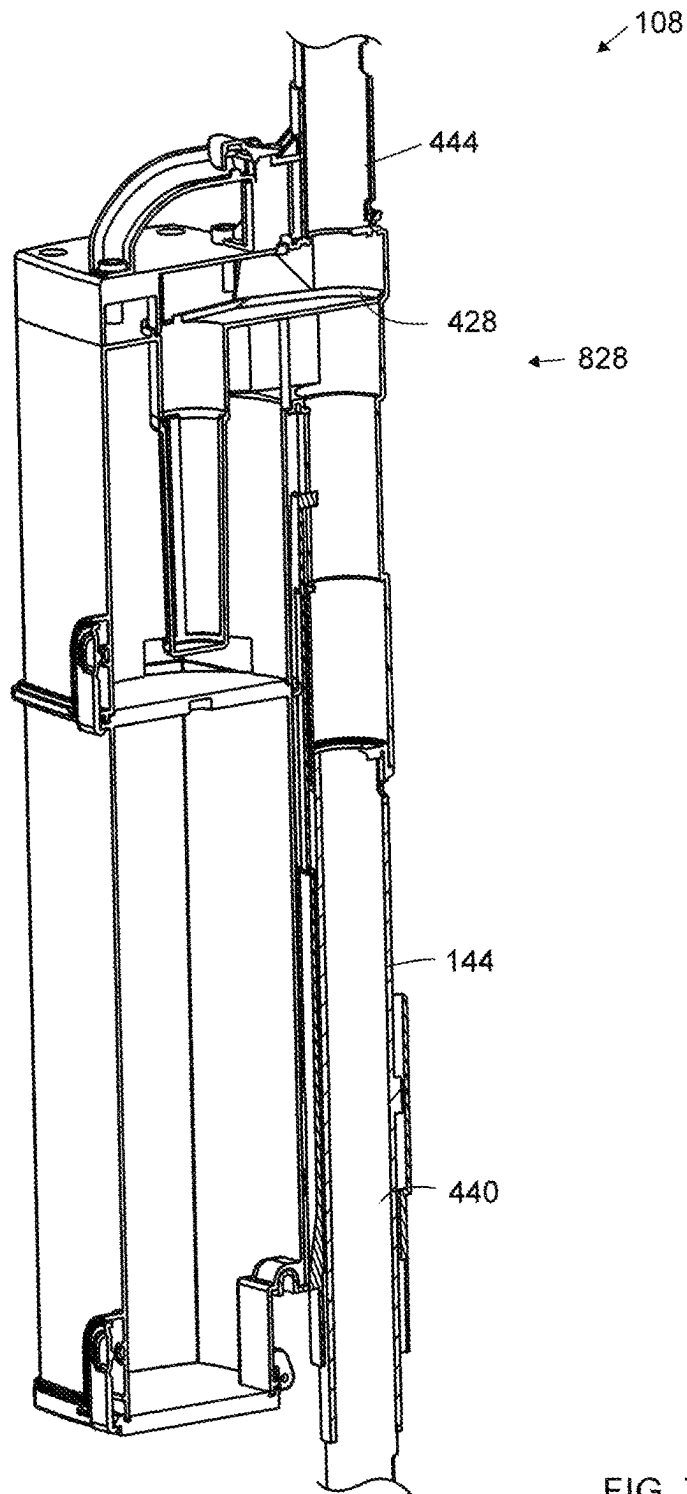


FIG. 77

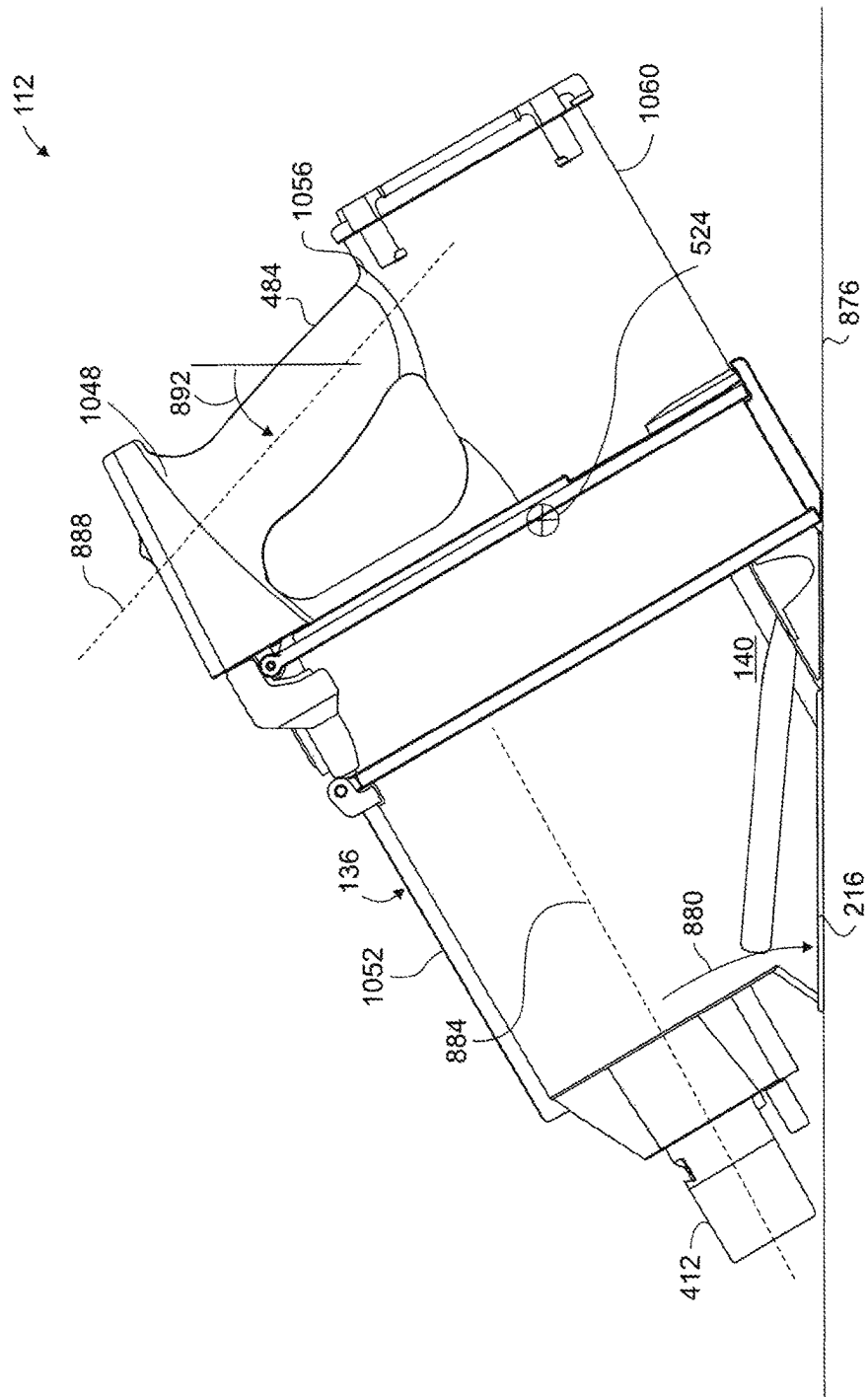


FIG. 78

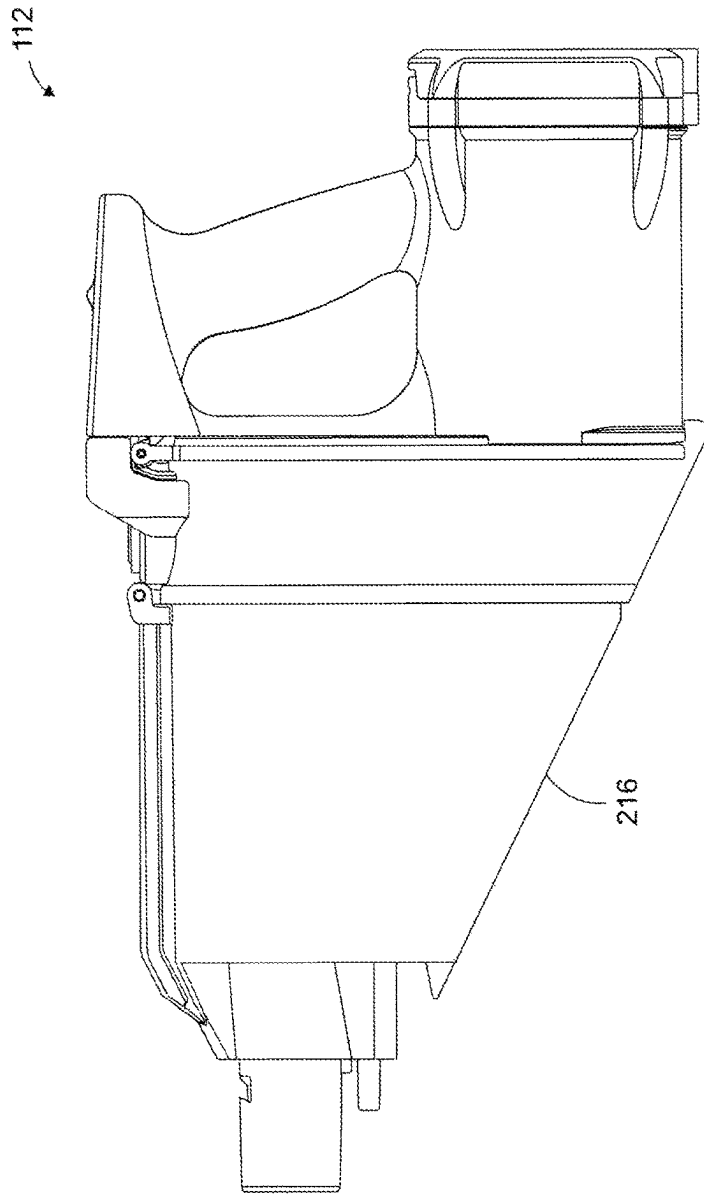


FIG. 79

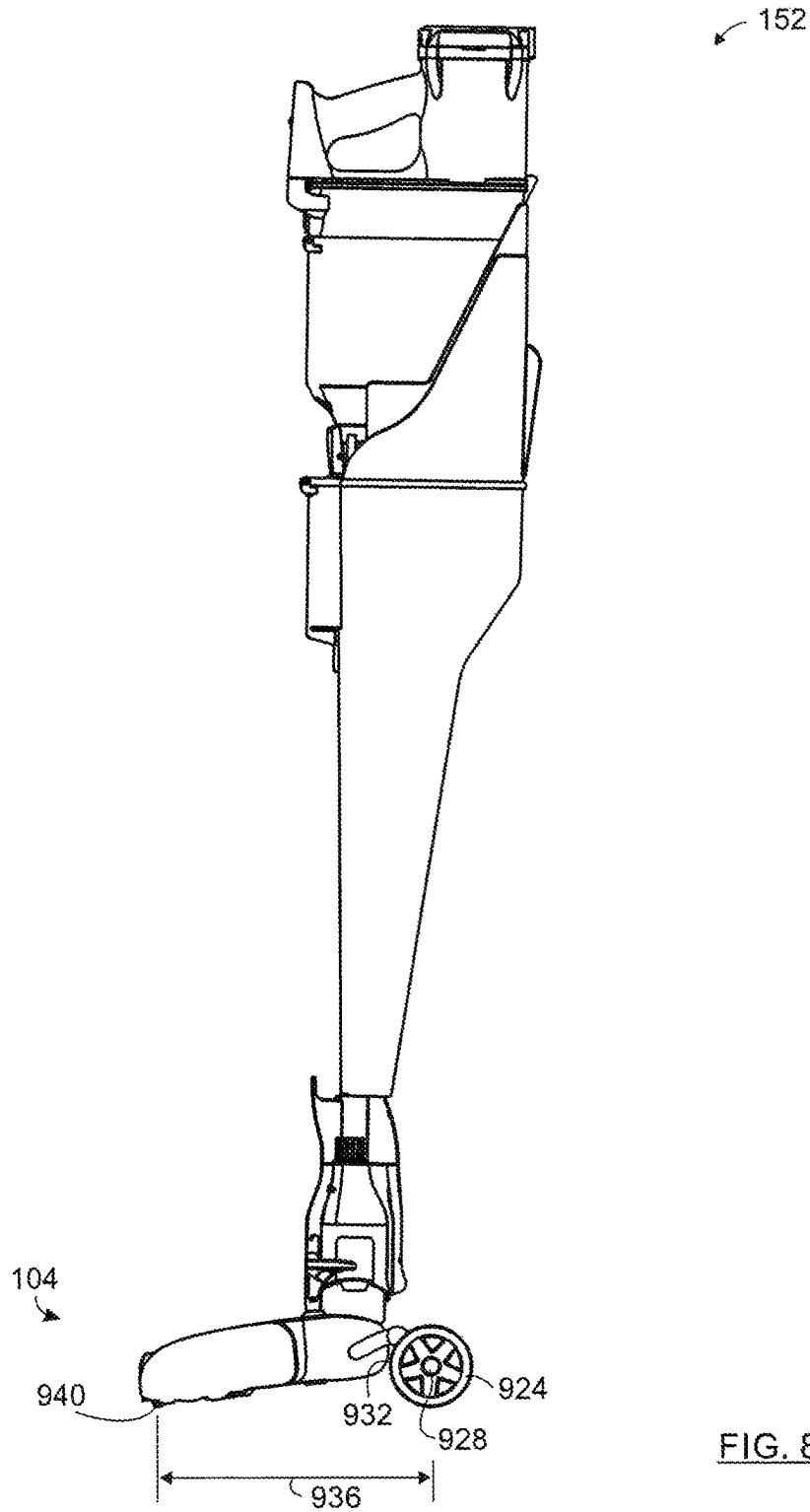


FIG. 80

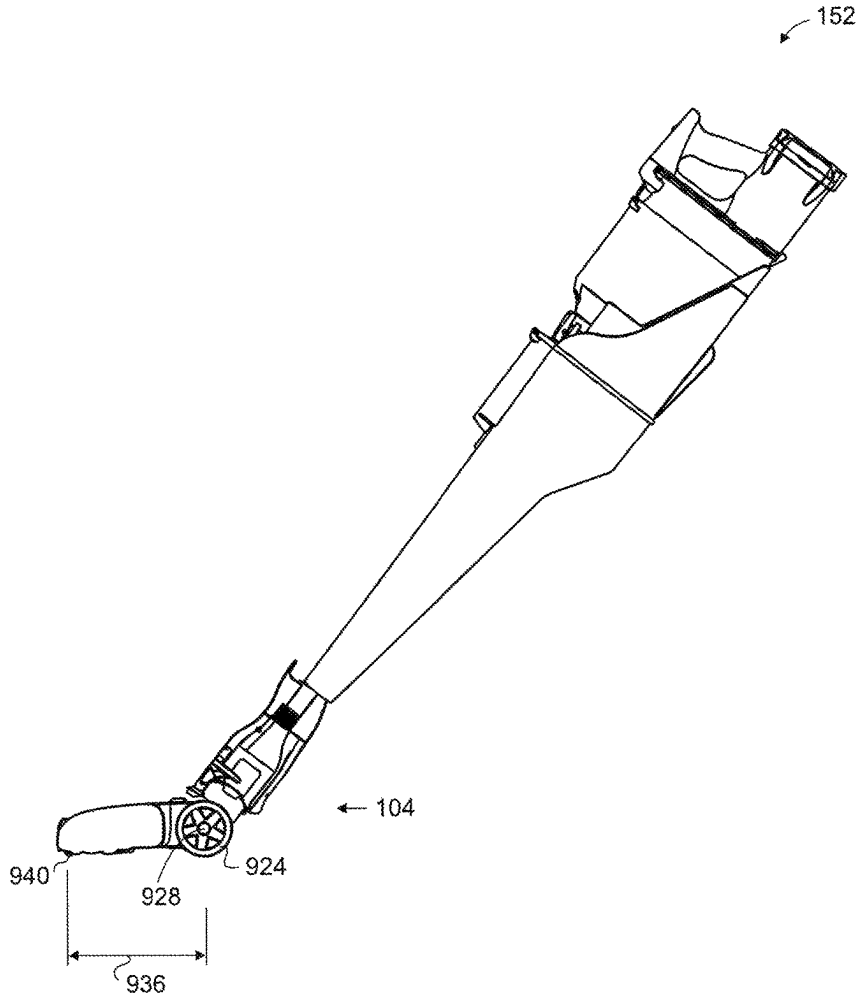


FIG. 81

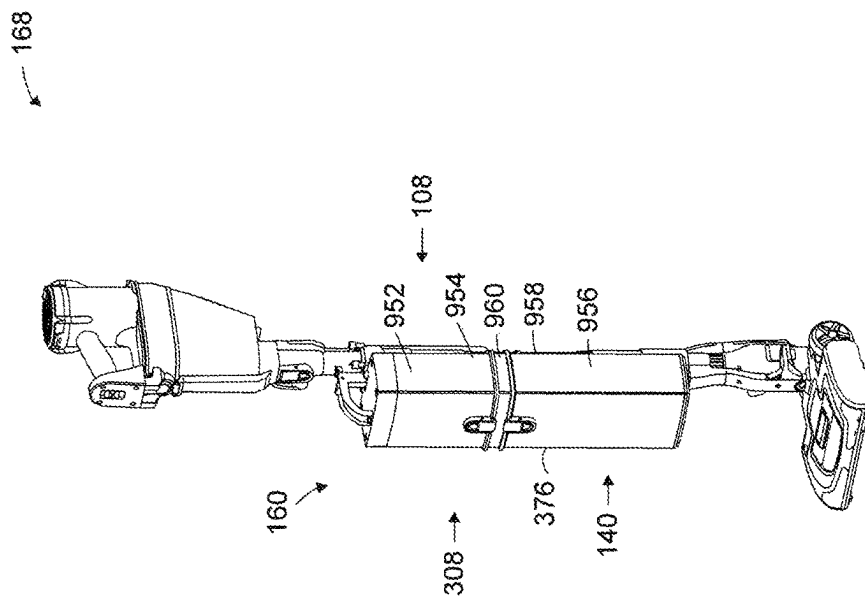


FIG. 82

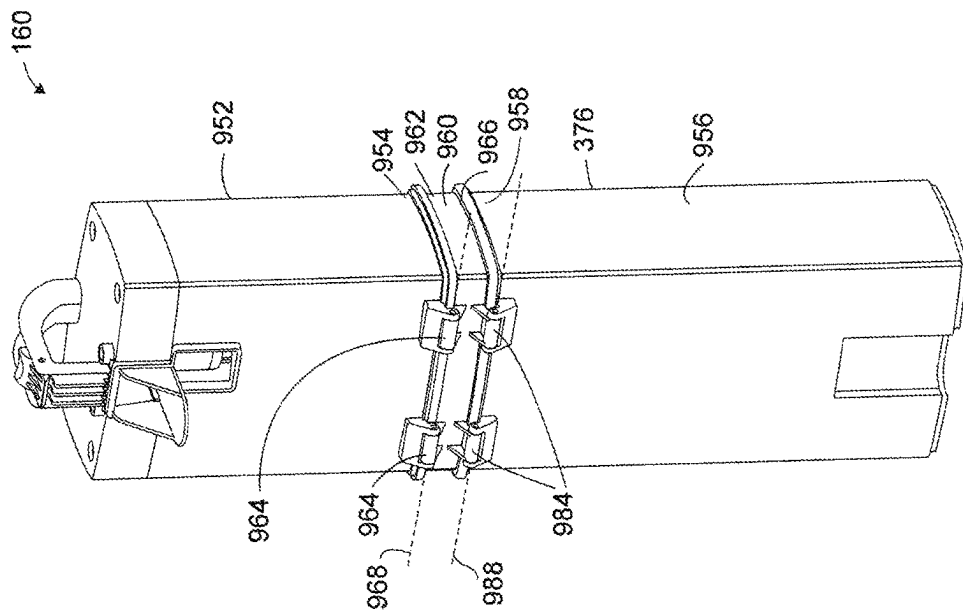


FIG. 83

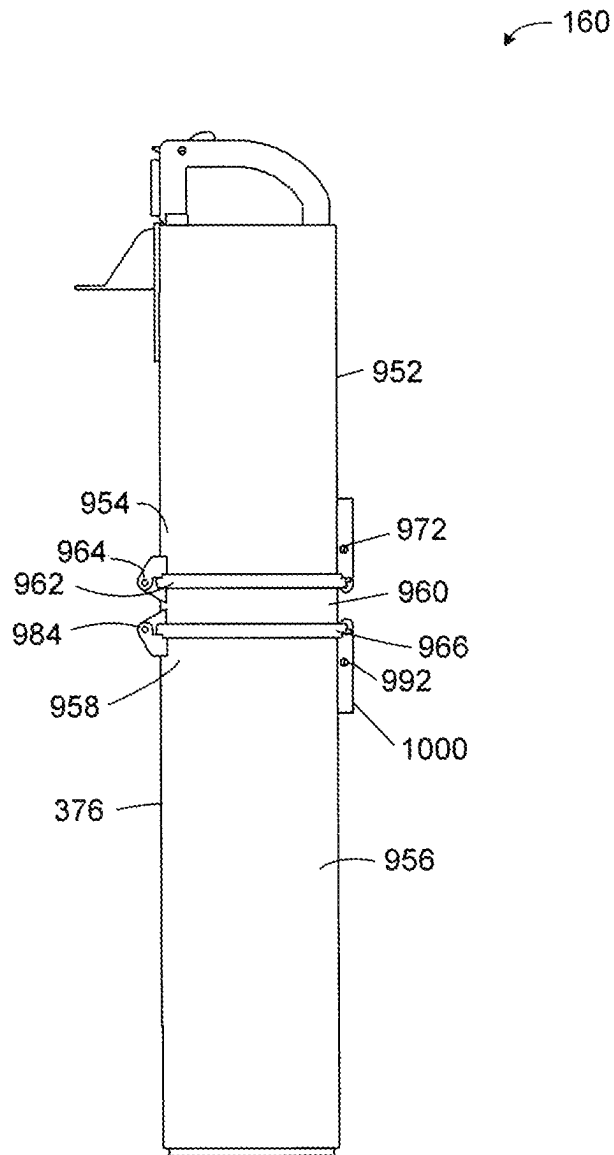


FIG. 84

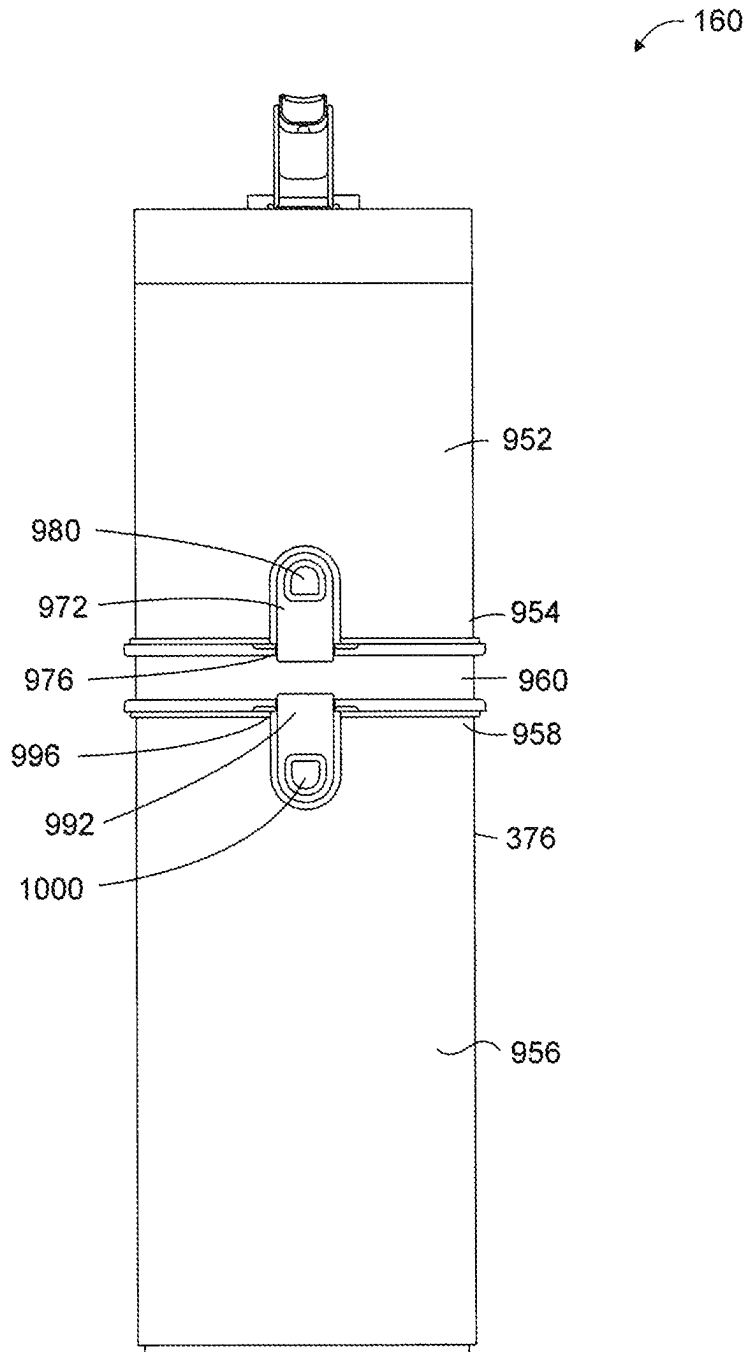


FIG. 85

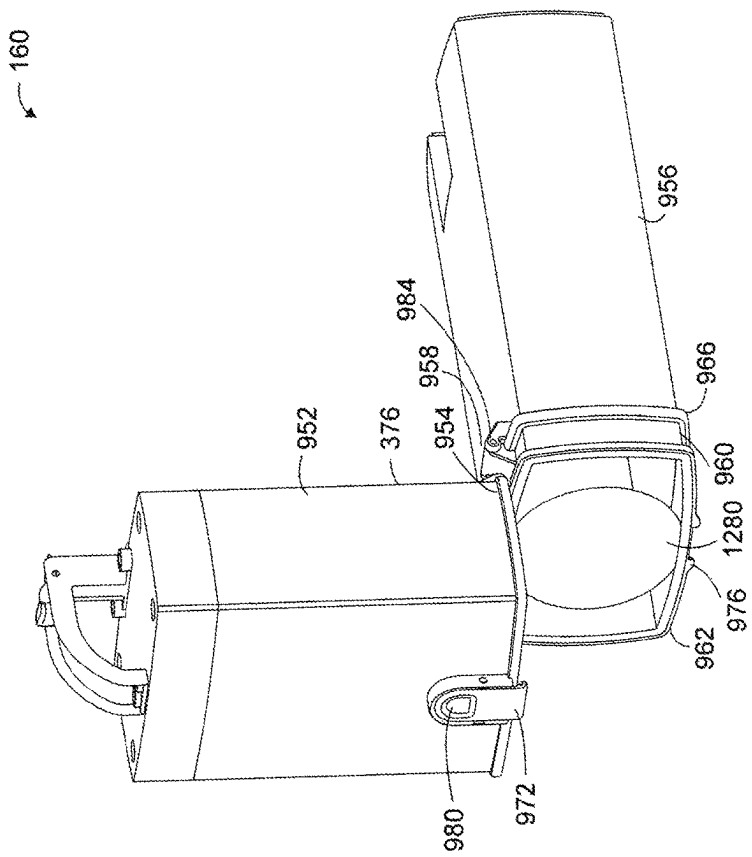


FIG. 86

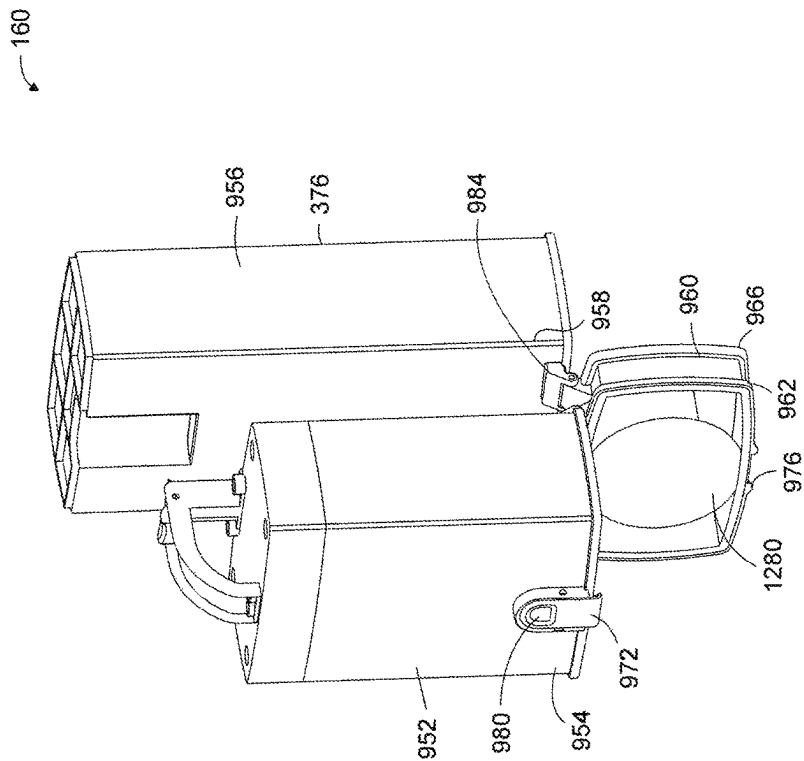


FIG. 87

160

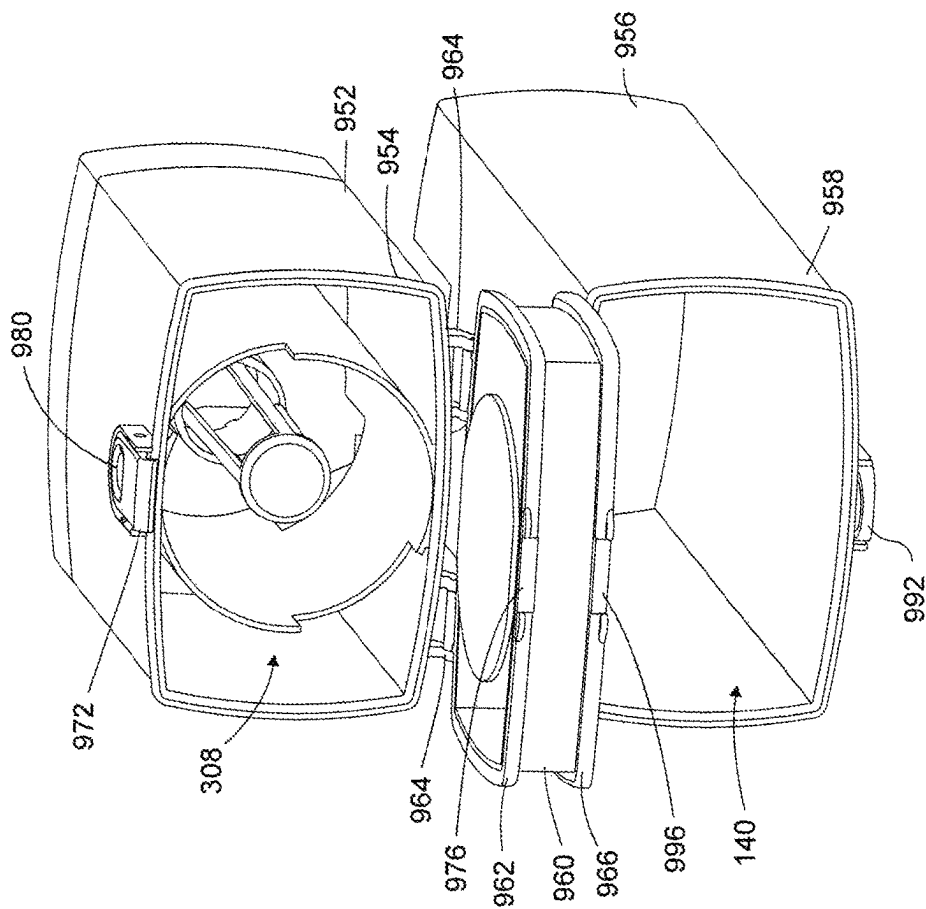


FIG. 88

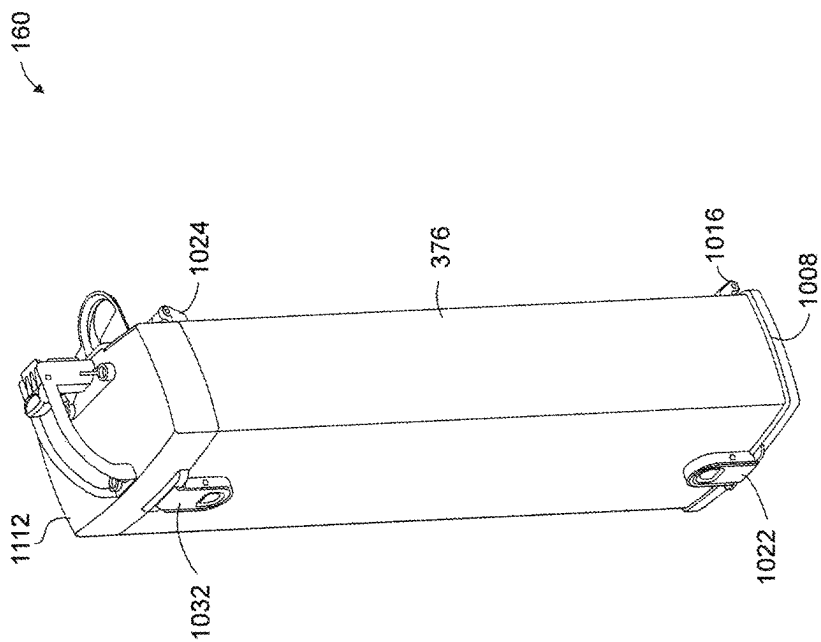


FIG. 89

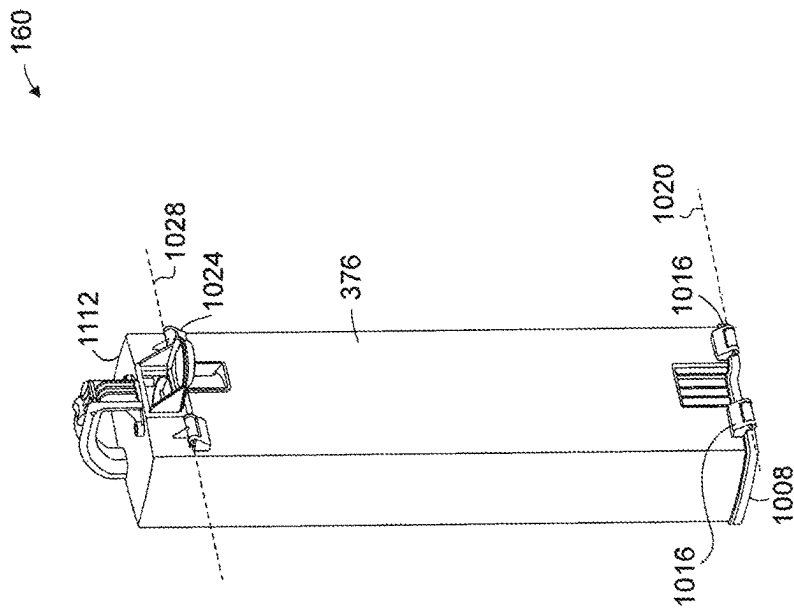


FIG. 90

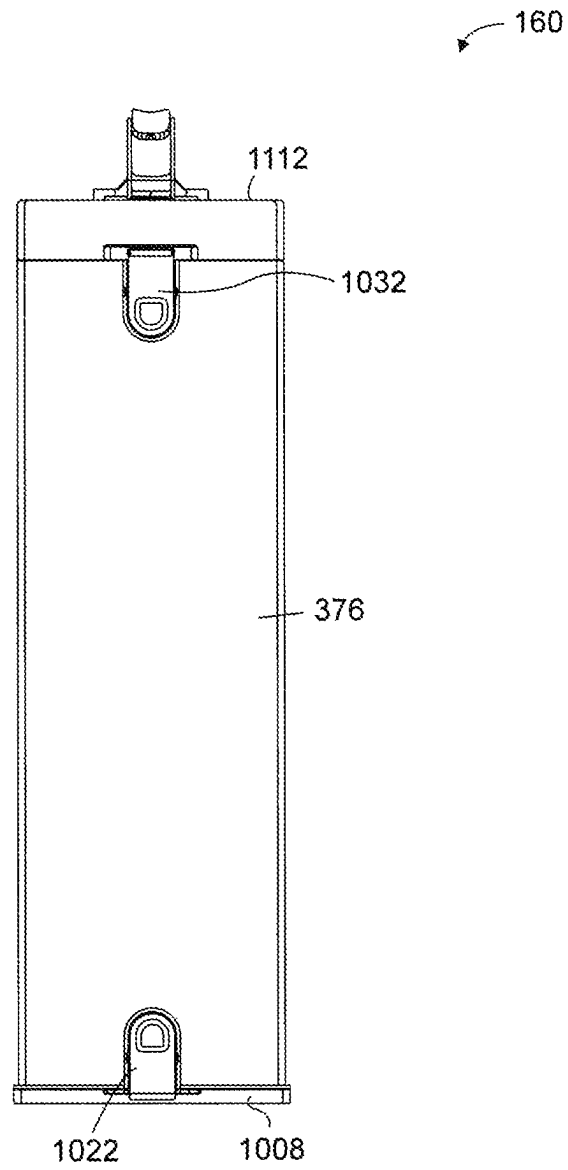


FIG. 91

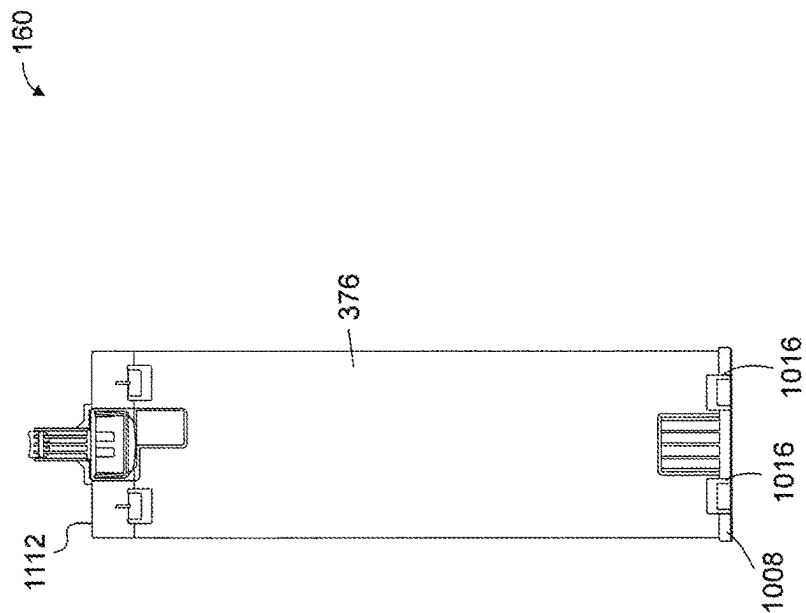


FIG. 92

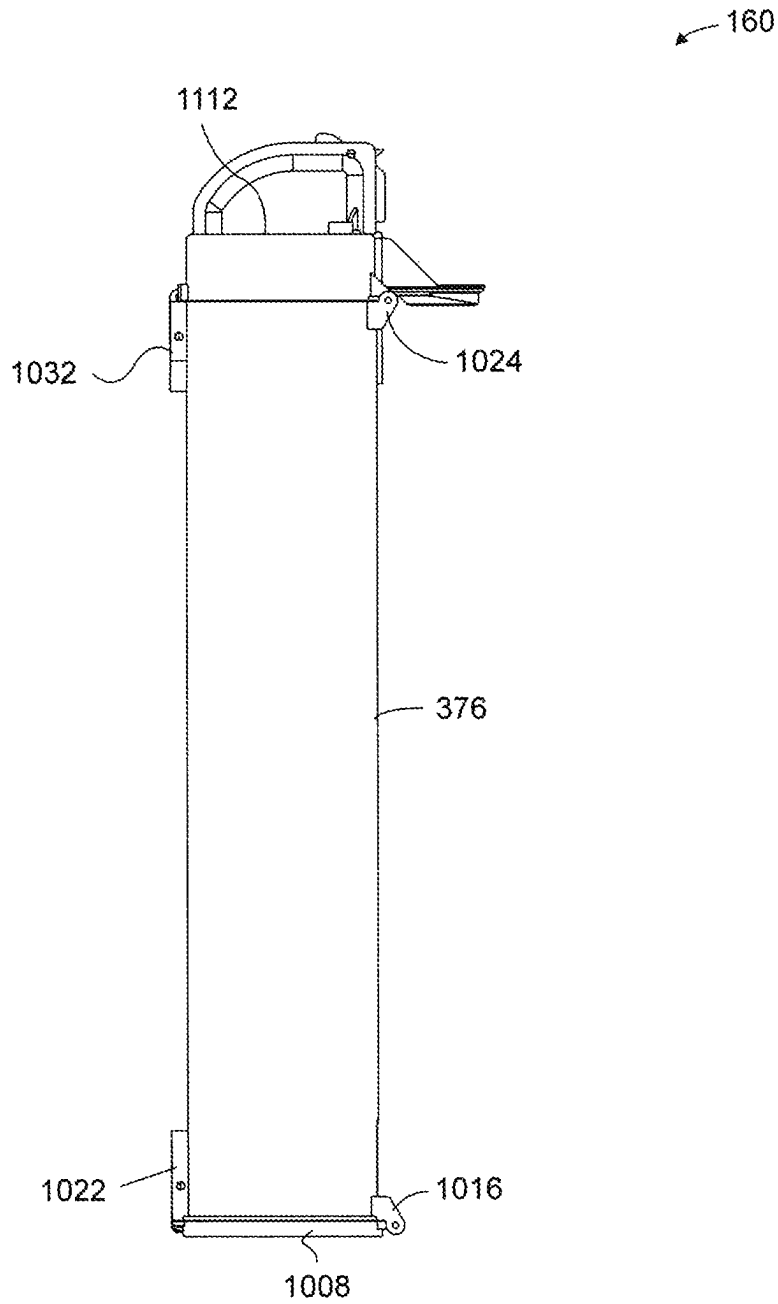


FIG. 93

← 160

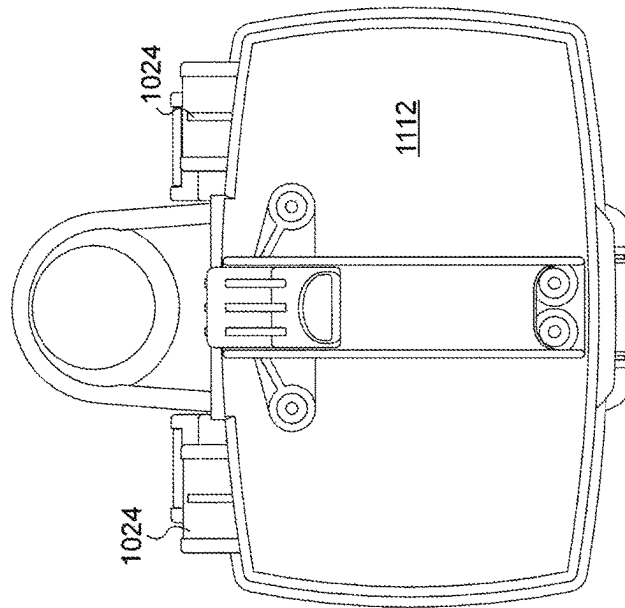


FIG. 94

160

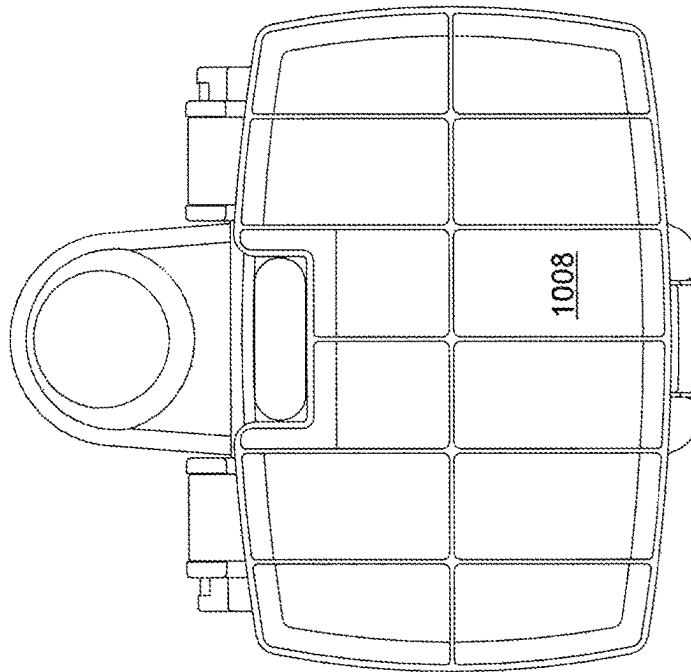


FIG. 95

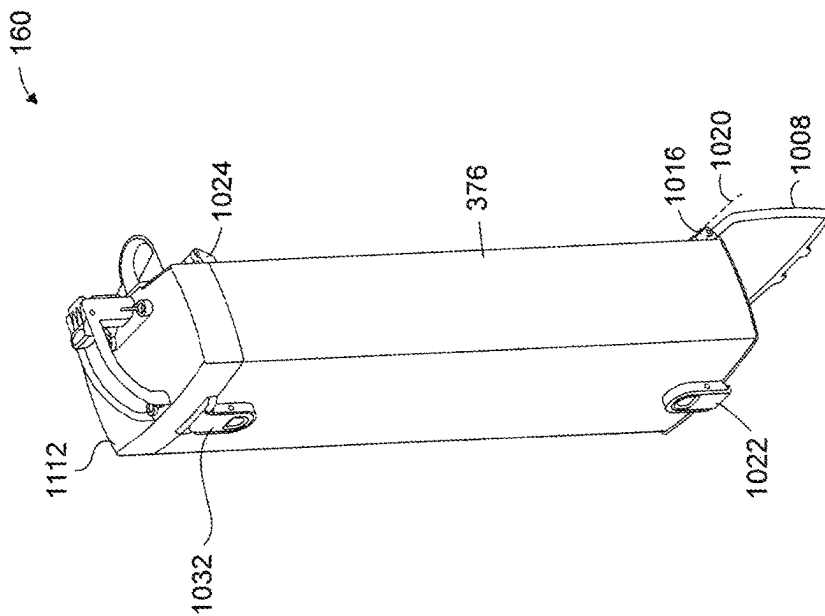


FIG. 95b

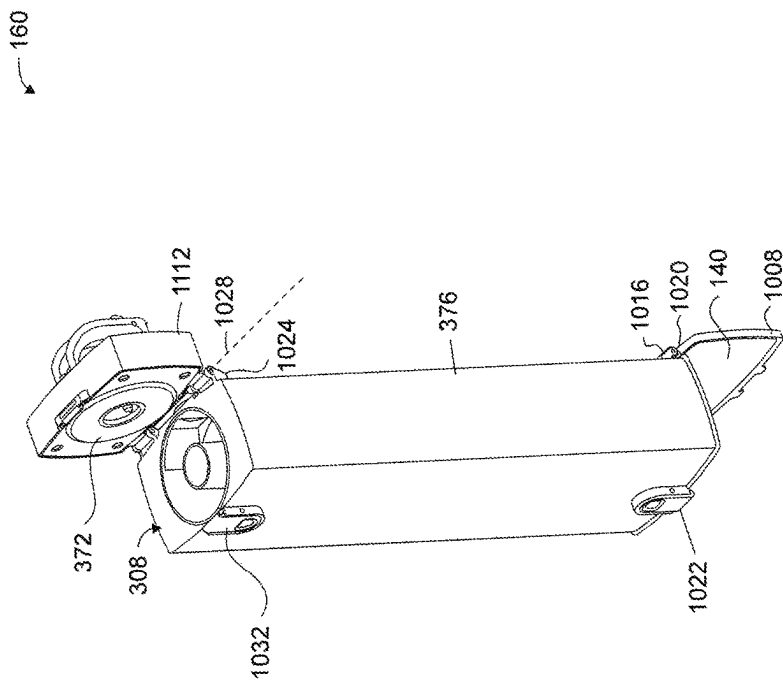


FIG. 95c

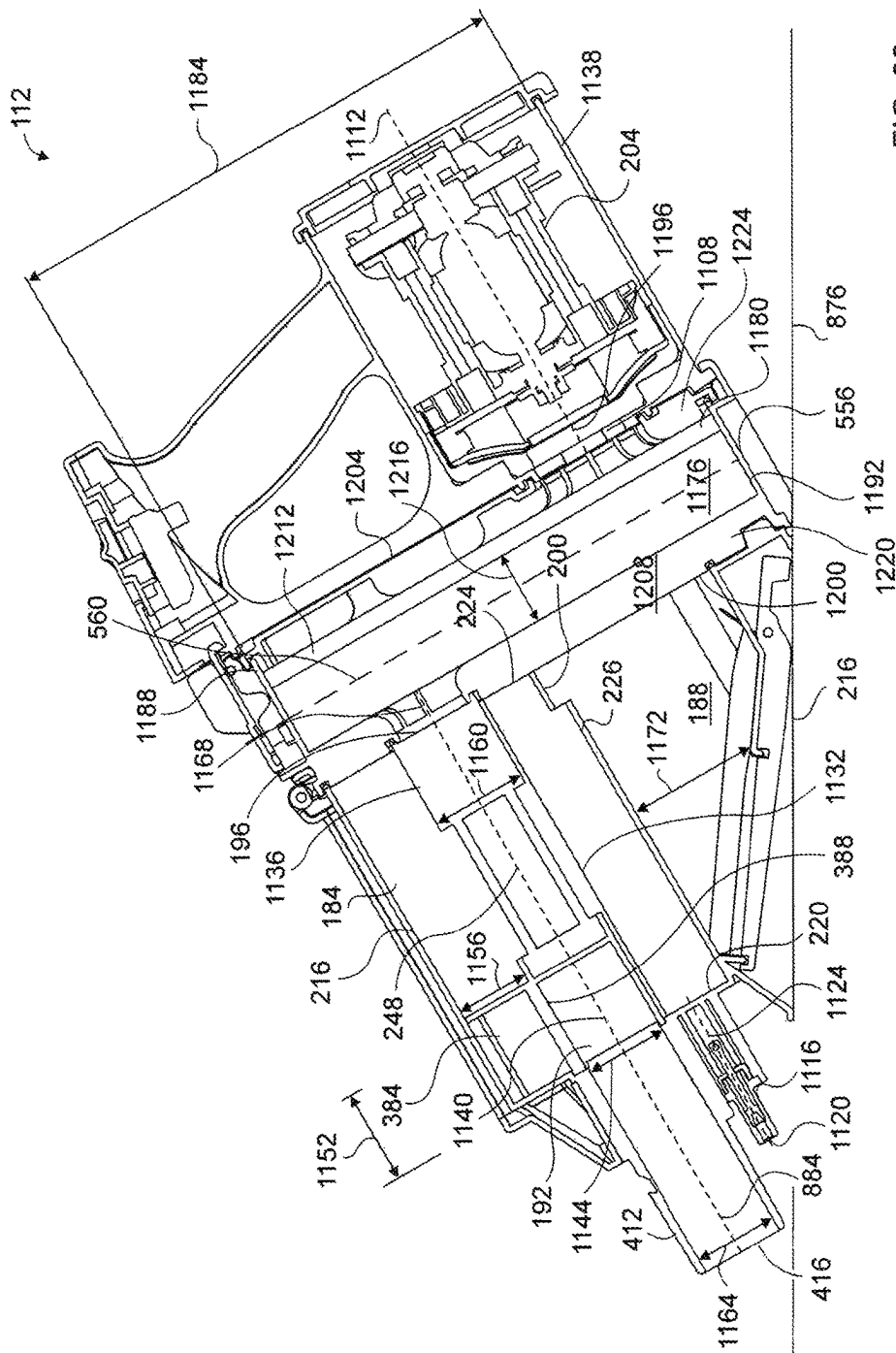


FIG. 96

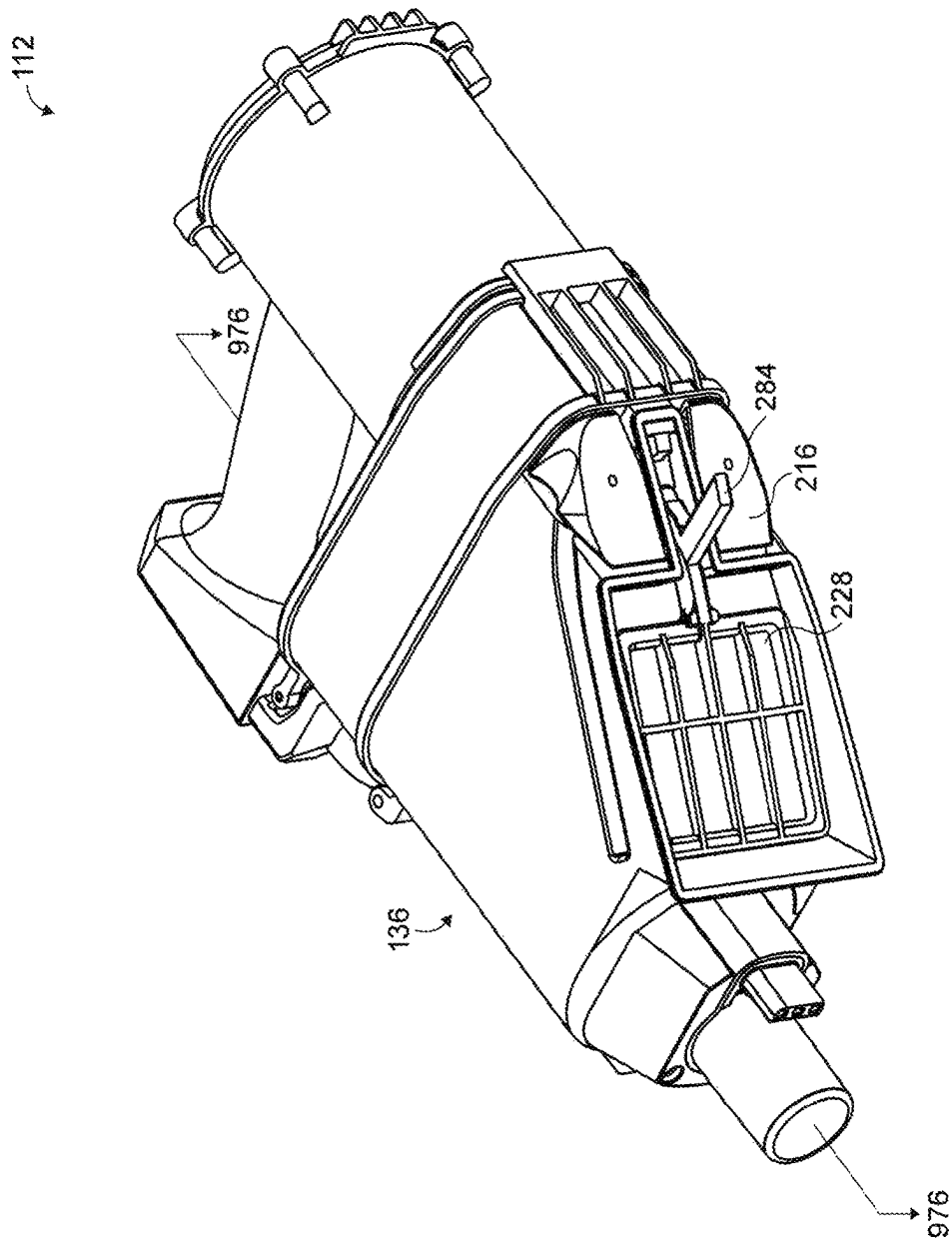


FIG. 97a

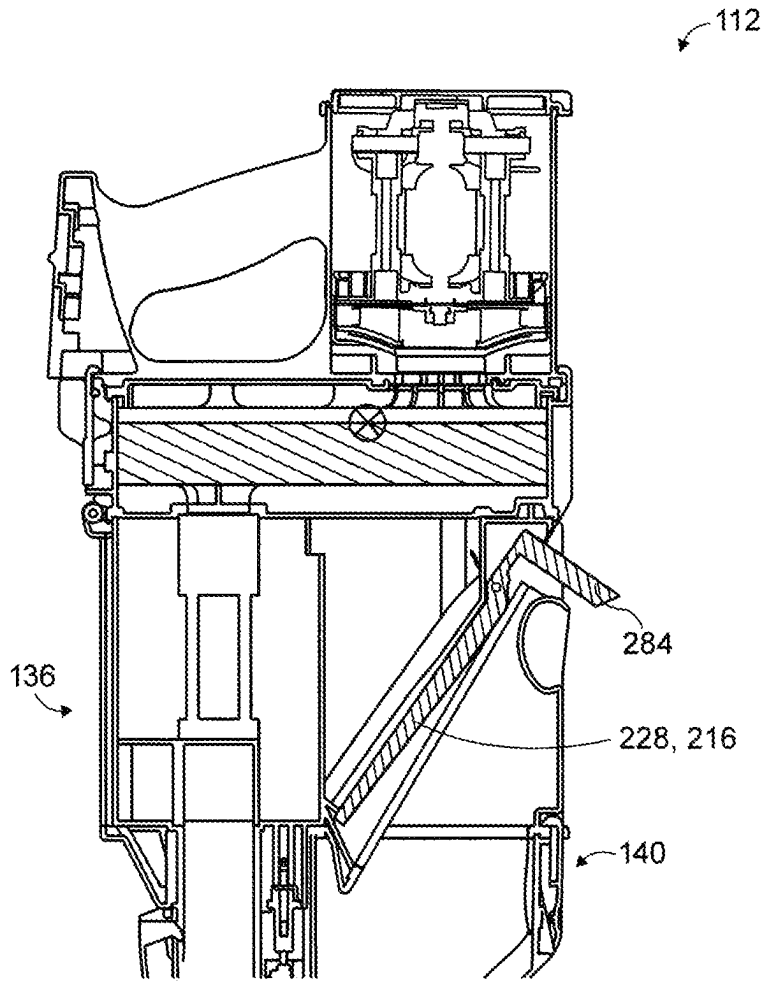


FIG. 97b

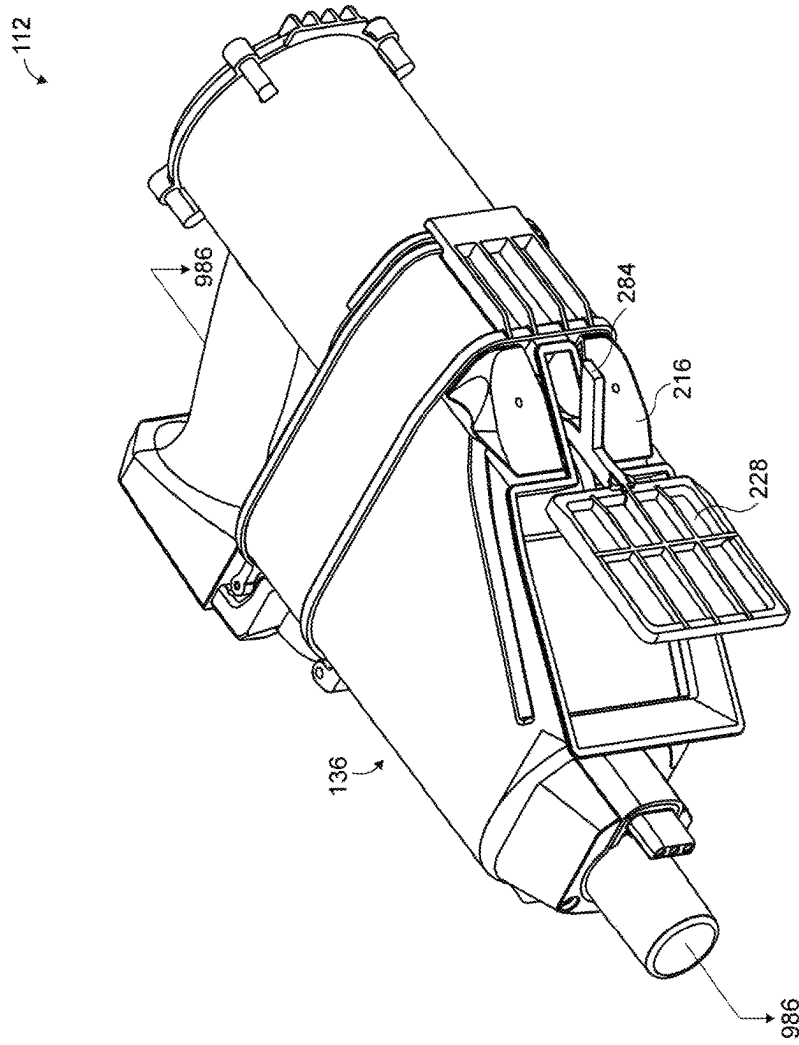


FIG. 98a

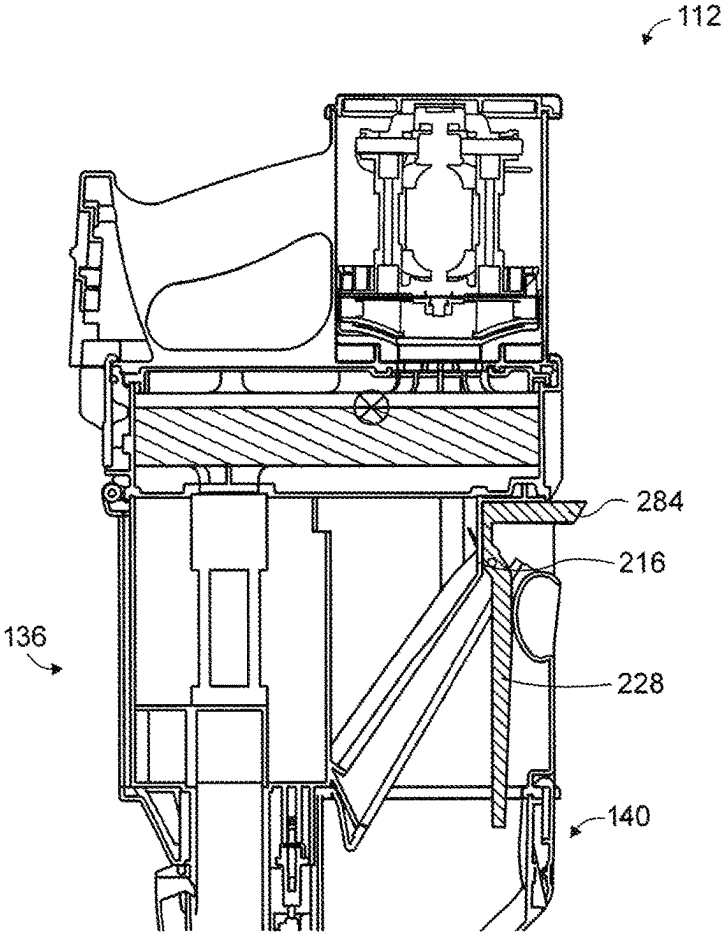


FIG. 98b

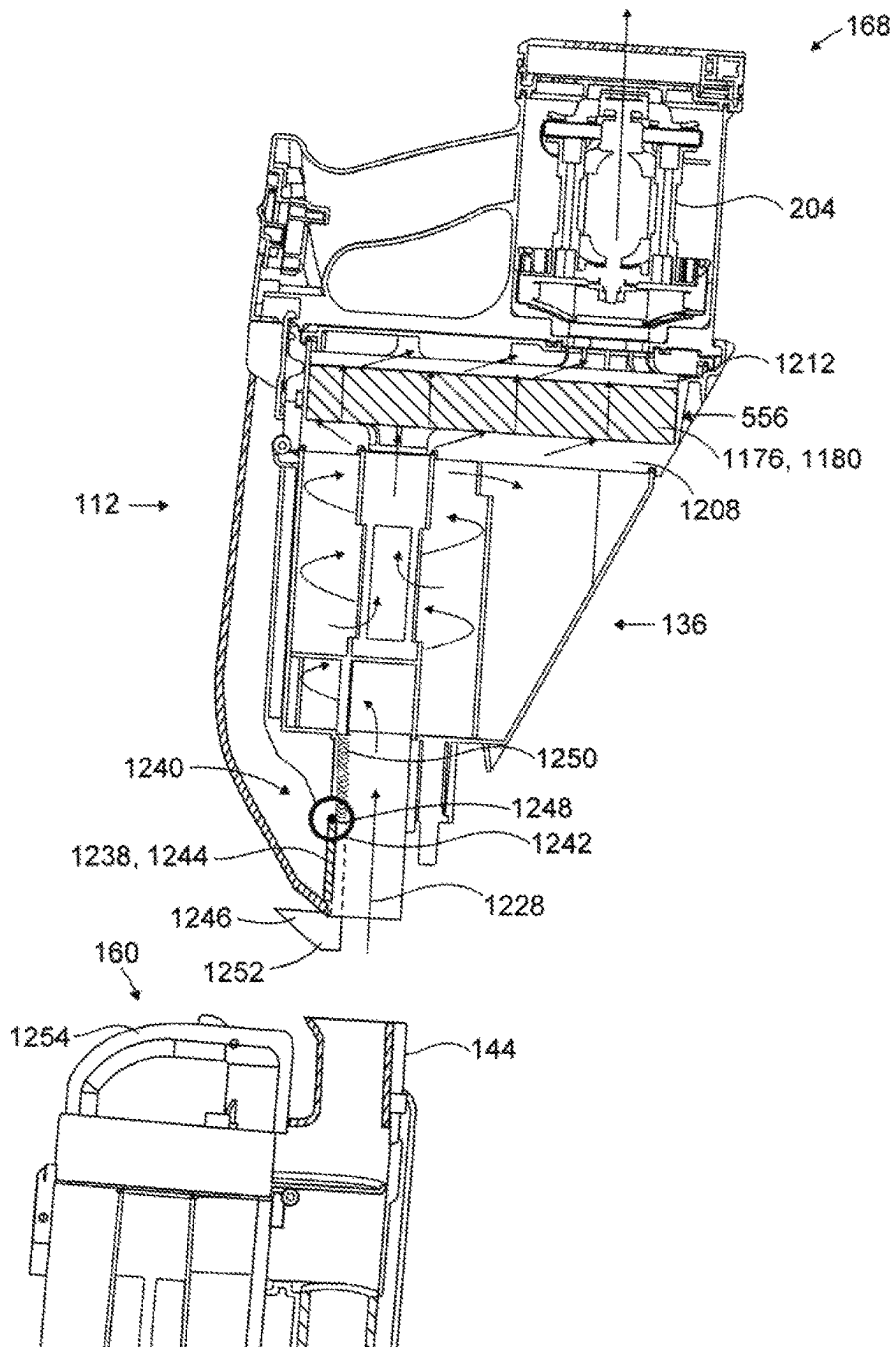


FIG. 99

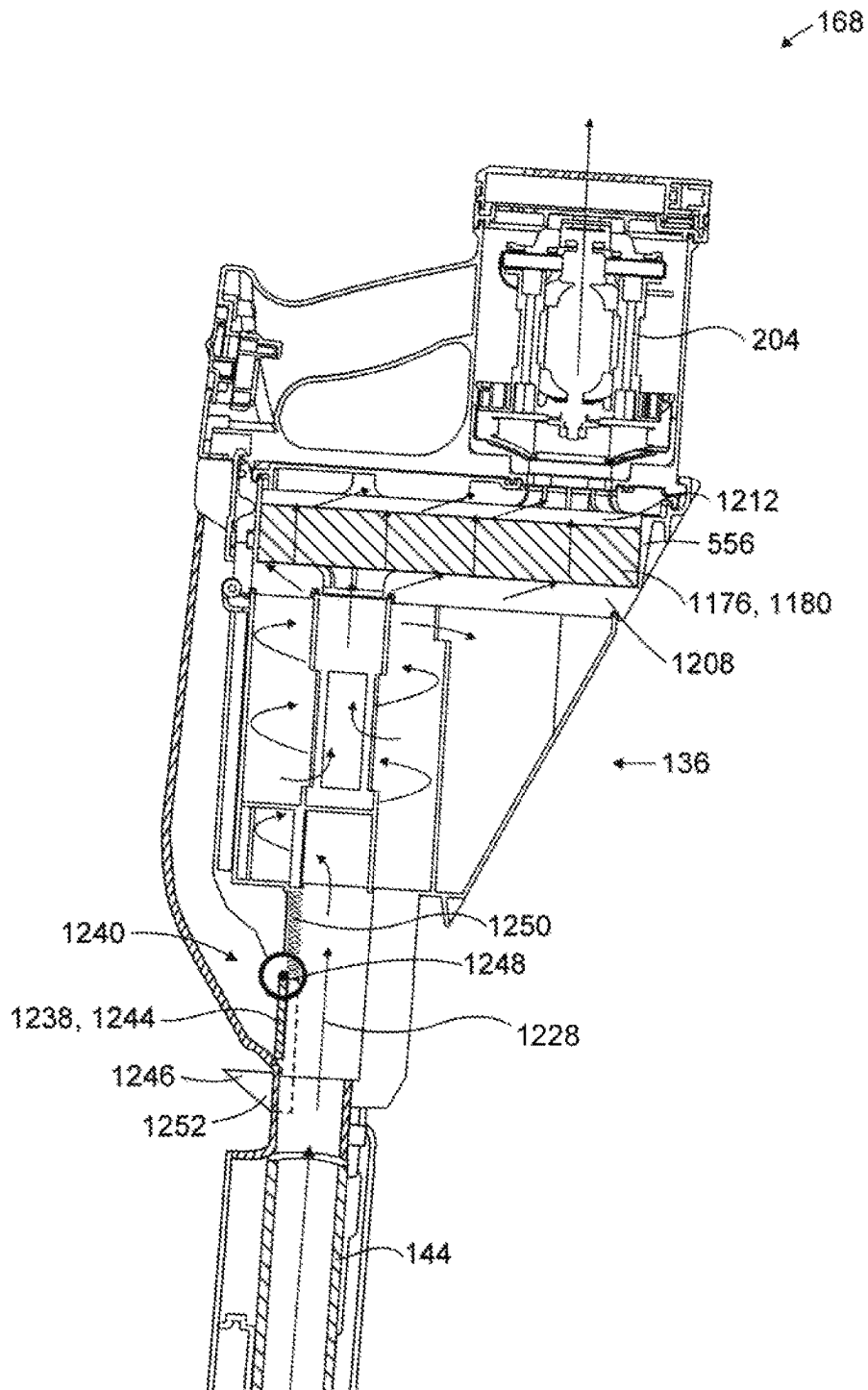


FIG. 100

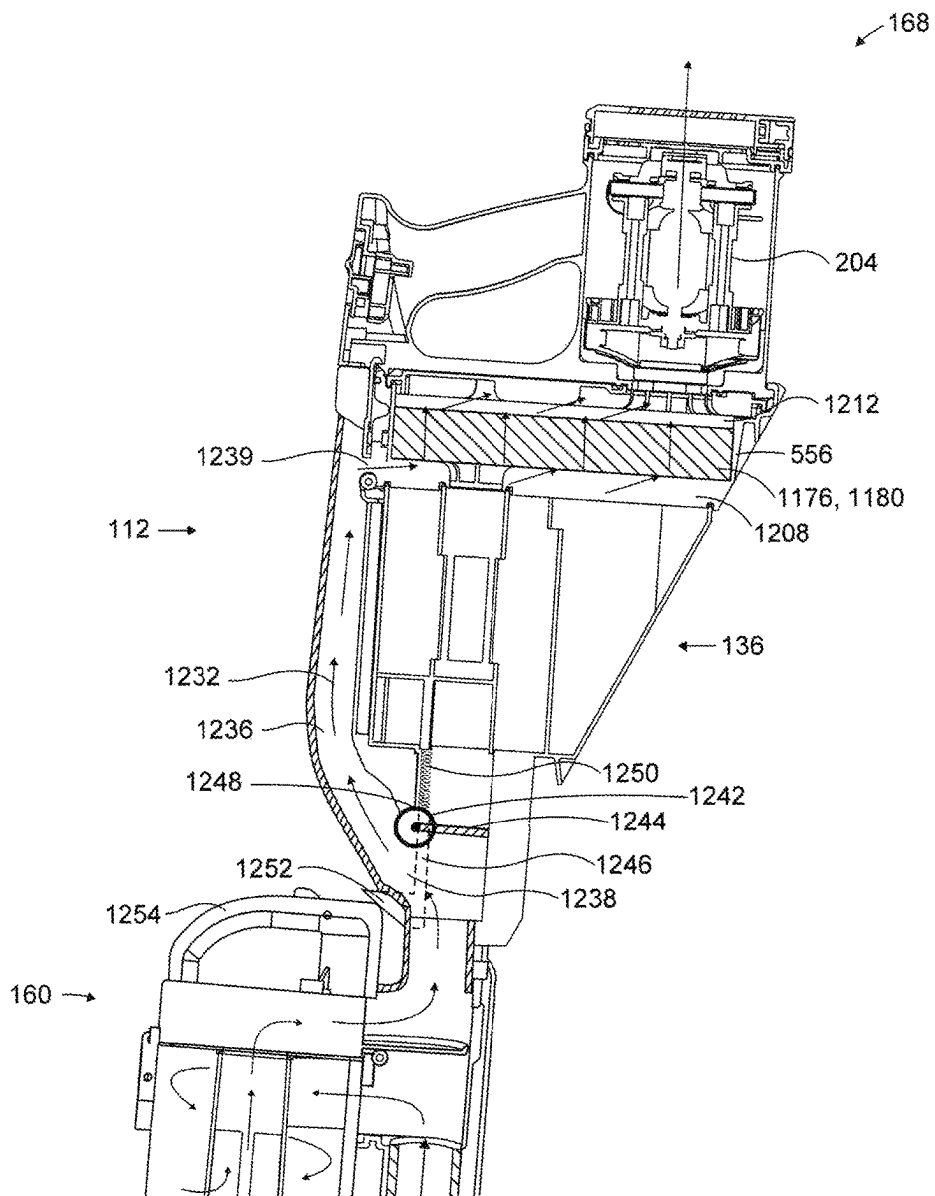


FIG. 101

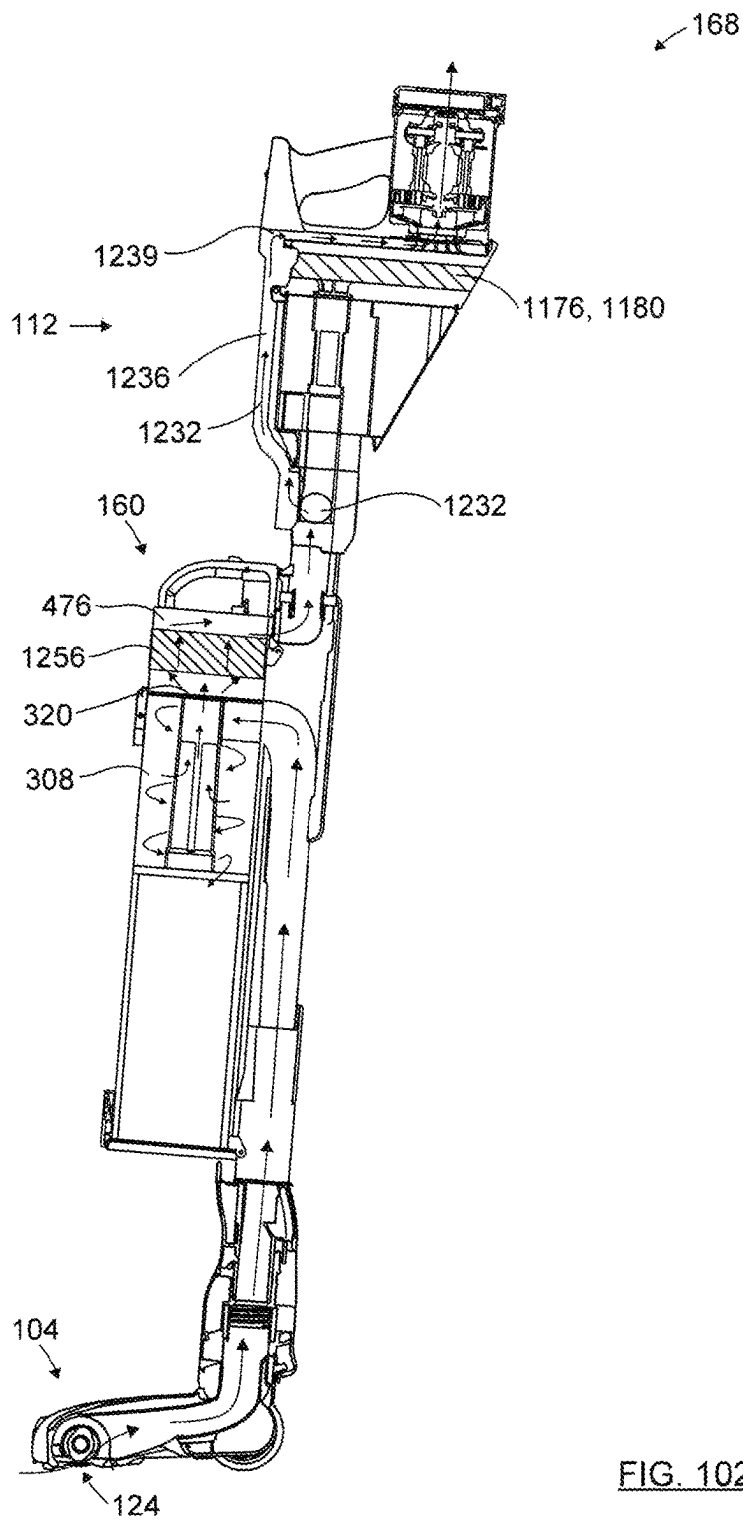


FIG. 102

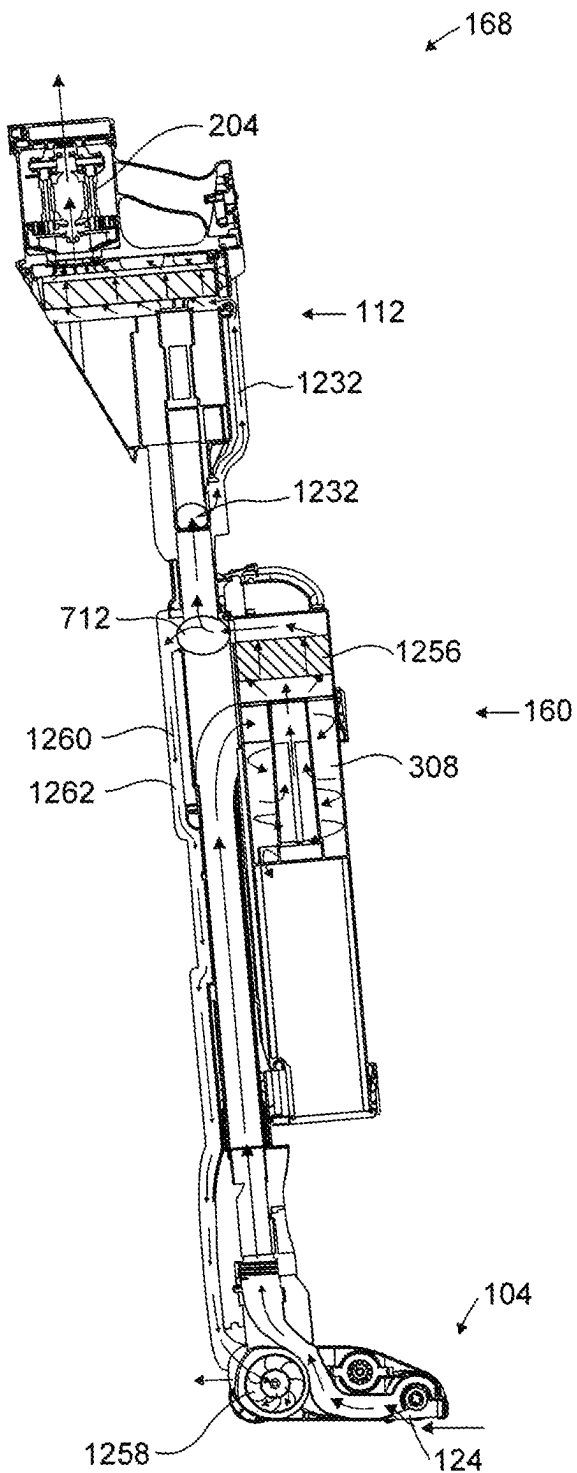


FIG. 103

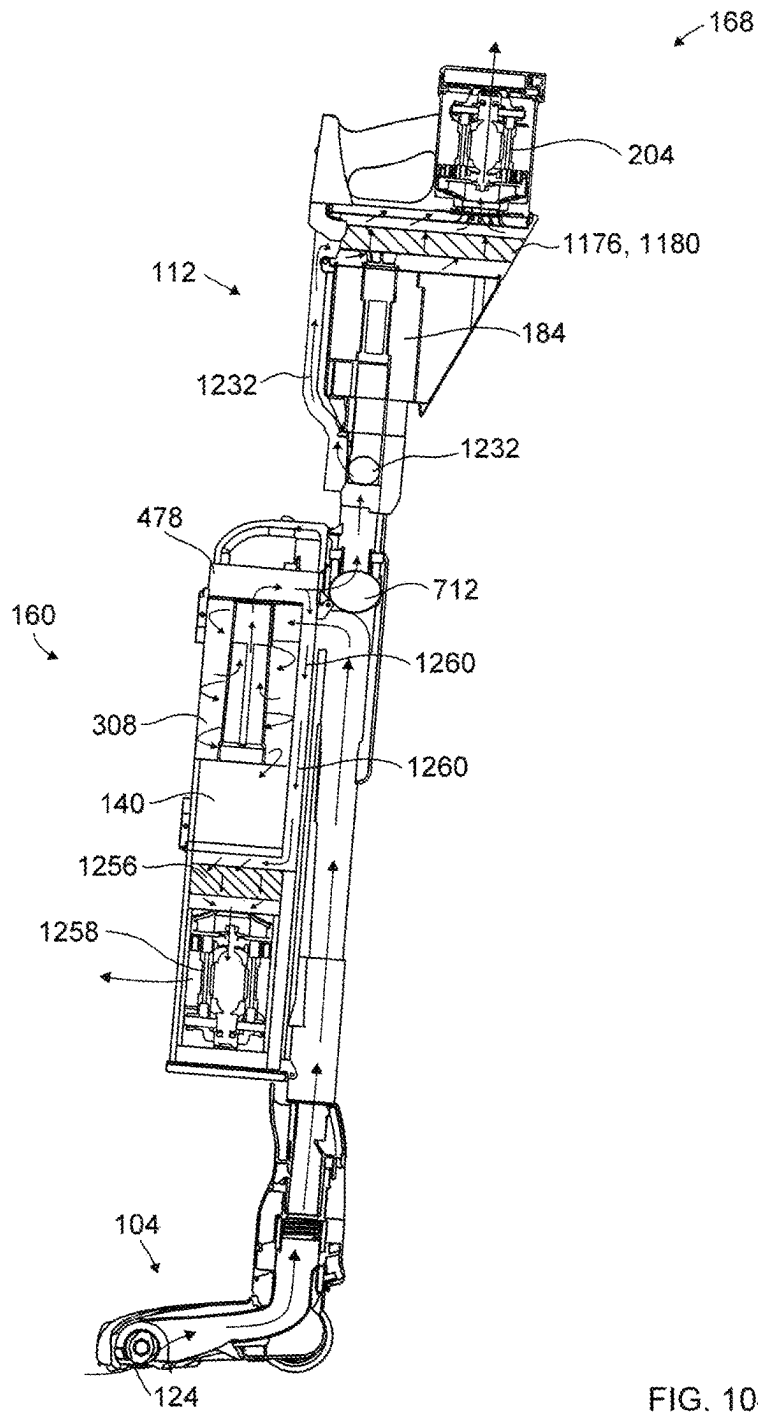


FIG. 104a

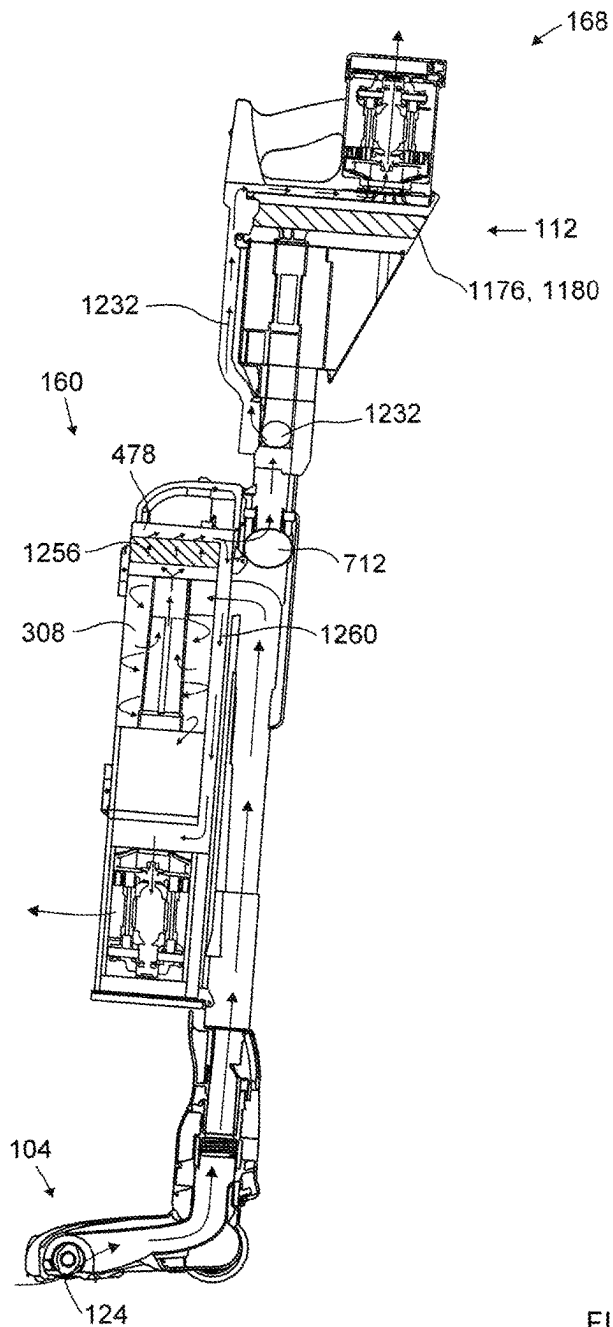


FIG. 104b

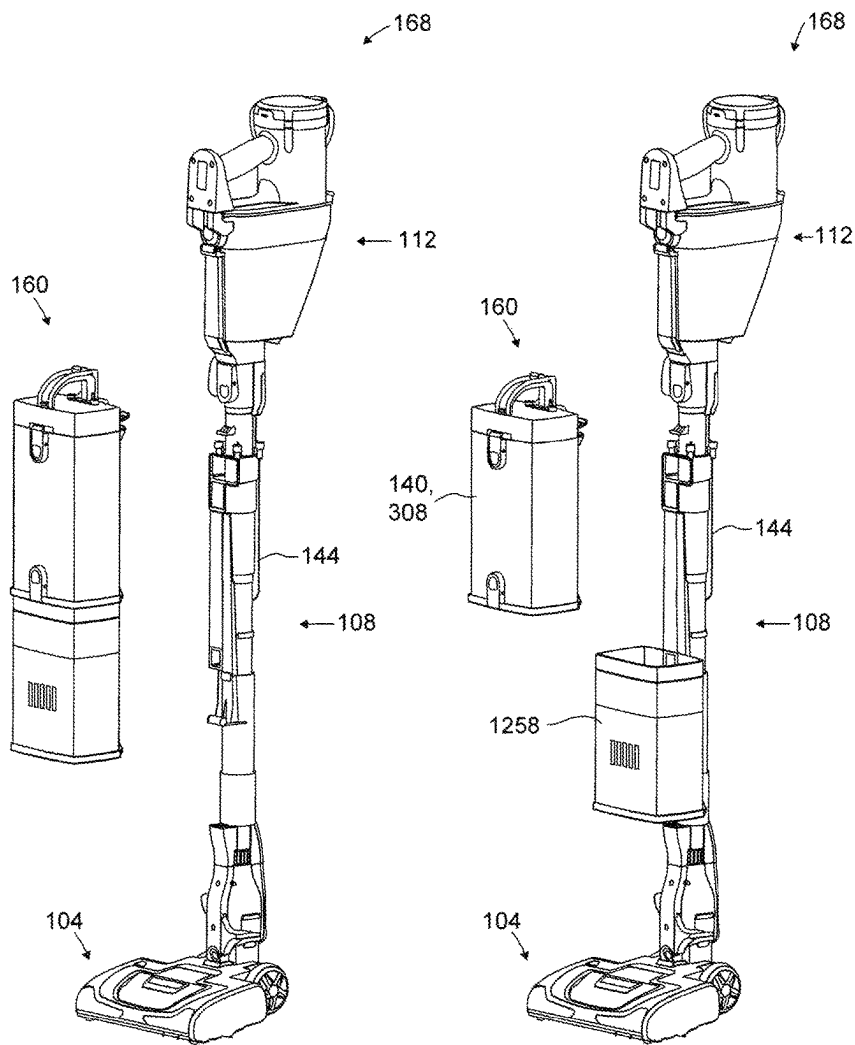


FIG. 105a

FIG. 105b

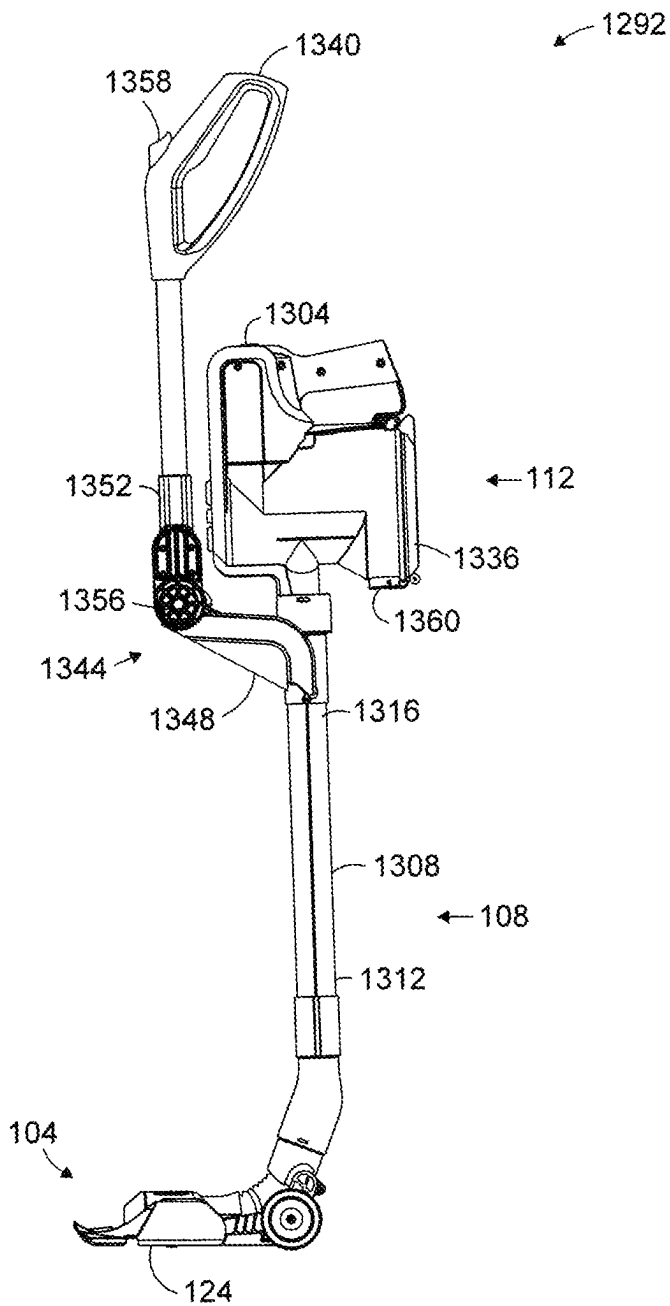


FIG. 106

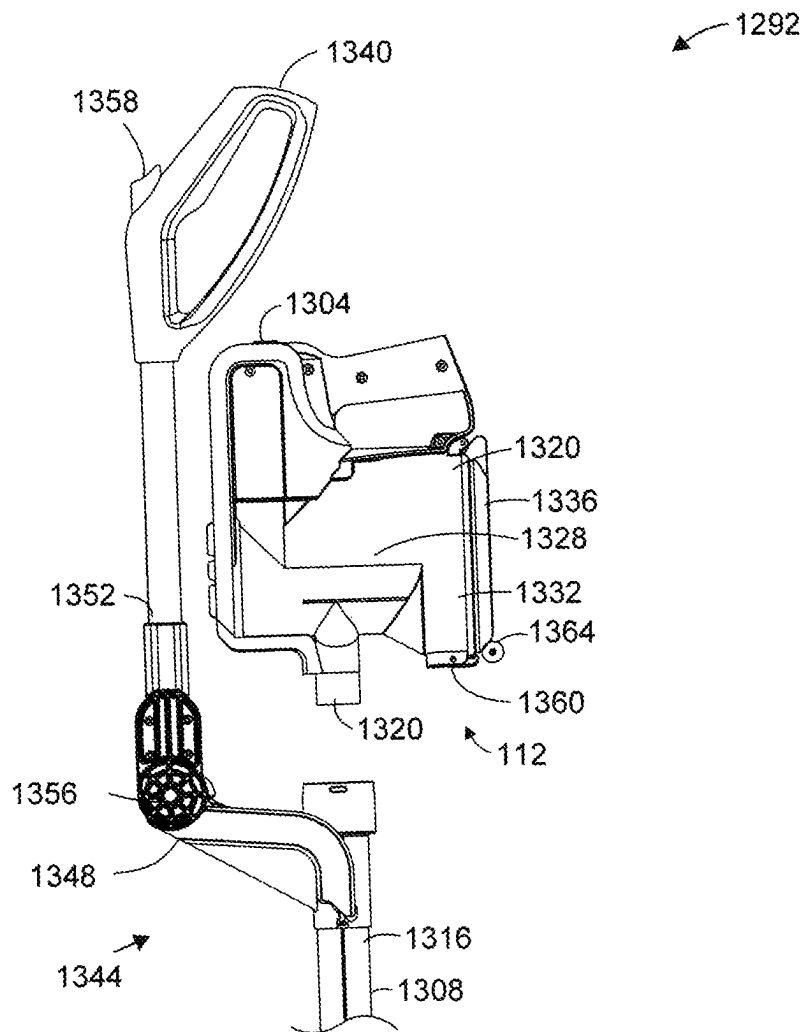


FIG. 107

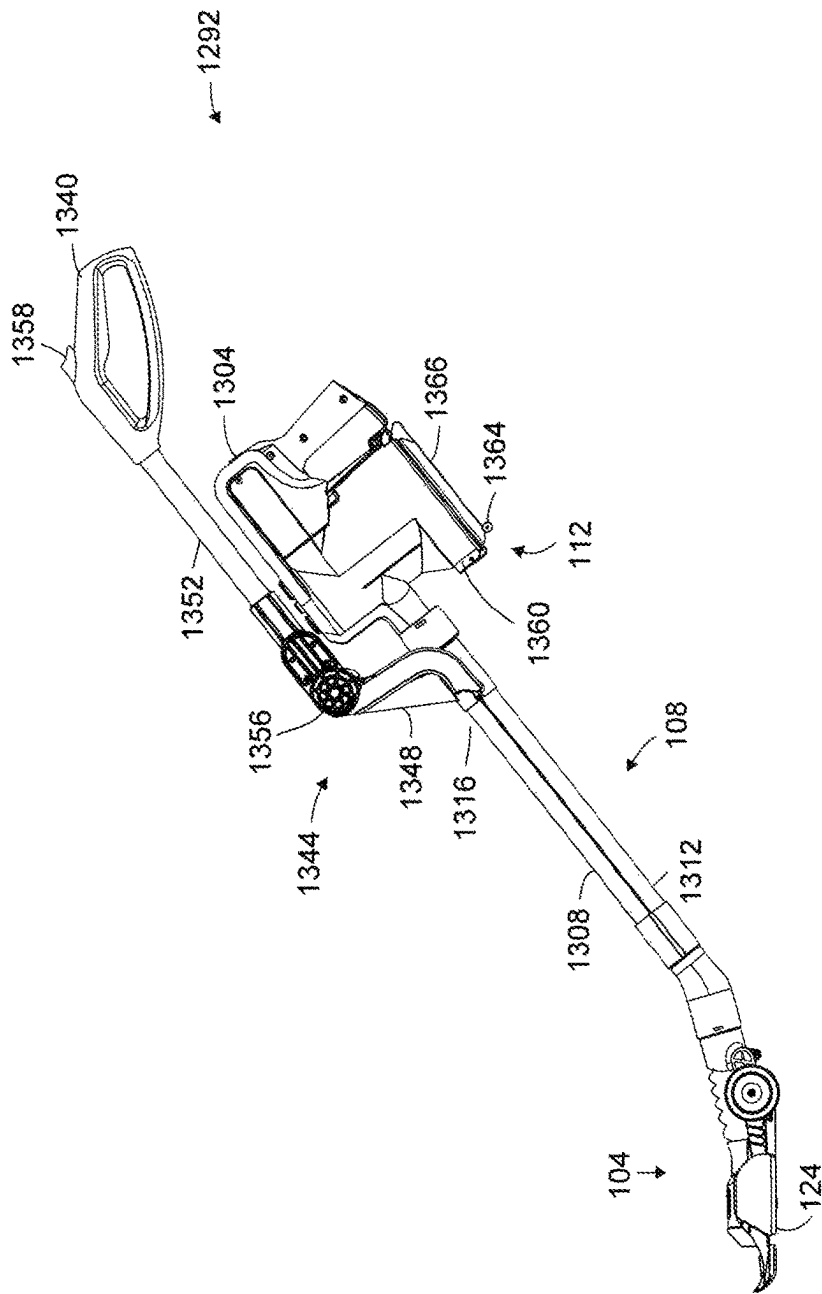


FIG. 108

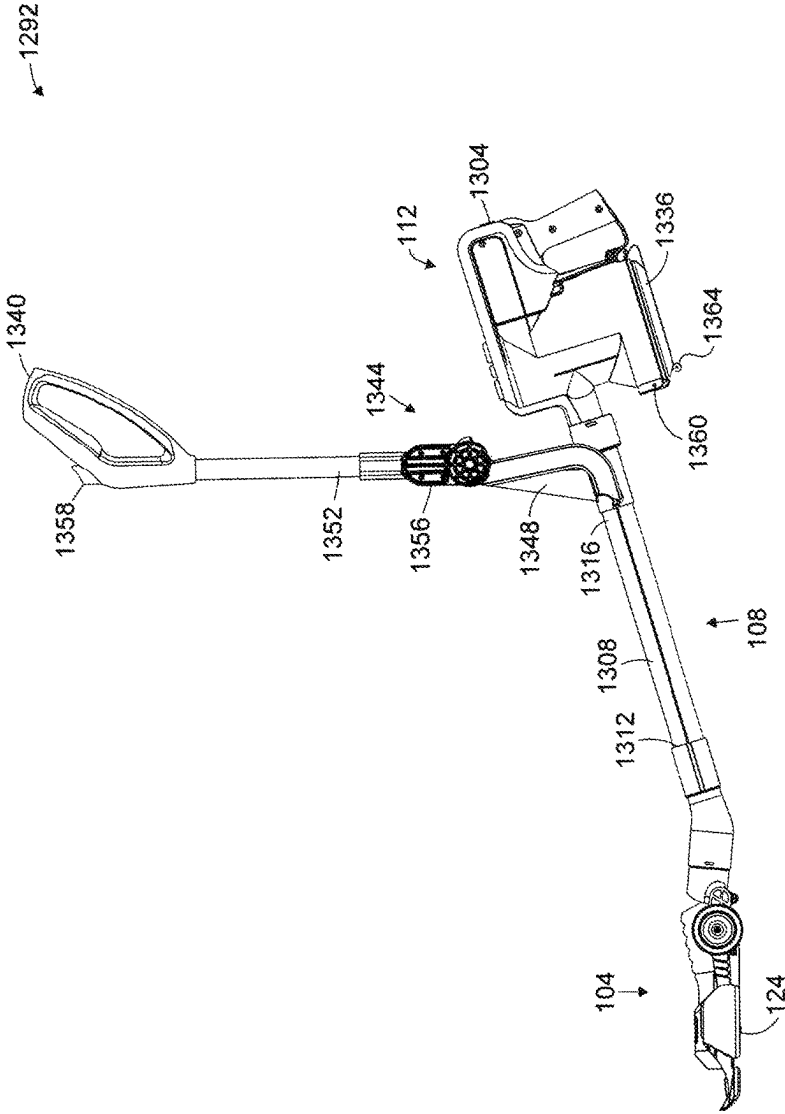


FIG. 109

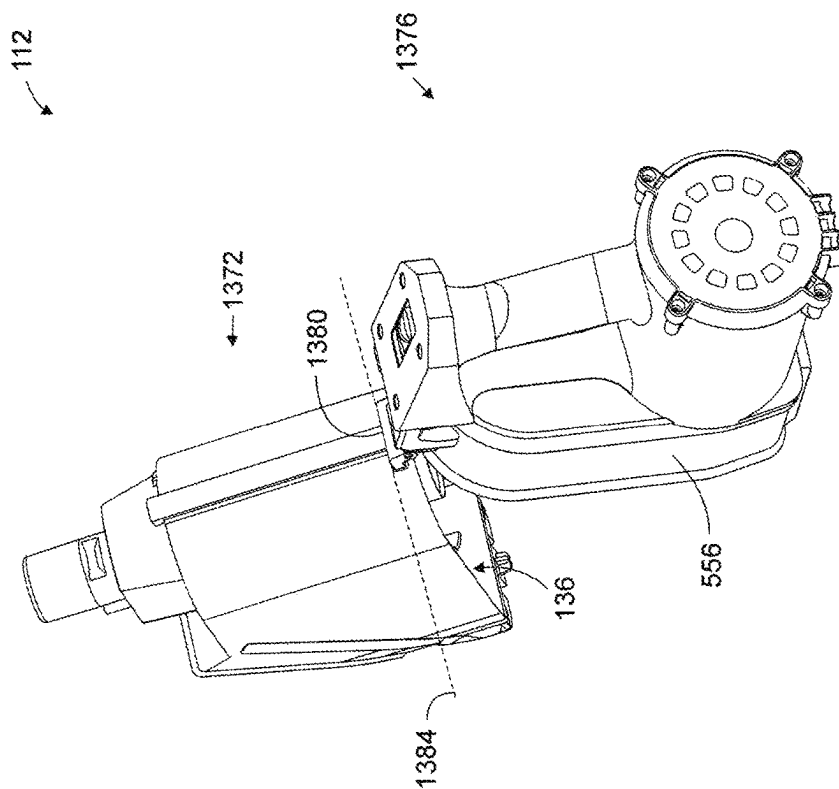


FIG. 110a

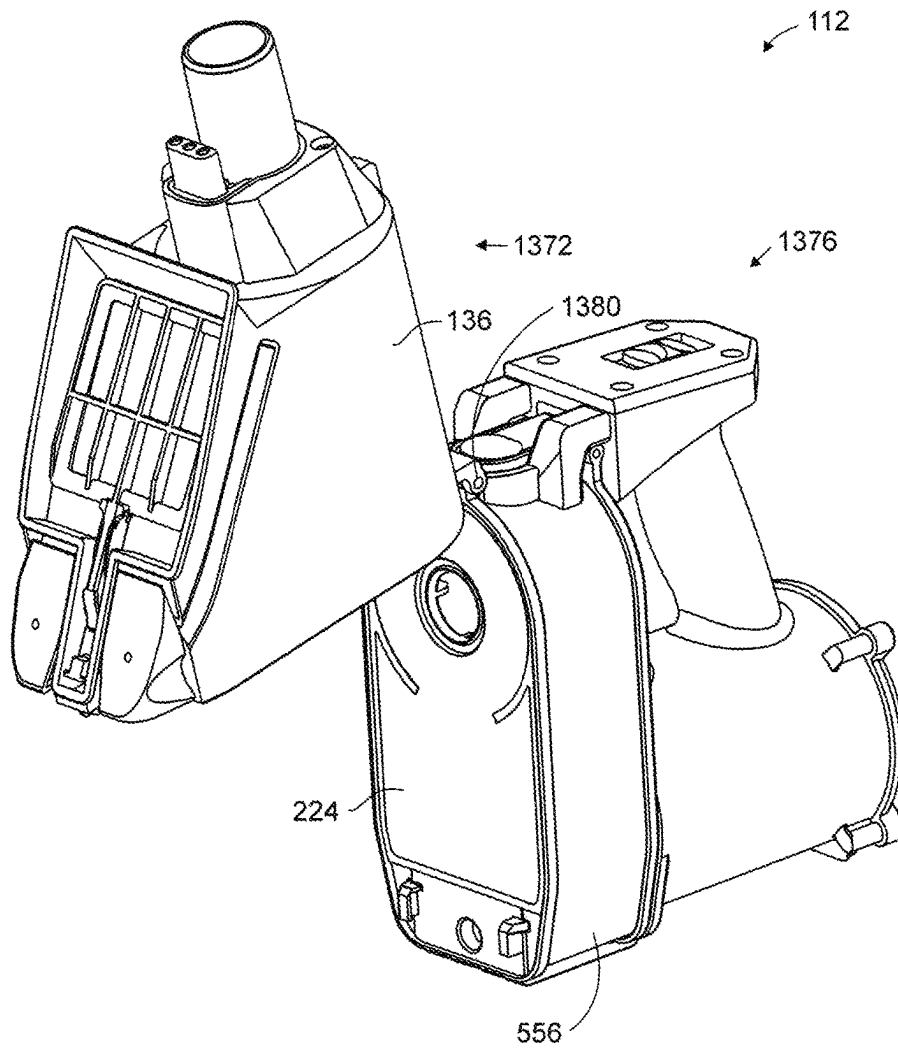


FIG. 110b

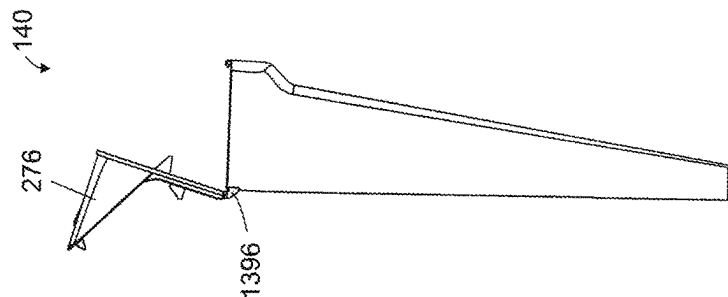


FIG. 113

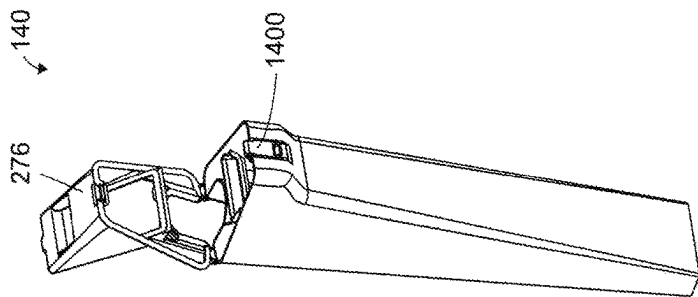


FIG. 112

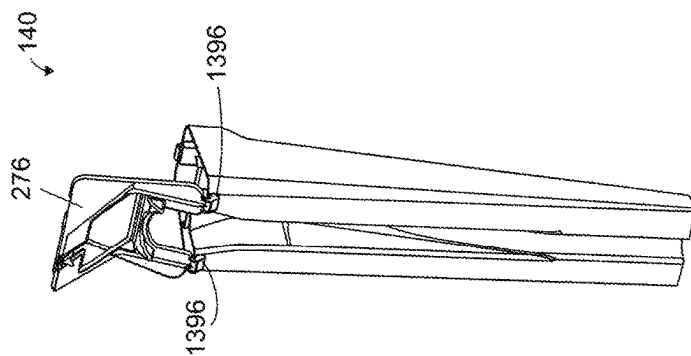


FIG. 111

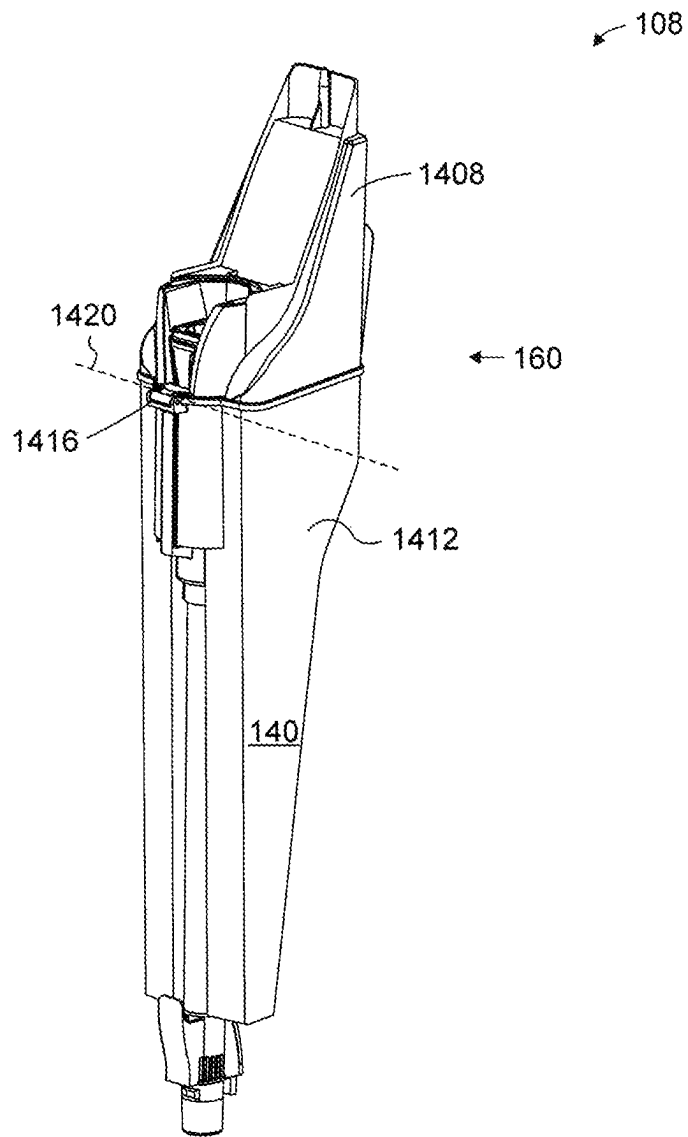


FIG. 114

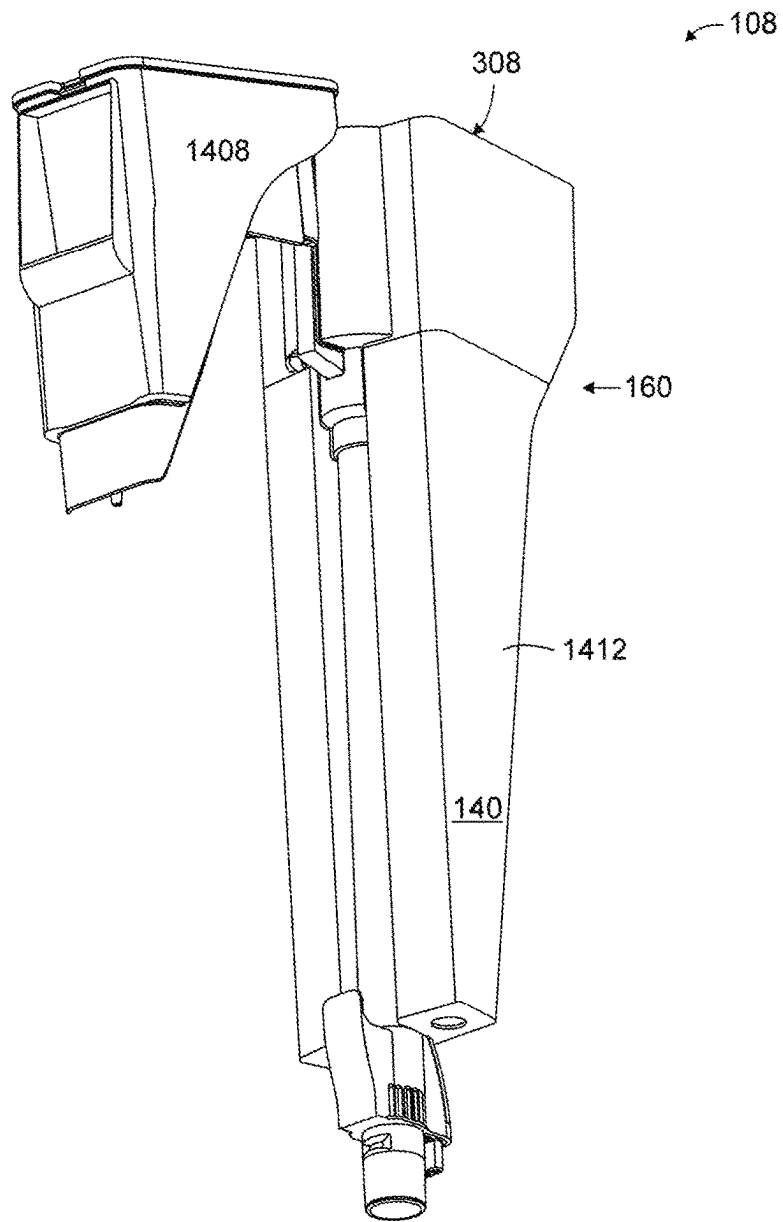


FIG. 115

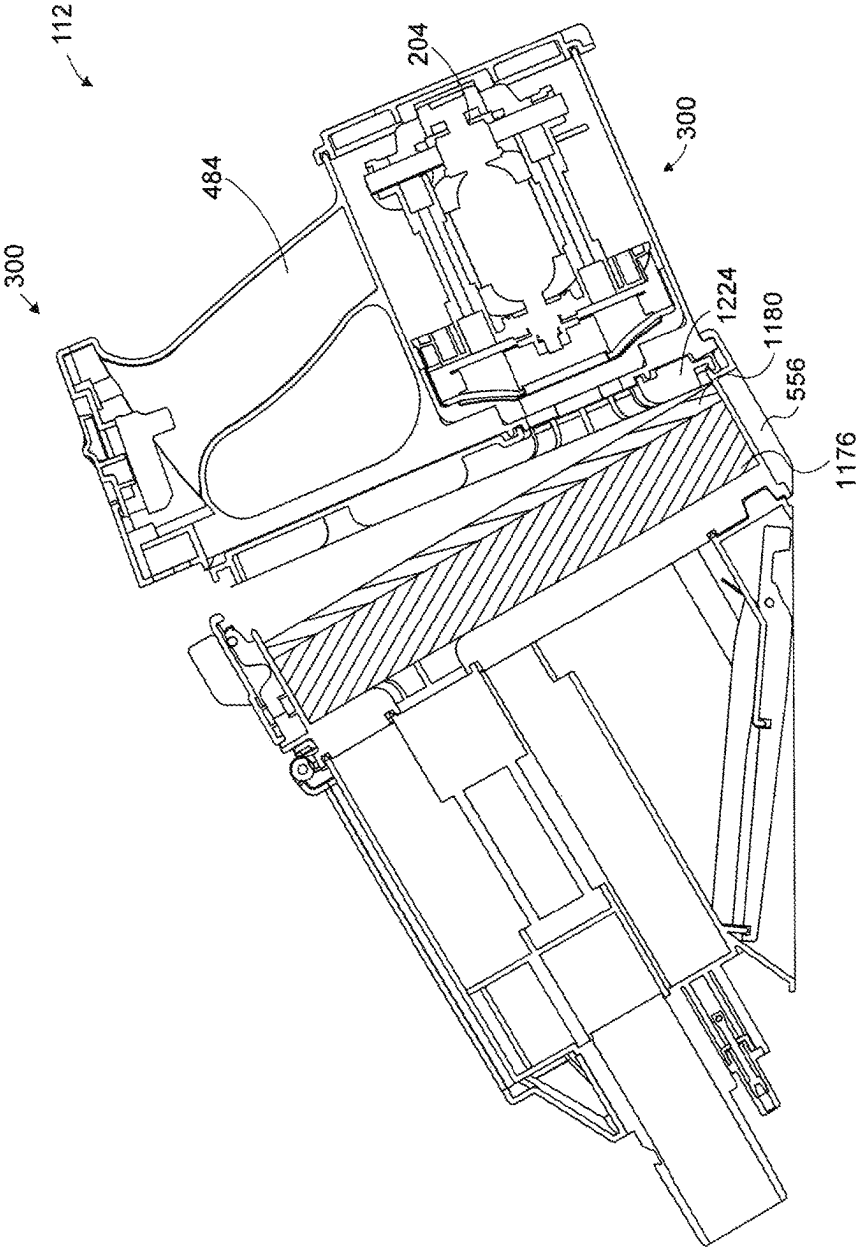
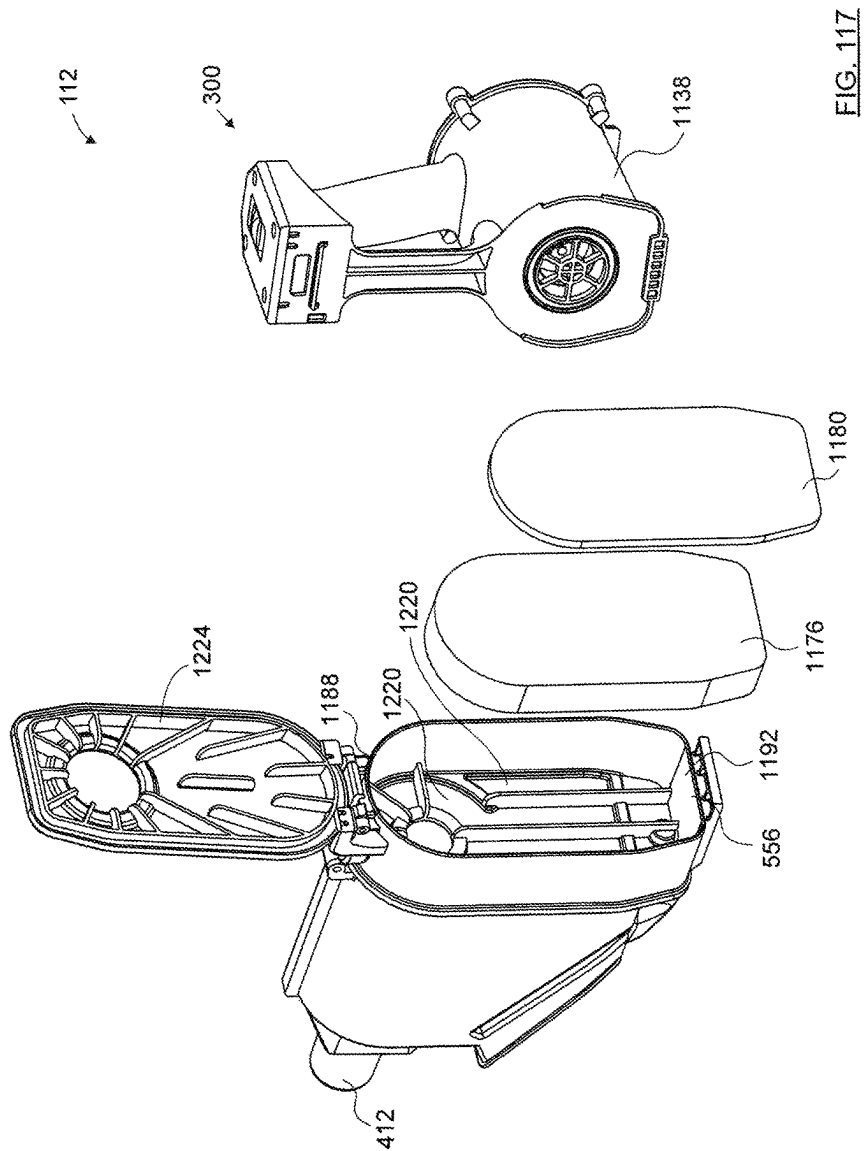


FIG. 116



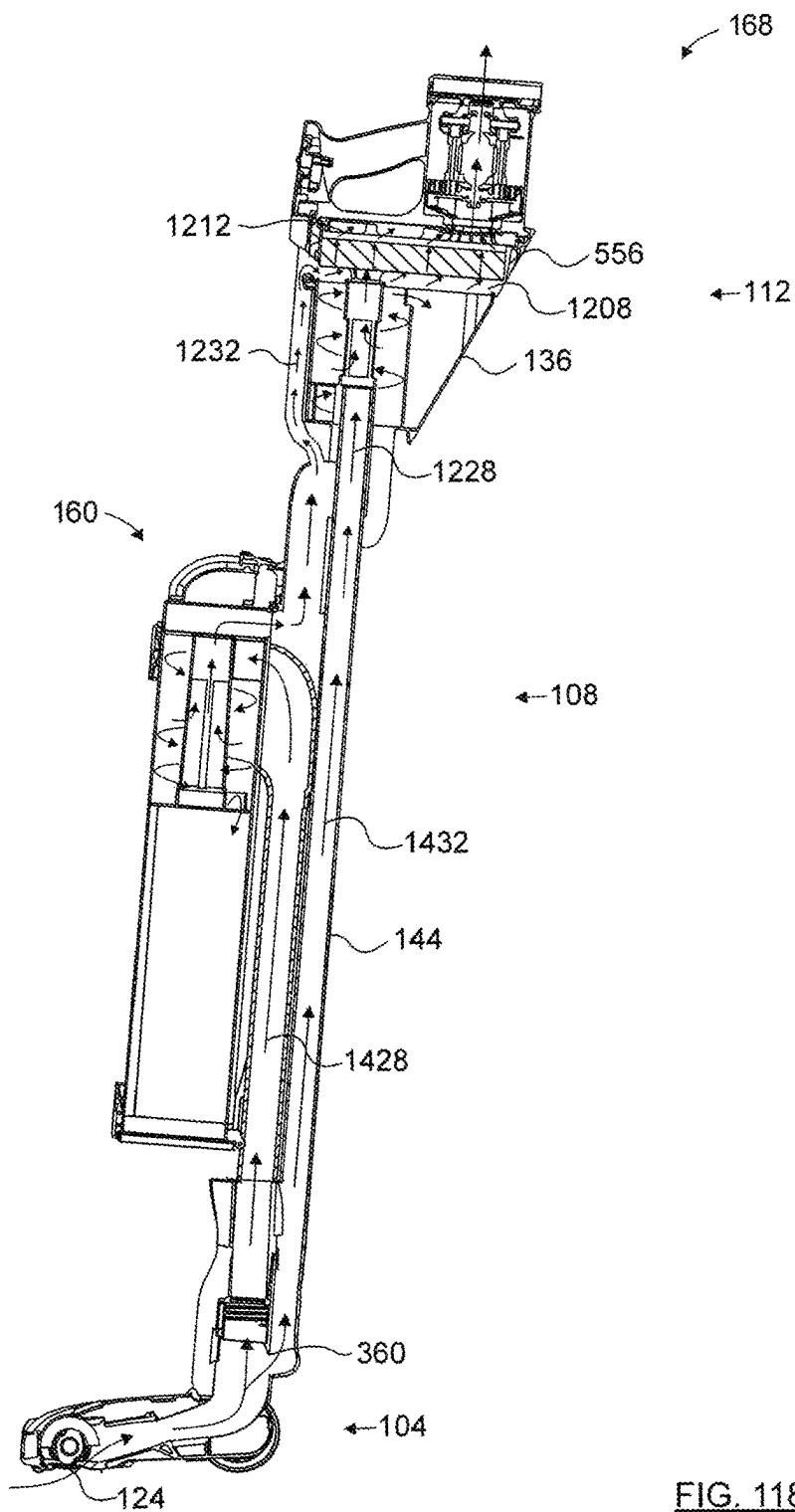


FIG. 118

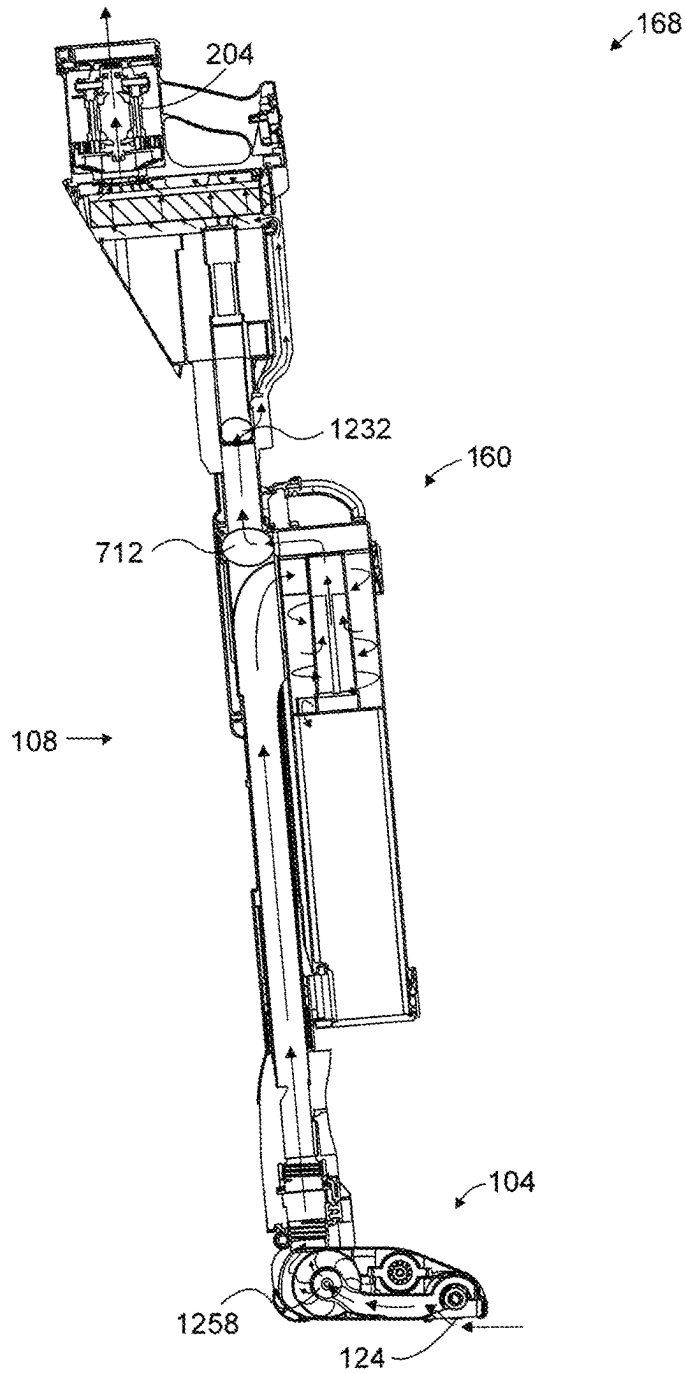


FIG. 119a

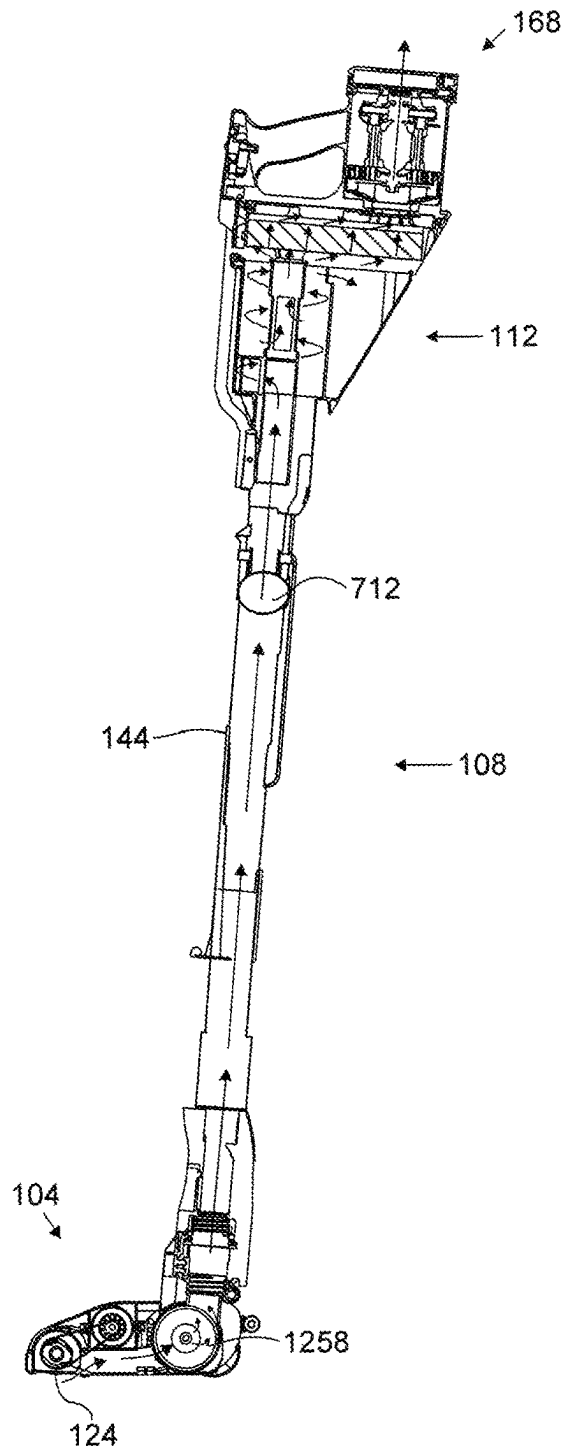


FIG. 119b

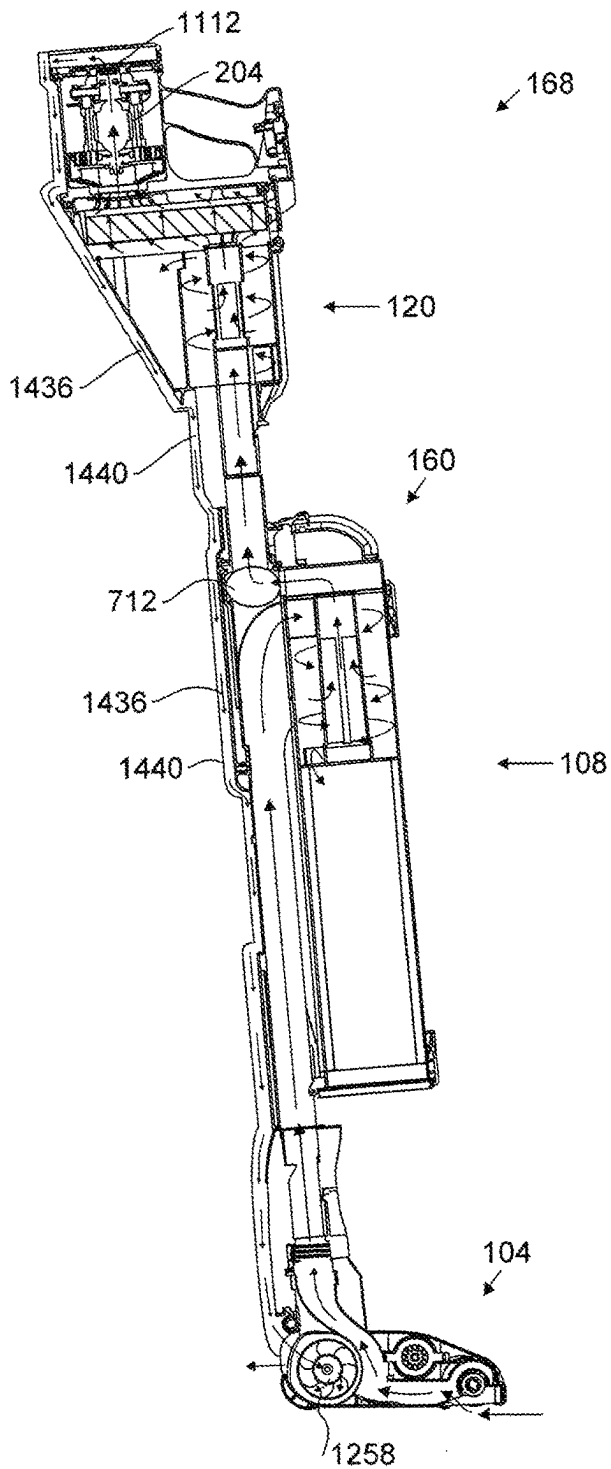


FIG. 120

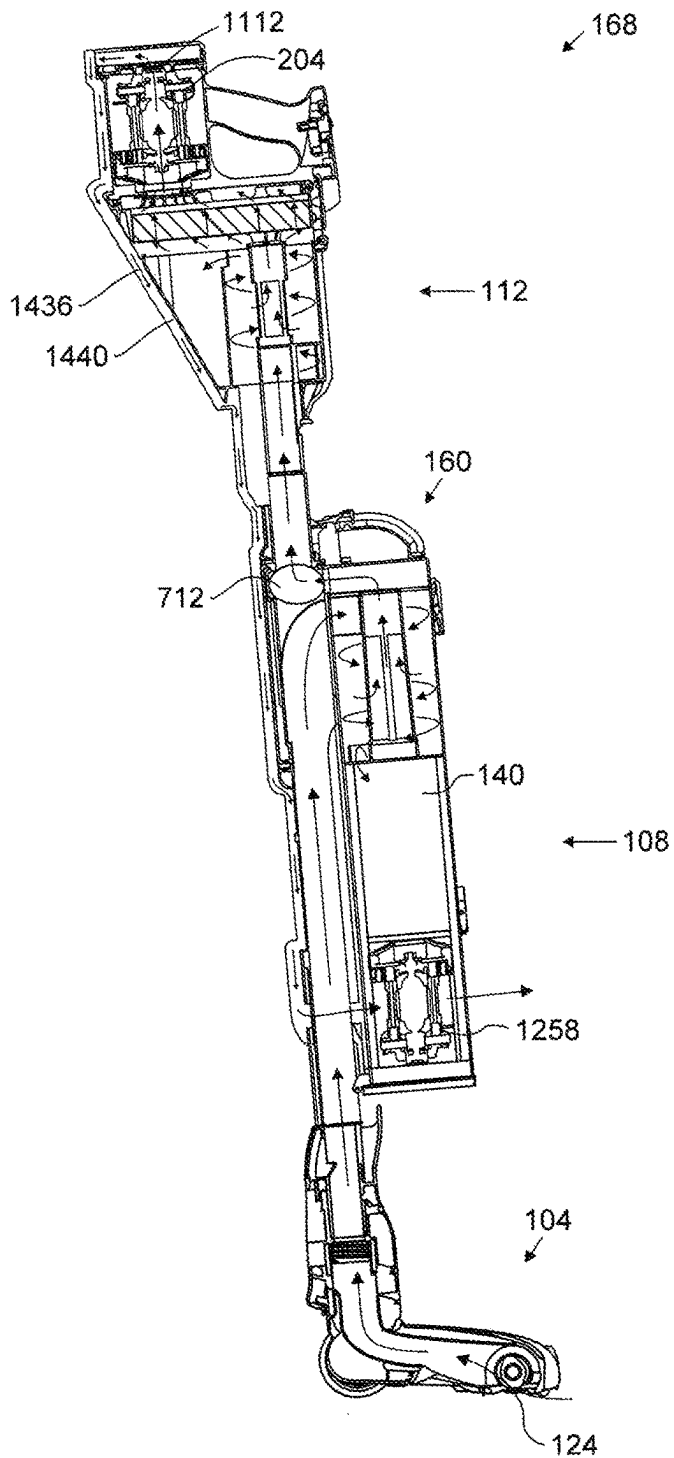


FIG. 121a

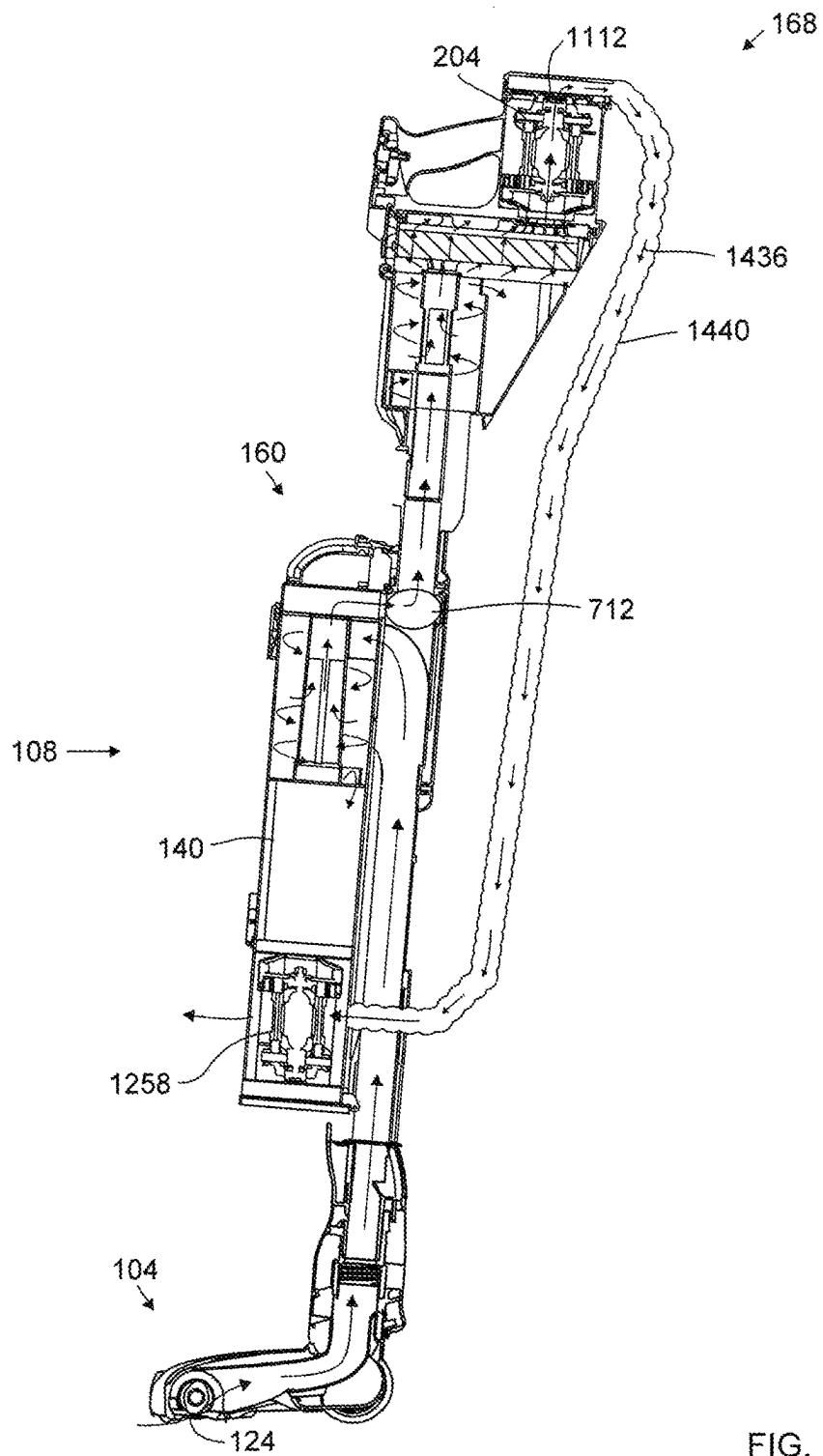


FIG. 121b

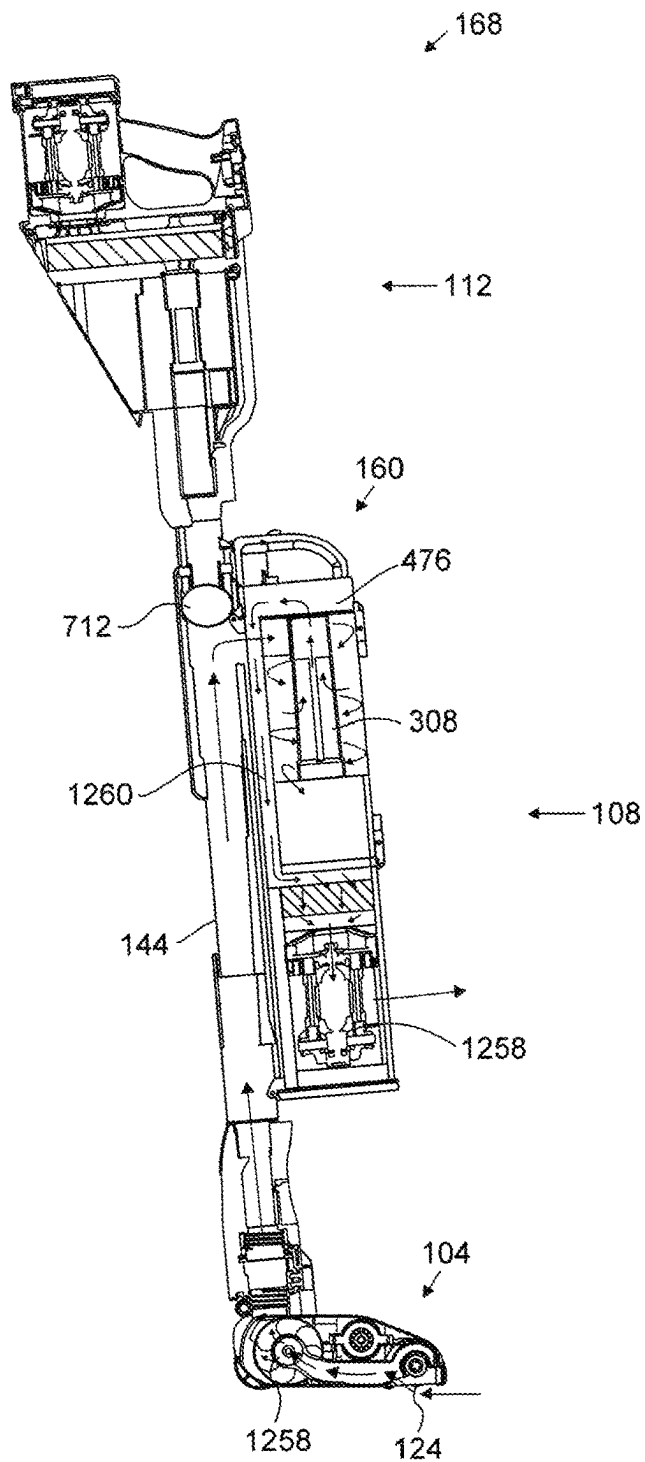


FIG. 122

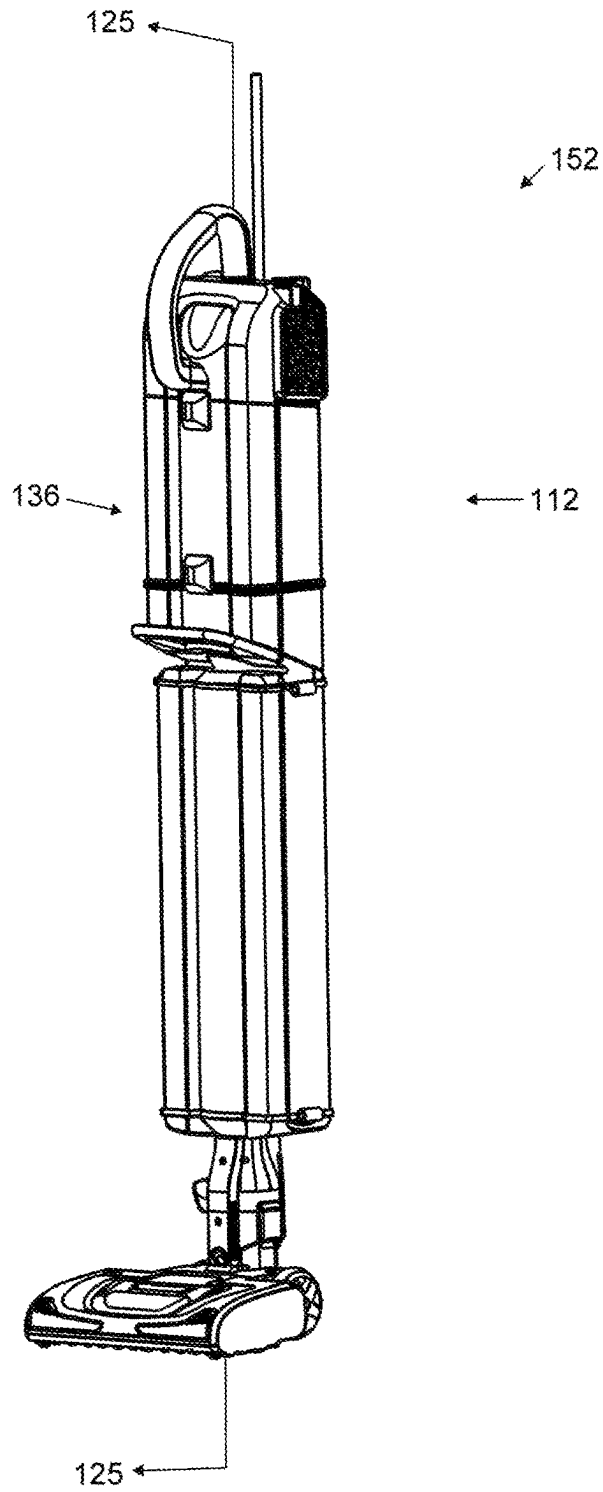


FIG. 123

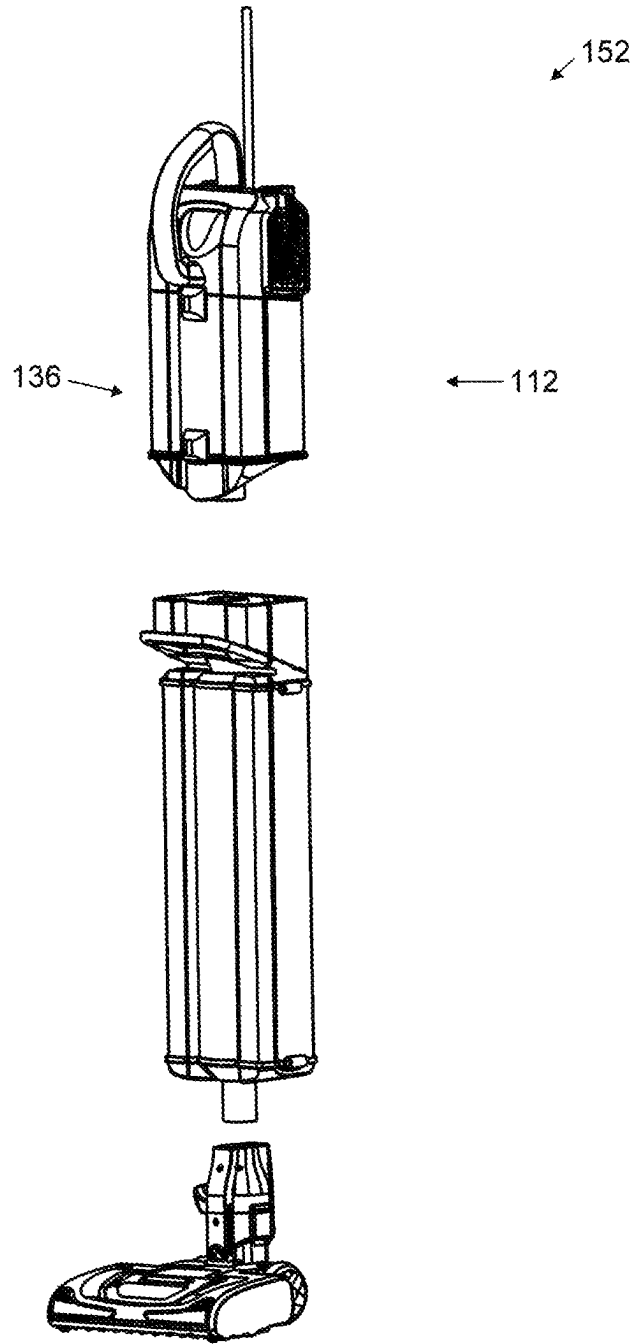


FIG. 124

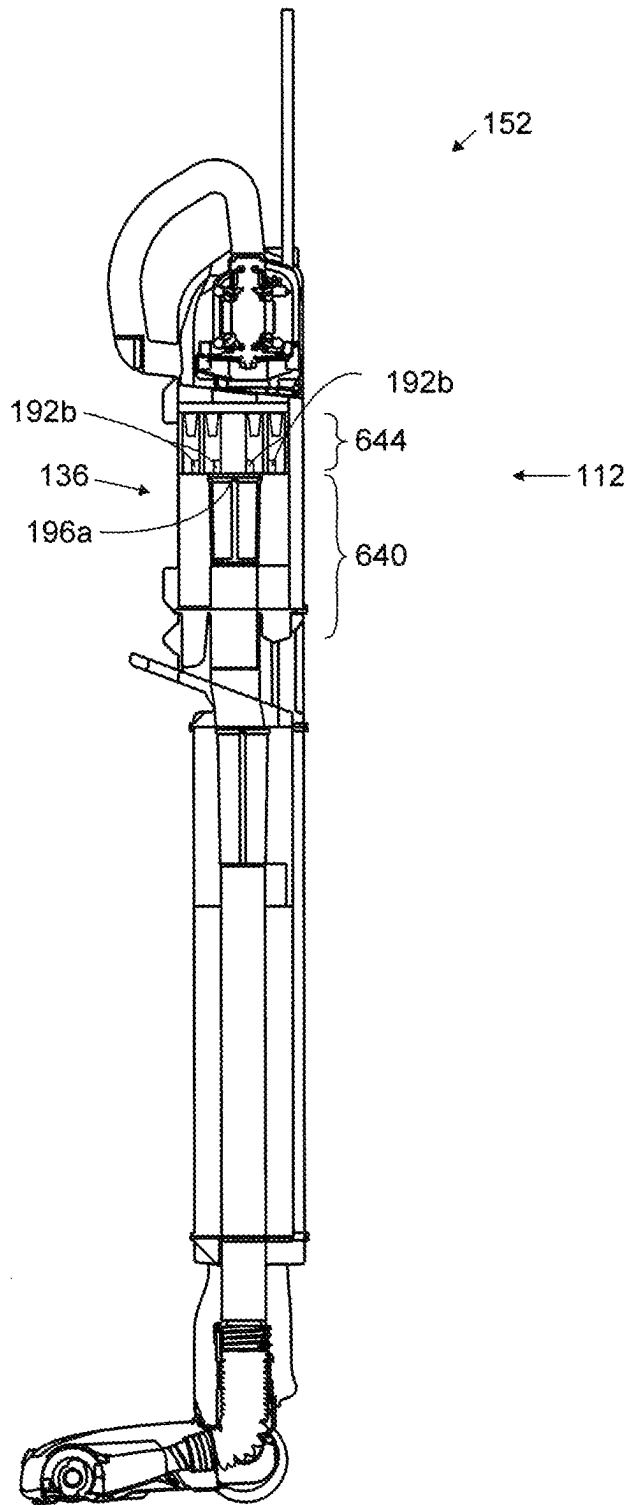


FIG. 125

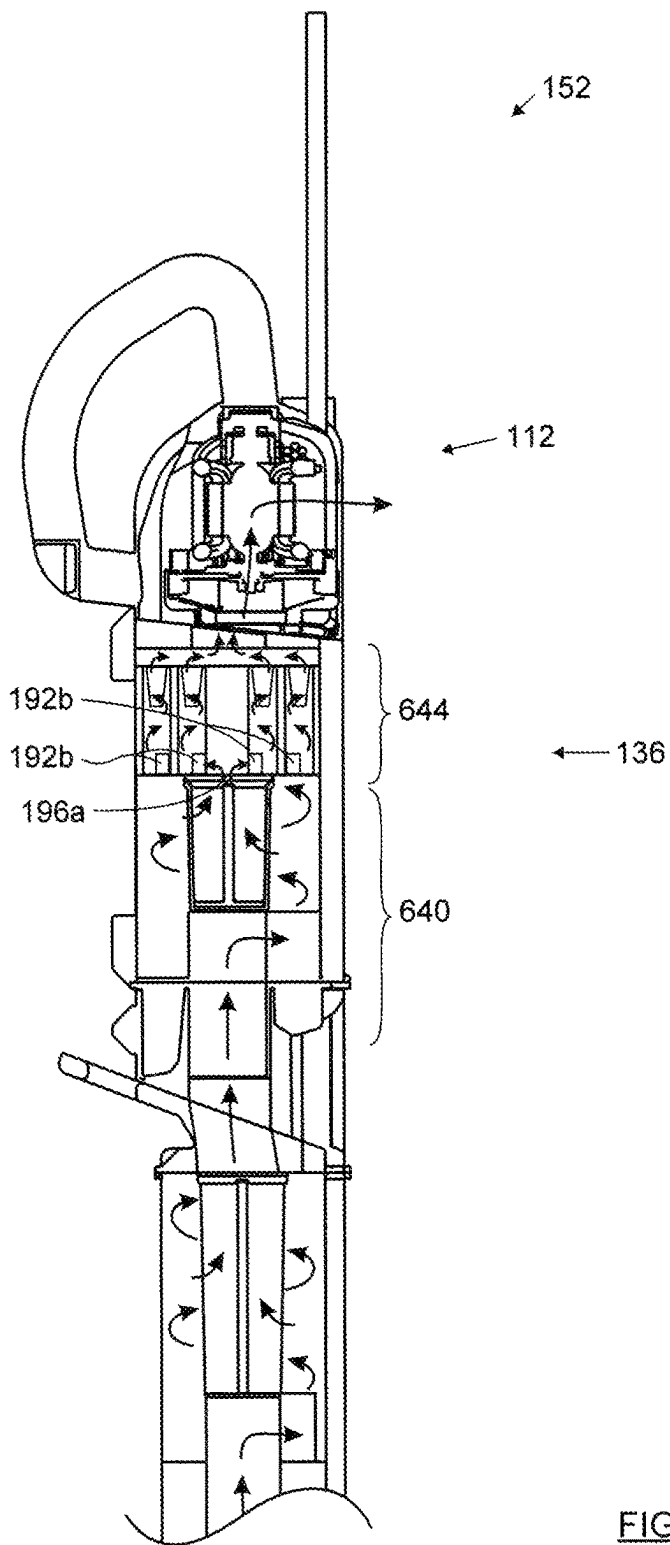


FIG. 126

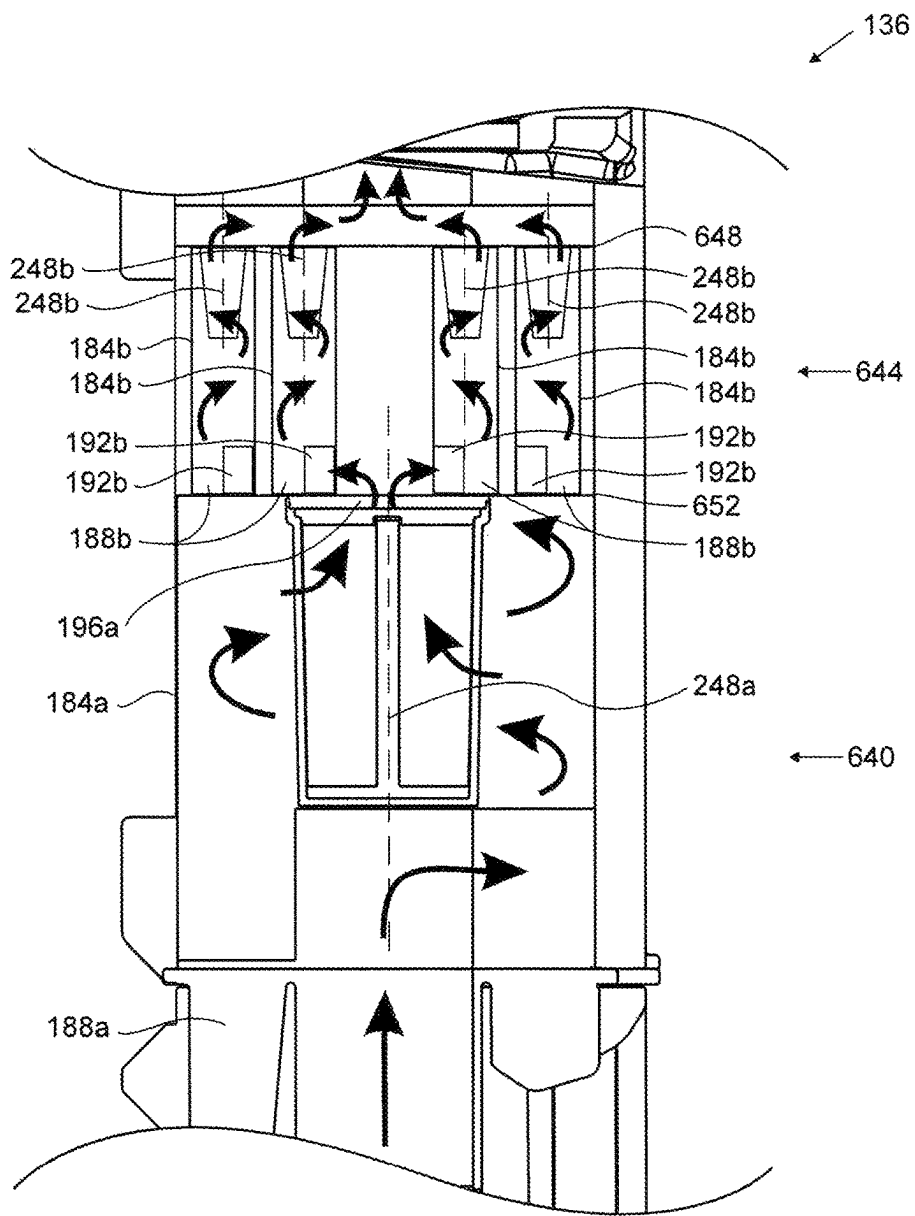


FIG. 127

1

SURFACE CLEANING APPARATUS**CROSS REFERENCE TO RELATED APPLICATIONS**

This application is a continuation of co-pending U.S. patent application Ser. No. 14/822,211, filed Aug. 10, 2015, which claimed priority from U.S. Provisional Patent Application No. 62/093,189, filed Dec. 17, 2014, the entirety of which are hereby incorporated by reference.

FIELD

This disclosure relates to the field of surface cleaning apparatus. In some aspects, this disclosure relates to a type of stick vacuum cleaner wherein a hand vacuum cleaner is removably mounted to a drive handle and provides motive power to draw dirty air into the surface cleaning head.

INTRODUCTION

Various types of surface cleaning apparatus are known. These include upright vacuum cleaner, stick vacuum cleaners, hand vacuum cleaners and canister vacuum cleaners. Stick vacuum cleaners and hand vacuum cleaners are popular as they tend to be smaller and may be used to clean a small area or when a spill has to be cleaned up. Hand vacuum cleaners or handvacs are advantageous as they are lightweight and permit above floor cleaning and cleaning in hard to reach locations. However, they have a limited dirt collection capacity. Upright vacuum cleaners enable a user to clean a floor and may have a pod that is removably attached for above floor cleaning. In such cases, the pod comprises, e.g., a cyclone, a dirt collection chamber and the suction motor for the upright vacuum cleaner. However, such the pods tend to be bulky since they comprise the total dirt collection capacity for the upright vacuum cleaner.

SUMMARY

In accordance with one aspect of this disclosure, a stick vacuum cleaner is provided which has a removable hand vacuum cleaner and also a supplemental bin which may function as a main dirt collection bin when the hand vacuum cleaner forms part of the stick vacuum cleaners. An advantage of this design is that the supplemental bin may provide enhanced dirt collection capacity for the stick vacuum cleaner. The supplemental bin may be removable so as to reduce the size of the stick vacuum cleaner when a smaller sized stick vacuum cleaner is desired, e.g., for cleaning in small or confined spaces.

In accordance with this aspect, there is provided a multimode surface cleaning apparatus comprising:

- (a) a surface cleaning head having a dirty air inlet;
- (b) an upright section moveably mounted to the surface cleaning head, the upright section moveable between a plurality of reclined floor cleaning positions;
- (c) a hand vacuum cleaner removably mounted to the upright section, the hand vacuum cleaner comprising a cyclone chamber, a dirt collection region, a suction motor and a clean air outlet; and,
- (d) an auxiliary dirt collection assembly removably mounted to the upright section

wherein, in a first upright mode of operation, the auxiliary dirt collection assembly is removed from the upright section and the hand vacuum cleaner is in airflow communication with the dirty air inlet and, in a second

2

upright mode of operation, the multimode surface cleaning apparatus is operable with the auxiliary dirt collection assembly mounted to the upright section.

In some embodiments, the auxiliary dirt collection assembly may comprise a dirt collection chamber and when the auxiliary dirt collection assembly is mounted to the upright section, dirt separated in the cyclone chamber is collectable in the dirt collection chamber of the auxiliary dirt collection assembly.

In some embodiments, when the auxiliary dirt collection assembly may be mounted to the upright section, the dirt collection chamber of the auxiliary dirt collection assembly is selectively connectable in communication with the dirt collection region of the hand vacuum cleaner.

In some embodiments, in the second upright mode of operation, the dirt collection region of the hand vacuum cleaner may be positioned above the dirt collection chamber of the auxiliary dirt collection assembly.

In some embodiments, the cyclone chamber may have a dirt outlet and the dirt collection region comprises a dirt collection chamber of the hand vacuum cleaner.

In some embodiments, the dirt collection chamber may have a manually openenable dumping door and the dirt collection chamber of the auxiliary dirt collection assembly may be in communication with the dirt collection chamber of the hand vacuum cleaner when the dumping door is opened.

In some embodiments, when the auxiliary dirt collection assembly is mounted to the upright section, the dirt collection chamber of the auxiliary dirt collection assembly may be automatically connected in communication with a dirt outlet of the cyclone chamber.

In some embodiments, in the second upright mode of operation, the dirt collection region of the hand vacuum cleaner may be positioned above the dirt collection chamber of the auxiliary dirt collection assembly.

In some embodiments, the dirt collection region of the hand vacuum cleaner may be in communication with the dirt outlet of the cyclone chamber and the dirt collection region may have a dumping door that is automatically opened when the auxiliary dirt collection assembly is mounted to the upright section and the dirt collection chamber of the auxiliary dirt collection assembly is in communication with the dirt collection region of the hand vacuum cleaner when the dumping door is opened.

In some embodiments, the auxiliary dirt collection assembly may comprise a cyclone chamber and a dirt collection region.

In some embodiments, in the second upright mode of operation, the cyclone chamber of the auxiliary dirt collection assembly may be connected in series with the cyclone chamber of the hand vacuum cleaner.

In some embodiments, in the second upright mode of operation, the cyclone chamber of the auxiliary dirt collection assembly may be connected in parallel with the cyclone chamber of the hand vacuum cleaner.

In some embodiments, in the second upright mode of operation, the cyclone chamber of the hand vacuum cleaner may be bypassed and air exiting the cyclone chamber of the auxiliary dirt collection assembly passes through a pre-motor filter of the hand vacuum cleaner, the suction motor and exits via the clean air outlet of the hand vacuum cleaner.

In some embodiments, the auxiliary dirt collection assembly may further comprise a pre-motor filter.

In some embodiments, in the second upright mode of operation, the cyclone chamber of the auxiliary dirt collec-

3

tion assembly may be connected in parallel with the cyclone chamber of the hand vacuum cleaner.

In some embodiments, in the second upright mode of operation, the cyclone chamber of the hand vacuum cleaner and a pre-motor filter of the hand vacuum cleaner may be bypassed and air exiting the cyclone chamber of the auxiliary dirt collection assembly may pass through the pre-motor filter of the auxiliary dirt collection assembly, the suction motor and exits via the clean air outlet of the hand vacuum cleaner.

In some embodiments, the auxiliary dirt collection assembly may further comprise an auxiliary dirt collection assembly suction motor.

In some embodiments, in the second upright mode of operation, at least a portion of air entering the dirty air inlet may bypass the hand vacuum cleaner and exit via an alternate clean air outlet.

In some embodiments, the alternate clean air outlet may be provided on the auxiliary dirt collection assembly.

In some embodiments, the hand vacuum cleaner may have a handle and, when the multimode surface cleaning apparatus is in the first and second upright modes of operation, the handle may be a drive handle of the multimode surface cleaning apparatus.

In some embodiments, the upright section may comprise an up flow duct and the auxiliary dirt collection assembly may be removably mounted to the up flow duct.

In some embodiments, the up flow duct may comprise a rigid extension cleaning wand and the rigid extension cleaning wand may be removable from one of the upright section and the surface cleaning head and, in a first above floor mode of operation, an above floor cleaning, unit may comprise the hand vacuum cleaner and the rigid extension cleaning wand.

In some embodiments, the up flow duct may comprise a rigid tube, the hand vacuum cleaner may have a handle and, the hand vacuum cleaner may have an air inlet that is drivably engageable with the rigid tube whereby, when the multimode surface cleaning apparatus is in the first and second upright modes of operation, the handle may be a drive handle of the multimode surface cleaning apparatus.

In some embodiments, the auxiliary dirt collection assembly may have a longitudinal axis that is generally parallel to the up flow duct.

In some embodiments, the auxiliary dirt collection assembly may comprise a cyclone chamber having a longitudinal axis that is generally parallel to the up flow duct.

In some embodiments, the hand vacuum cleaner may be provided on a rear portion of the upright section and the auxiliary dirt collection assembly may be provided on a front portion of the upright section.

In some embodiments, the upright section may comprise an up flow duct and the auxiliary dirt collection assembly may be removably mounted to a front side of the up flow duct and a portion of the hand vacuum cleaner may be positioned rearward of the up flow duct.

In some embodiments, the suction motor may be positioned rearward of the up flow duct.

In some embodiments, the upright section may comprise a lower portion and an upper portion and the upper section may be moveable forwardly relative to the lower section and the auxiliary dirt collection assembly may be removably mounted to the lower section.

In some embodiments, the upright section may comprise an up flow duct having a lower portion and an upper portion and the upper section may be moveable forwardly relative to the lower section and the auxiliary dirt collection assembly may be removably mounted to the lower section.

4

In some embodiments, the up flow duct may comprise a rigid tube, the hand vacuum cleaner may have a handle and, the hand vacuum cleaner may have an air inlet that is drivably engageable with the rigid tube whereby, when the multimode surface cleaning apparatus is in the first and second upright modes of operation, the handle may be a drive handle of the multimode surface cleaning apparatus.

DRAWINGS

FIG. 1 is a front perspective view of a surface cleaning apparatus in accordance with at least one embodiment;

FIG. 2 is a rear perspective view of the apparatus of FIG. 1;

FIG. 3 is a side elevation view of the apparatus of FIG. 1;

FIG. 4 is a front perspective view of the apparatus of FIG. 1 with a supplemental dirt collection chamber partially removed;

FIG. 5 is a front perspective view of a surface cleaning apparatus in accordance with another embodiment;

FIG. 6 is a rear perspective view of the apparatus of FIG. 5;

FIG. 7 is a side elevation view of the apparatus of FIG. 5 with an electrical cord bag;

FIG. 8 is a front elevation view of the apparatus of FIG. 5;

FIG. 9 is a rear elevation view of the apparatus of FIG. 5;

FIG. 10 is a top plan view of the apparatus of FIG. 5;

FIG. 11 is a bottom plan view of the apparatus of FIG. 5;

FIG. 12 is an exploded front perspective view of the apparatus of FIG. 5;

FIG. 12a is an exploded front perspective view of an alternate apparatus of FIG. 5;

FIG. 13 is a front perspective view of a surface cleaning apparatus in accordance with another embodiment;

FIG. 14 is a rear perspective view of the apparatus of FIG. 13;

FIG. 15 is a side elevation view of the apparatus of FIG. 13;

FIG. 16 is a front elevation view of the apparatus of FIG. 13;

FIG. 17 is a rear elevation view of the apparatus of FIG. 13;

FIG. 18 is a top plan view of the apparatus of FIG. 13;

FIG. 19 is a bottom plan view of the apparatus of FIG. 13;

FIG. 20 is a front perspective view of the apparatus of FIG. 13 with a supplemental cyclone bin assembly partially removed;

FIG. 21 is a cross-sectional view taken along line 21-21 in FIG. 1;

FIG. 22 is a bottom perspective view of a handvac of the apparatus of FIG. 1;

FIG. 23 is a perspective cross-sectional view of a cyclone bin assembly of the handvac of FIG. 22 transverse to the cyclone axis;

FIG. 23a is a top plan view of the cross-section of FIG. 23;

FIG. 24 is a front perspective view of the supplemental dirt collection chamber of the apparatus of FIG. 1;

FIG. 25 is a cross-sectional view taken along line 25-25 in FIG. 5;

FIG. 26 is a cross-sectional view taken along line 26-26 in FIG. 13;

FIG. 27 is a front perspective view of the apparatus of FIG. 1 in a lightweight upright mode;

FIG. 28 is a rear perspective view of the apparatus of FIG. 1 in the lightweight upright mode of FIG. 27;

FIG. 29 is a side elevation view of the apparatus of FIG. 1 in the lightweight upright mode of FIG. 27;

FIG. 30 is a cross-sectional view taken along line 30-30 in FIG. 27;

FIG. 31 is a front perspective view of the apparatus of FIG. 1 in an above-floor cleaning mode;

FIG. 32 is a rear perspective view of the apparatus of FIG. 1 in the above-floor cleaning mode of FIG. 31;

FIG. 33 is a side elevation view of the apparatus of FIG. 1 in the above-floor cleaning mode of FIG. 31;

FIG. 34 is a front perspective view of the apparatus of FIG. 1 in a stair-cleaning mode;

FIG. 35 is a rear perspective view of the apparatus of FIG. 1 in the stair-cleaning mode of FIG. 34;

FIG. 36 is a side elevation view of the apparatus of FIG. 1 in the stair cleaning mode of FIG. 34;

FIG. 36a is a front perspective view of the apparatus of FIG. 5 in an above-floor cleaning mode;

FIG. 37 is a front perspective view of the apparatus of FIG. 13 in a lightweight upright mode;

FIG. 38 is a rear perspective view of the apparatus of FIG. 13 in the lightweight upright mode of FIG. 37;

FIG. 39 is a front elevation view of the apparatus of FIG. 13 in the lightweight upright mode of FIG. 37;

FIG. 40 is a rear elevation view of the apparatus of FIG. 13 in the lightweight upright mode of FIG. 37;

FIG. 41 is a side elevation view of the apparatus of FIG. 13 in the lightweight upright mode of FIG. 37;

FIG. 42 is a top plan view of the apparatus of FIG. 13 in the lightweight upright mode of FIG. 37;

FIG. 43 is a bottom plan view of the apparatus of FIG. 13 in the lightweight upright mode of FIG. 37;

FIG. 44 is a cross-sectional view taken along line 44-44 in FIG. 37;

FIG. 44a is a perspective view of the apparatus of FIG. 13 in an above-floor cleaning mode;

FIG. 44b is another perspective view of the apparatus of FIG. 13 in the above-floor cleaning mode of FIG. 44a;

FIG. 45 is a rear perspective view of the supplemental dirt collection chamber of FIG. 24;

FIG. 46 is a side elevation view of the supplemental dirt collection chamber of FIG. 24;

FIG. 47 is a front perspective view of a surface cleaning apparatus in accordance with another embodiment;

FIG. 48 is a cross-sectional view taken along line 48-48 in FIG. 47;

FIG. 49 is a cross-section view taken along line 49-49 in FIG. 47;

FIG. 50 is a side elevation view of the apparatus of FIG. 47;

FIG. 51 is a front elevation view of the apparatus of FIG. 47;

FIG. 52 is a front perspective view of an upright section of the apparatus of FIG. 13 including a diversion valve in a closed position;

FIG. 53 is a front perspective view of the upright section of FIG. 52 with a cyclone bin assembly seated on a pedal of the diversion valve;

FIG. 54 is a front perspective view of the upright section of FIG. 52 with the cyclone bin assembly connected to a wand, and the diversion valve in the open position;

FIG. 55 is a cross-sectional view taken along line 55-55 in FIG. 52;

FIG. 56 is a cross-sectional view taken along line 56-56 in FIG. 53;

FIG. 57 is a cross-sectional view taken along line 57-57 in FIG. 54;

FIG. 58 is a front perspective view of an upright section of the apparatus of FIG. 13 including another diversion valve in a closed position

FIG. 59 is a front perspective view of the upright section of FIG. 58 with the cyclone bin assembly being connected to a wand, and the diversion valve in the closed position;

FIG. 60 is a front perspective view of the upright section of FIG. 58 with the cyclone bin assembly connected to the wand, and the diversion valve in the open position

FIG. 61 is a cross-sectional view taken along line 61-61 in FIG. 58;

FIG. 62 is a cross-sectional view taken along line 62-62 in FIG. 59;

FIG. 63 is a cross-sectional view taken along line 63-63 in FIG. 60;

FIG. 64 is a front perspective view of an upright section of the apparatus of FIG. 13 including another diversion valve in a closed position;

FIG. 65 is a front perspective view of the upright section of FIG. 64 with the diversion valve in a partially opened position;

FIG. 66 is a front perspective view of the upright section of FIG. 64 mounted to the wand with the diversion valve in an open position;

FIG. 67 is a cross-sectional view of the upright section of FIG. 64;

FIG. 68 is another cross-sectional view of the upright section of FIG. 64;

FIG. 69 is an enlarged view of a portion of FIG. 68;

FIG. 70 is a cross-sectional view taken along line 70-70 in FIG. 65;

FIG. 71 is a cross-sectional view taken along line 71-71 in FIG. 66;

FIG. 72 is a front perspective view of an upright section of the apparatus of FIG. 13 with another diversion valve in a closed position;

FIG. 73 is a front perspective view of the upright section of FIG. 72 being connected to the wand and with the diversion valve in a closed position;

FIG. 74 is a front perspective view of the upright section of FIG. 72 connected to the wand and with the diversion valve in an open position;

FIG. 75 is a cross-section view taken along line 75-75 in FIG. 72;

FIG. 76 is a cross-section view taken along line 76-76 in FIG. 73;

FIG. 77 is a cross-section view taken along line 77-77 in FIG. 74;

FIG. 78 is a side elevation view of the handvac of the apparatus of FIG. 1;

FIG. 79 is a side elevation view of the handvac of the apparatus of FIG. 5;

FIG. 80 is a side elevation view of the apparatus of FIG. 5 in an upright storage position with a surface cleaning head having rearwardly deployed wheels;

FIG. 81 is a side elevation view of the apparatus of FIG. 80 in a reclined in-use position with the rear wheels of the surface cleaning head retracted;

FIG. 82 is a front perspective view of the apparatus of FIG. 13 with a cyclone bin assembly in accordance with at least one embodiment;

FIG. 83 is a rear perspective view of the cyclone bin assembly of FIG. 82 in a closed position;

FIG. 84 is a side elevation view of the cyclone bin assembly of FIG. 82 in a closed position;

FIG. 85 is a front elevation view of the cyclone bin assembly of FIG. 82 in a closed position;

FIG. 86 is a front elevation view of the cyclone bin assembly of FIG. 82 with a cyclone chamber portion in an open position;

FIG. 87 is a front elevation view of the cyclone bin assembly of FIG. 82 with the cyclone chamber portion and a dirt collection portion in open positions;

FIG. 88 is a top perspective view of the cyclone bin assembly of FIG. 82 with the cyclone chamber portion and the dirt collection portion in open positions;

FIG. 89 is a front perspective view of the cyclone bin assembly of the apparatus of FIG. 13;

FIG. 90 is a rear perspective view of the cyclone bin assembly of FIG. 89;

FIG. 91 is a front elevation view of the cyclone bin assembly of FIG. 89;

FIG. 92 is a rear elevation view of the cyclone bin assembly of FIG. 89;

FIG. 93 is a side elevation view of the cyclone bin assembly of FIG. 89;

FIG. 94 is a top plan view of the cyclone bin assembly of FIG. 89;

FIG. 95 is a bottom plan view of the cyclone bin assembly of FIG. 89;

FIG. 95*b* is a front perspective view of the cyclone bin assembly of FIG. 89 with a bottom portion in an open position;

FIG. 95*c* is a front perspective view of the cyclone bin assembly of FIG. 89 with top and bottom portions in open positions;

FIG. 96 is a cross-sectional view taken along line 96-96 in FIG. 22;

FIG. 97*a* is a bottom perspective view of the handvac of the apparatus of FIG. 1;

FIG. 97*b* is a partial cross-sectional view taken along line 97*b*-97*b* of FIG. 97*a*;

FIG. 98*a* is a bottom perspective view of the handvac of the apparatus of FIG. 1 with an open door;

FIG. 98*b* a partial cross-sectional view taken along line 98*b*-98*b* of FIG. 98*a*;

FIG. 99 is a partial cross-sectional view of a surface cleaning apparatus having a handvac disconnected from the upright section, and a bypass valve in a first closed position;

FIG. 100 is a cross-sectional view of the surface cleaning apparatus of FIG. 99 having a handvac connected to the upright section and the bypass valve in the first closed position;

FIG. 101 is a cross-sectional view of the surface cleaning apparatus of FIG. 99 having the handvac connected to the upright section and a supplementary cyclone bin assembly, and the bypass valve in a second open position;

FIG. 102 is a cross-sectional view of a surface cleaning apparatus having a having a bypass airflow path and a pre-motor filter in a supplemental cyclone bin assembly;

FIG. 103 is a cross-sectional view of a surface cleaning apparatus having a clean air suction motor in a surface cleaning head;

FIG. 104*a* is a cross-sectional view of a surface cleaning apparatus having a having a clean air suction motor in a supplemental cyclone bin assembly;

FIG. 104*b* is a cross-sectional view of another surface cleaning apparatus having a clean air suction motor in a supplemental cyclone bin assembly;

FIG. 105*a* is a perspective view of a surface cleaning apparatus having a supplemental cyclone bin assembly disconnected from an upright section;

FIG. 105*b* is a perspective view of a surface cleaning apparatus having a cyclone chamber and dirt collection chamber disconnected from an upright section;

FIG. 106 is a side elevation view a surface cleaning apparatus in accordance with another embodiment;

FIG. 107 is a partial side elevation view of the apparatus of FIG. 106 with a handvac disconnected from an upright section;

FIG. 108 is a side elevation view of the apparatus of FIG. 106 in a reclined in-use position with an arm assembly in a first position;

FIG. 109 is a side elevation view of the apparatus of FIG. 106 in a steeply reclined in-use position with the arm assembly in a second position;

FIG. 110*a* is a rear perspective view of the handvac of the apparatus of FIG. 1 in an open position;

FIG. 110*b* is a front perspective view of the handvac of FIG. 110*a* in the open position;

FIG. 111 is a front perspective view of the dirt collection chamber of the apparatus of FIG. 1 in an open position;

FIG. 112 is a rear perspective view of the dirt collection chamber of FIG. 111 in the open position;

FIG. 113 is a side elevation view of the dirt collection chamber of FIG. 111 in the open position;

FIG. 114 is a front perspective view of the upright section of the apparatus of FIG. 5 with a cyclone bin assembly in a closed position;

FIG. 115 is a front perspective view of the upright section of FIG. 114 with the cyclone bin assembly in an open position;

FIG. 116 is a cross-sectional view of the handvac of the apparatus of FIG. 1 having a pre-motor filter chamber in an open position;

FIG. 117 is a exploded view of the handvac of FIG. 116;

FIG. 118 is a cross-sectional view of a surface cleaning apparatus having a plurality of cyclone chambers in parallel;

FIG. 119*a* is a cross-sectional view of a surface cleaning apparatus having a dirty air suction motor in a surface cleaning head in series with a clean air suction motor in a handvac;

FIG. 119*b* is a cross-sectional view of the surface cleaning apparatus of FIG. 119*a* with a supplemental cyclone bin assembly removed;

FIG. 120 is a cross-sectional view of a surface cleaning apparatus having a clean air suction motor in a surface cleaning head in series with a clean air suction motor in a handvac;

FIG. 121*a* is a cross-sectional view of a surface cleaning apparatus having a clean air suction motor in a supplemental cyclone bin assembly in series with a clean air suction motor in a handvac;

FIG. 121*b* is a cross-sectional view of the surface cleaning apparatus of FIG. 121*a* with a hose connecting the handvac suction motor and the suction motor of the supplemental cyclone bin assembly;

FIG. 122 is a cross-sectional view of a surface cleaning apparatus having an airflow which bypasses the handvac;

FIG. 123 is a perspective view of a surface cleaning apparatus in accordance with another embodiment;

FIG. 124 is an exploded perspective view of the surface cleaning apparatus of FIG. 123;

FIG. 125 is a cross-sectional view taken along line 125-125 in FIG. 123;

FIG. 126 is enlarged partial view of FIG. 125; and
FIG. 127 is an enlarged partial view of FIG. 126.

DESCRIPTION OF VARIOUS EMBODIMENTS

Numerous embodiments are described in this application, and are presented for illustrative purposes only. The described embodiments are not intended to be limiting in any sense. The invention is widely applicable to numerous embodiments, as is readily apparent from the disclosure herein. Those skilled in the art will recognize that the present invention may be practiced with modification and alteration without departing from the teachings disclosed herein. Although particular features of the present invention may be described with reference to one or more particular embodiments or figures, it should be understood that such features are not limited to usage in the one or more particular embodiments or figures with reference to which they are described.

The terms “an embodiment,” “embodiment,” “embodiments,” “the embodiment,” “the embodiments,” “one or more embodiments,” “some embodiments,” and “one embodiment” mean “one or more (but not all) embodiments of the present invention(s),” unless expressly specified otherwise.

The terms “including,” “comprising” and variations thereof mean “including but not limited to,” unless expressly specified otherwise. A listing of items does not imply that any or all of the items are mutually exclusive, unless expressly specified otherwise. The terms “a,” “an” and “the” mean “one or more,” unless expressly specified otherwise.

As used herein and in the claims, two or more parts are said to be “coupled”, “connected”, “attached”, or “fastened” where the parts are joined or operate together either directly or indirectly (i.e., through one or more intermediate parts), so long as a link occurs. As used herein and in the claims, two or more parts are said to be “directly coupled”, “directly connected”, “directly attached”, or “directly fastened” where the parts are connected directly in physical contact with each other. As used herein, two or more parts are said to be “rigidly coupled”, “rigidly connected”, “rigidly attached”, or “rigidly fastened” where the parts are coupled so as to move as one while maintaining a constant orientation relative to each other. None of the terms “coupled”, “connected”, “attached”, and “fastened” distinguish the manner in which two or more parts are joined together.

General Overview

Referring to FIGS. 1-3, a surface cleaning apparatus 100 is shown in accordance with a first embodiment. In the embodiment shown, the surface cleaning apparatus 100 is a type of upright vacuum cleaner which is referred to as a stick vacuum cleaner. As illustrated, surface cleaning apparatus 100 includes a surface cleaning head 104, an upright section 108, and a hand-carriable vacuum cleaner 112 (also referred to as handvac or hand vacuum cleaner 112).

Upright section 108 may be movably and drivingly connected to surface cleaning head 104. For example, upright section 108 may be permanently or removably connected to surface cleaning head 104 and moveably mounted thereto for movement from a storage position to an in use position, such as by a pivotable joint 116. Joint 116 may permit upright section 108 to pivot (i.e. rotate) with respect to surface cleaning head 104 about a horizontal axis. Accordingly, upright section 108 may be rotatable rearwardly so as

to be positionable in a plurality of reclined floor cleaning positions (see for example FIGS. 81 and 108).

Upright section 108 may also be steeringly connected to surface cleaning head 104 for maneuvering surface cleaning head 104. For example, joint 116 may be a swivel joint.

Handvac 112 may be removably connected to upright section 108. When mounted to upright section 108, a user may grasp handvac 112 to manipulate upright section 108 to steer surface cleaning head 104 across a surface to be cleaned. Accordingly, when handvac 112 is mounted to upright section 108, handle 484 is the drive handle of surface cleaning apparatus 100.

Surface cleaning apparatus 100 has at least one dirty air inlet, one clean air outlet, and an airflow path extending between the inlet and the outlet. In the illustrated example, lower end 120 of surface cleaning head 104 includes a dirty air inlet 124, and a rear end 128 of handvac 112 includes a clean air outlet 132. An airflow path extends from dirty air inlet 124 through surface cleaning head 104, upright section 108, and handvac 112 to clean air outlet 132.

As exemplified, at least one suction motor, and preferably the only suction motor, and one air treatment member, which may be the only air treatment member, is provided in the handvac 112 to permit handvac 112 to operate independently when disconnected from surface cleaning head 104 and optionally from upright section 108. It will be appreciated that while at least one suction motor and at least one air treatment member are positioned in the airflow path to separate dirt and other debris from the airflow, that when used with other aspects disclosed herein, each of the suction motor and the air treatment member may be provided in the surface cleaning head 104, the upright section 108, and/or the handvac 112.

The air treatment member may be any suitable air treatment member, including, for example, one or more cyclones, filters, and bags. Preferably, at least one air treatment member is provided upstream of the suction motor to clean the dirty air before the air passes through the suction motor. In the illustrated embodiment, handvac 112 includes a cyclone bin assembly 136 including a cyclone chamber and a dirt collection region. In some embodiments, the dirt collection region may be a portion (e.g., a lower portion) of the cyclone chamber. In other embodiments, the dirt collection region may be a dirt collection chamber that is separated from the cyclone chamber by a dirt outlet of the cyclone chamber.

Plurality of Dirt Collection Chambers

In accordance with one aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a stick surface cleaning apparatus may have more than one dirt collection chamber. For example, the handvac may include a first dirt collection chamber, and the upright section may include a second dirt collection chamber. The second dirt collection chamber provides the surface cleaning apparatus with an enlarged dirt collection capacity in comparison with the dirt collection capacity of the handvac alone. Accordingly, the surface cleaning apparatus may operate for longer intervals before one or more of the dirt collection chambers needs to be emptied.

In accordance with this aspect, and as exemplified in FIG. 4, upright section 108 may have an auxiliary dirt collection assembly 140, which may comprise or consist of an auxiliary dirt collection chamber 141. For example, the auxiliary dirt collection chamber 140 may be the only component provided in the auxiliary dirt collection assembly and therefore the auxiliary dirt collection chamber 140 may be the

11

auxiliary dirt collection assembly. Alternately, as disclosed in alternate embodiments, the auxiliary dirt collection assembly may also include one or more of a pre-motor filter, one or more cyclone chambers that may have one or more associated dirt collection chambers and a suction motor.

As illustrated, up flow duct **144** (also referred to as a wand if removable for use, e.g., in an above floor cleaning mode as exemplified in FIGS. **33** and **44a**) may define the airflow path between surface cleaning head **104** and handvac **112**. Auxiliary dirt collection chamber **140** may be a supplemental dirt collection chamber that is selectively mounted to up flow duct **144** and augments the dirt collection capacity of surface cleaning apparatus **100** when mounted to upper section **108**.

It will be appreciated that if up flow duct **144** is the member that supports handvac **112** when auxiliary dirt collection assembly **140** is removed, the up flow duct is designed to be load supporting and may be a rigid tube. Further if the up flow duct is removable to function as an above floor cleaning wand, then the up flow duct may also be a rigid tube. In other embodiments, e.g., the up flow duct is not a load supporting member, then all or a portion of up flow duct **144** may be flexible, such as a flexible hose.

As exemplified in FIGS. **1** and **21**, the dirt collection assembly **140** of the upright section **108** may collect at least a portion of the dirt separated from the dirty airflow by the handvac **112**. Accordingly, the dirt collection assembly **140** of the upright section **108** may be in communication with the dirt collection chamber of handvac **112** all or a portion of the time when the handvac **112** is mounted to the upright section **108**. For example, the dirt collection chamber of handvac **112** may have a door that automatically opens when handvac **112** is mounted to the upright section **108**. Accordingly, dirt separated by handvac **112** may travel to the supplemental dirt collection assembly **140**. Alternately, the door may be manually operable by a user. Accordingly, dirt may only be transferred to the supplemental dirt collection assembly **140** when a user elects to open the door. Alternately, the supplemental dirt collection assembly **140** may receive dirt from an auxiliary air treatment member, in which case the auxiliary dirt collection assembly may comprise a housing having both the auxiliary air treatment member and the auxiliary dirt collection chamber.

The dirt collection chamber of auxiliary dirt collection assembly **140** and handvac dirt collection chamber **188** may be of any suitable volumetric sizes. Preferably, the volumetric storage capacity of the dirt collection chamber of auxiliary dirt collection assembly **140** is at least equal to the volumetric storage capacity of handvac dirt collection chamber **188**, and more preferably larger than the volumetric storage capacity of handvac dirt collection chamber **188**. For example, the volumetric storage capacity of the dirt collection chamber of auxiliary dirt collection assembly **140** may be 1-20 times the volumetric storage capacity of handvac dirt collection chamber **188**, more preferably 1.5-10 times, and most preferably 3-5 times. In alternative embodiments, the volumetric storage capacity of the dirt collection chamber of auxiliary dirt collection assembly **140** may be less than that of handvac dirt collection chamber **188**.

As exemplified in FIG. **21**, handvac **112** may include a cyclone bin assembly **136** including one or more cyclone chambers **184** and one or more dirt collection chambers **188**. The cyclone chamber or chambers and the dirt collection chamber or chambers may be of any design. As exemplified, cyclone chamber **184** includes an air inlet **192** in fluid communication with wand **144**, an air outlet **196** downstream of air inlet **192**, and a dirt outlet **200** in fluid

12

communication with dirt collection chamber **188**. Suction motor **204** or another suction source may draw dirty air to enter air inlet **192** and travel cyclonically across cyclone chamber **184** to dirt outlet **200** where dirt is ejected into dirt collection chamber **188**. Afterwards, the air is discharged from cyclone chamber **184** at air outlet **196**.

As exemplified in FIGS. **21-23**, cyclone bin assembly **136** may include laterally opposed side walls **208**, a top wall **212**, a bottom wall **216**, a first end wall **220**, and a second end wall **224**. As shown, a common interior wall **226** may divide cyclone chamber **184** from dirt collection chamber **188**. For example, cyclone chamber **184** may be defined by top wall **212** and interior wall **226** which extend between end walls **220** and **224**. Top wall **212** and interior wall **226** may be curved to define a substantially cylindrical or frustoconical sidewall of cyclone chamber **184**. In alternative embodiments, cyclone chamber **184** may have a sidewall of any other suitable shape that is conducive to cyclonic flow. In some alternative embodiments, interior wall **226** of cyclone chamber **184** may be discrete from dirt collection chamber **188** instead of forming a common wall dividing cyclone chamber **184** from dirt collection chamber **188**.

Dirt collection chamber **188** may be defined by bottom wall **216**, side walls **208**, and interior wall **226**. In some embodiments, bottom wall **216** may be openable for fluidly connecting handvac dirt collection chamber **188** to supplemental dirt collection assembly **140** of upright section **108**. This may permit dirt separated by cyclone chamber **184** and discharged through dirt outlet **200** to move through opened bottom wall **216** and collect in supplemental dirt collection assembly **140**.

Optionally, when the auxiliary dirt collection assembly is mounted to upright section **108**, dirt separated in the cyclone chamber is collectable in the dirt collection chamber of the auxiliary dirt collection assembly. The auxiliary dirt collection assembly may be selectively connectable in communication with the dirt collection region of the hand vacuum cleaner by, e.g., an openable door **228** (also referred to as a dumping door). The door may be manually openable, such as by a handle, or automatically operated, such as when the auxiliary dirt collection assembly is mounted to upright section **108**. In this case, dirt will collect in the handvac **112** and will remain there until door **228** is openable so as to allow the collected dirt to transfer to supplemental dirt collection assembly **140**. In the latter case, supplemental dirt collection assembly **140** is automatically connected in communication with a dirt outlet of the cyclone chamber when the auxiliary dirt collection assembly is mounted to upright section **108**. In this case, dirt will collect in the supplemental dirt collection assembly **140** when handvac **112** is mounted to the upright section **108**.

In the illustrated example, bottom wall **216** includes a door **228**, which may be a pivotally openable door **228**. As shown, door **228** may be pivotally connected to dirt collection chamber **188** by a hinge **232** for rotation about a hinge axis **236**. Door **228** may extend forwardly from a rear end **240** to a front end **244**. Preferably, hinge **232** and hinge axis **236** are positioned at rear end **240** of door **228**. In alternative embodiments, hinge **232** and hinge axis **236** may be positioned at front end **244** or intermediate front and rear ends **240** and **244**.

Door **228** is preferably outwardly pivotal of dirt collection chamber **188**. For example, door **228** may be movable between a closed position (FIG. **22**) in which door **228** closes bottom wall **216**, and an open position (FIG. **21**) in which door **228** is rotated away from dirt collection chamber **188** for opening bottom wall **216** to permit dirt to move from

handvac dirt collection chamber **188** to supplemental dirt collection assembly **140**. As shown, in the open position front end **244** of door **228** may be moved away from handvac dirt collection chamber **188**.

Hinge axis **236** may have any suitable orientation. In the illustrated example, hinge axis **236** extends laterally side-to-side of surface cleaning apparatus **100**. Hinge axis **236** may be transverse to one or more of cyclone axis **248** of cyclone chamber **184**, motor axis **252** of suction motor **204**, or downstream direction **256** through air inlet **192**. In the example shown, hinge axis **236** is perpendicular to cyclone axis **248**, motor axis **252**, and downstream direction **256**. In alternative embodiments, hinge axis **236** may be substantially parallel to one or more of cyclone axis **248**, motor axis **252**, or downstream direction **256**.

In some embodiments, door **228** may extend upwardly and forwardly between rear end **240** and front end **244**. For example, front end **244** may be positioned closer to cyclone chamber **184** and cyclone axis **248** than rear end **240**. When door **228** is opened (FIG. **21**), this may provide a bottom opening **260** having a transverse width **264** between cyclone chamber **184** and bottom wall **216**.

Optionally, the dirt collection region (the dirt collection chamber) of the hand vacuum cleaner is positioned above the supplemental dirt collection assembly **140**. Accordingly, dirt that is received in the dirt collection chamber of the hand vacuum cleaner may be transferred by due to gravity to the supplemental dirt collection assembly **140**. Accordingly, for example, dirt outlet **200** may be positioned on a bottom end **268** of cyclone chamber **184** for discharging dirt toward bottom wall **216** and opening **260** to be delivered by gravity into supplemental dirt collection assembly **140** of upright section **108**.

Reference is now made to FIGS. **21**, **22**, and **24**. Preferably, when handvac **112** is connected to upright section **108**, opening **260** is fluidly coupled to an inlet to dirt collection assembly **140**. In the illustrated example, door **228** and opening **260** of cyclone bin assembly **136** align with an inlet **272** of dirt collection assembly **140**. As shown, inlet **272** may be formed as an opening in an upper portion **276** of dirt collection assembly **140**. In some embodiments, inlet **272** may include a door (not shown) which opens automatically and concurrently with door **228**. Optionally, the door of inlet **272** may be biased (e.g. by a spring) to close inlet **272** and seal dirt collection assembly **140** when door **228** is closed or handvac **112** is disconnected from upright section **108**.

Preferably, opening **260** and inlet **272** of upper portion **276** of dirt collection assembly **140** are sized and positioned to receive at least a portion of door **228** when door **228** is in the open position. This may permit door **228** to open outwardly into the open position as shown in FIG. **21**.

If door **228** is moveable from the closed position to the open position automatically upon connecting handvac **112** to upright section **108**, then handvac **112** may include an actuator drivingly connected to door **228** to move door **228** (e.g., pivot door **228** about hinge axis **236**) to the open position when handvac **112** is connected to upright section **108**. In the illustrated embodiment, door **228** includes an arm **280** pivotally connected at hinge **232**. As shown, arm **280** may include a lever portion **284** which extends rearwardly of hinge **232**, and which may be depressed to pivot door **228** to the open position. Further, dirt collection assembly **140** is shown including an engaging member **288** positioned to align with lever portion **284** of arm **280**. In use, engaging member **288** may depress lever portion **284** of arm **280** upon connecting handvac **112** to upright section **108** to automatically pivot door **228** into the open position,

whereby opening **260** may be fluidly connected to inlet **272** of supplemental dirt collection assembly **140**. In one aspect, this may permit a user, who has used handvac **112** when disconnected from upright section **108**, to automatically empty handvac dirt collection chamber **188** by connecting handvac **112** to upright section **108**. Afterwards, handvac **112** may be disconnected from upright section **108** with an empty dirt collection chamber **188**.

If door **228** is manually moveable from the closed position to the open position then, as exemplified in FIGS. **97a-b** and **98a-b**, door **228** may be provided with an actuator, e.g., a manually operable lever portion **284**. Lever portion **284** may extend downwardly from door **228** such that lever portion **284** is user-accessible and user-operable while handvac **112** is mounted to upright section **108**. As exemplified, lever portion **284** may protrude from the bottom wall **216** of cyclone bin assembly **136** to provide user-accessibility to lever portion **284**.

As exemplified in FIGS. **21**, **22**, **24**, **97a-b**, and **98a-b**, whether door **228** is manually or automatically operable, door **228** may be biased to the closed position. For example, door **228** may be biased for rotation about hinge axis **236** toward the closed position by a biasing member (not shown), such as a torsion spring. This may permit door **228** to close automatically upon disconnecting handvac **112** from upright section **108**, to prevent dirt from spilling from dirt collection chamber **188** and to permit immediate use of handvac **112** for cleaning. In alternative embodiments, door **228** may not be biased toward the closed position. For example, door **228** may remain in the open position upon disconnecting handvac **112** from upright section **108**. In such a case, door **228** may remain open until manually closed. For example, referring to FIGS. **98a-b**, door **228** may remain in the open position shown until lever portion **284** of arm **280** is user-activated to move door **228** to the closed position.

Removable Supplemental Dirt Collection Assembly

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a surface cleaning apparatus has two or more dirt collection chambers wherein one of the dirt collection chambers is optionally removable, and the surface cleaning apparatus is operable when the removable dirt collection chamber has been removed. Accordingly, as discussed with respect to the previous embodiment, a supplemental dirt collection chamber may be provided on the up flow duct or wand of a stick vacuum cleaner and may be the main dirt collection chamber (e.g., it may collect most or all of the separated dirt when the stick vacuum cleaner is operated with the supplemental dirt collection chamber in position). This may be referred to as a large dirt capacity upright mode or a second upright mode of operation.

The supplemental dirt collection chamber may be removable for emptying and to reconfigure the vacuum to a light weight upright mode or a first upright mode of operation. Once removed, the vacuum cleaner may be operable to separate dirt and collect the separated dirt in another dirt collection chamber (e.g. the handvac dirt collection chamber). An advantage of the light weight upright mode is that the size and weight of the vacuum cleaner may be reduced by removal of the supplemental dirt collection chamber. This may be of assistance when the vacuum cleaner is used to clean around and under furniture, and when the vacuum cleaner is to be carried upstairs.

As exemplified in FIGS. **1** and **4**, dirt collection assembly **140** of upright section **108** may be removably connected to wand **144** and handvac **112**. This may permit dirt collection

15

assembly **140** to be removed for emptying, or to operate apparatus **100** in a light weight upright mode. It will be appreciated that, in alternate embodiments, wand **144** and dirt collection assembly **140** of upright section **108** may be integrally formed or permanently connected as a one piece assembly.

Dirt collection assembly **140** may be removably mounted to wand **144** in any suitable fashion. In the illustrated embodiment, a lower end **292** of dirt collection assembly **140** may be toed onto a lower end **296** of wand **144**, and then dirt collection assembly **140** may be pivoted about lower end **292** toward wand **144** and held in position by a suitable releasable fastening mechanism.

In the illustrated embodiment, handvac **112** may remain in fluid communication with wand **144** and surface cleaning head **104** while supplemental dirt collection assembly **140** is disconnected from wand **144** and removed altogether from apparatus **100**. This may permit dirt collection assembly **140** to be removed (e.g., for emptying or to operate apparatus **100** in a light weight upright mode) without disrupting the operation of apparatus **100**.

Upstream Air Treatment Member

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, an upstream air treatment member may be provided. The upstream air treatment member may be removably connectable upstream of the handvac. For example, the supplemental dirt collection assembly may have one or more cyclone chambers associated therewith. Accordingly, when the supplemental dirt collection assembly is positioned on upright section **108** (e.g., up flow duct **144**), a supplemental cyclone chamber assembly **160** may be connected in series or parallel with the cyclone chamber of the handvac. Accordingly, when operated as an upright vacuum, the surface cleaning apparatus may be a dual cyclonic stage surface cleaning apparatus. When used in an above floor cleaning mode, the handvac may be a single cyclonic stage surface cleaning apparatus. Typically, the surface cleaning apparatus may be used as an upright vacuum cleaner (i.e., with the supplemental cyclonic bin assembly attached) for cleaning floors. This may represent the majority of area that is to be cleaned. Therefore, for a majority of the use of the surface cleaning apparatus, it may be used as a dual stage cyclonic surface cleaning apparatus.

In accordance with this aspect, the upright section may include a first air treatment member for separating at least large dirt particles from the airflow, and the air treatment member of the handvac may be positioned downstream of the first air treatment member for separating small dirt particles ("fines") from the airflow. In this case, the greatest volume of separated dirt may be collected in the dirt collection chamber of the upright section, and a lesser volume of fines may be collected in the dirt collection chamber of the handvac. This may reduce the rate at which the handvac dirt collection chamber may be filled, and reduce the frequency at which the handvac dirt collection chamber must be emptied. It will be appreciated that each cyclonic stage may be of any design and may be designed to remove any type of dirt.

It will be appreciated that, in some embodiments, dirt separated by the handvac may be collected in the supplemental dirt collection assembly. In such a case, the dirt collection region of the handvac may be in communication (automatically or manually selectively) with a dirt collection region in the supplemental dirt collection assembly, which

16

region may be isolated from the dirt collection chamber for the cyclonic stage of the supplemental cyclone chamber assembly.

It will be appreciated that, if air travels through up flow duct **144** to handvac **112**, when cyclone bin assembly **160** is connected to wand **144**, air travelling through wand **144** may be diverted into cyclone bin assembly **160** and returned to wand **144** from cyclone bin assembly **160** downstream of the diversion. Optionally, in accordance with another aspect with is discussed in more detail subsequently, and which is exemplified in the embodiment of FIGS. **20** and **26**, in some embodiments the diversion may occur automatically upon mounting of the supplemental cyclone bin assembly **160** to upright section **108**. For example, cyclone bin assembly **160** may include a diversion member **428** which may be positionable in the conduit of wand **144** between the upstream and downstream ends **364** and **360** of wand **144**. As shown, diversion member **428** may divide wand **144** into an upstream wand portion **440** and a downstream wand portion **444**. Diversion member **428** may form an air-tight seal inside wand **144** for redirecting substantially all air traveling through upstream wand portion **440** into air inlet **316** of cyclone bin assembly **160**. In turn, air outlet **320** of cyclone bin assembly **160** may discharge into downstream wand portion **444** for travel downstream to handvac **112**.

As exemplified in the embodiment of FIGS. **5**, **12**, and **25** supplemental cyclone bin assembly **160**, **160** may be any suitable cyclone bin assembly and may include a cyclone chamber **308** and a dirt collection chamber **141**. Cyclone chamber **308** may include an air inlet **316** for receiving dirty air from the surface cleaning head, e.g., via wand **144**, an air outlet **320** for discharging air, e.g., to handvac **112**, a dirt outlet **324** for discharging separated dirt into dirt collection chamber **141**, a vortex finder **400** and a cyclone axis **392**. Wand **144** may include an upstream end **360** connected to surface cleaning head **104**, and a downstream end **364** connected to air inlet **316** of cyclone chamber **308**.

From cyclone bin assembly **160**, the airflow may flow downstream to handvac **112**. Accordingly, handvac cyclone bin assembly **136** is positioned downstream of and in series with supplemental cyclone bin assembly **160**. The air may be received in handvac cyclone bin assembly **136** where additional particulate matter may be further separated from the airflow and deposited into dirt collection chamber **188**. In many cases, the additional particulate matter separated by cyclone bin assembly **136** may constitute less than 30% of the total volume of dirt separated from apparatus **100**, and may constitute all or a majority of the fines that are separated. Accordingly, dirt collection chamber **188** may be filled at a lower volumetric rate than supplemental dirt collection chamber **141**. This may help to maintain dirt collection capacity in handvac **112**.

In operation, air exiting air outlet **320** of cyclone bin assembly **160** may enter handvac **112** for a second stage of cleaning by cyclone bin assembly **136**. As illustrated, handvac **112** may include a nozzle **412** having, an upstream end **416** and a downstream end **420**. When handvac **112** is connected to upright section **108**, upstream end **416** may be fluidly connected with air outlet **320** of upright section **108**, and downstream end **420** may be fluidly connected with inlet **192** of handvac cyclone chamber **184**.

In operation, air may be drawn into dirty air inlet **124** and enter upstream wand portion **440**. Diversion member **428** may redirect the air traveling through upstream wand portion **440** to enter air inlet **316** of cyclone chamber **308**. Air may travel through air inlet **316** tangentially to sidewall **376** and spiral downwardly toward lower end wall **368**, whereby

17

dirt may be separated from the airflow and pass through dirt outlet 324 to accumulate in dirt collection chamber 141. The airflow may then travel downstream into vortex finder 400 and exit cyclone chamber 308 at air outlet 320 at downstream end 404 of vortex finder 400, into an outlet passage 476. Outlet passage 476 may have a downstream end fluidly connected to downstream wand portion 444. The air may travel through downstream wand portion 444 to downstream wand end 364 into handvac 112. In handvac 112, additional dirt may be separated from the airflow by cyclone bin assembly 136 before the air is discharged through clean air outlet 132.

It will be appreciated that, in accordance with this aspect, cyclone bin assembly 160 may be any suitable cyclone bin assembly. In the example shown in FIGS. 5, 12, and 25, cyclone chamber 308 includes a lower end wall 368, an upper end wall 372, and a sidewall 376 extending between the lower end wall 368 and the upper end wall 372. Preferably, sidewall 376 is substantially cylindrical or frustoconical in accordance with conventional cyclone chamber design.

Dirt outlet 324 may be formed as an opening in sidewall 376 for directing separated dirt into dirt collection chamber 141. In some embodiments, at least a portion of sidewall 376 of cyclone chamber 308 may form a common dividing wall between cyclone chamber 308 and dirt collection chamber 141. In this case, dirt outlet 324 may be formed as an opening in the common portion of sidewall 376.

Dirt outlet 324 may be formed at any suitable position on sidewall 376. In the illustrated example, dirt outlet 324 is positioned at an upper end of cyclone chamber 308 proximate upper end wall 372. More particularly, the illustrated embodiment includes a dirt outlet 324 defined by a slot 380 in sidewall 376 bordered by upper end wall 372. This may increase the capacity of dirt collection chamber 141. More specifically, dirt may accumulate by gravity from the bottom of dirt collection chamber 141 upwardly. Thus, the capacity of the dirt collection chamber 141 may be defined at least in part by the position of dirt outlet 324. Dirt collection chamber 141 is full when the level of dirt in dirt collection chamber 141 rises to dirt outlet 324. Accordingly, the capacity of dirt collection chamber 141 is the volume of the dirt collection chamber 141 below dirt outlet 324. Thus, the capacity of dirt collection chamber 141 may be increased by positioning dirt outlet 324 in an uppermost position, such as proximate the upper end wall 372 of cyclone chamber 308 as shown.

Alternately, in some embodiments as exemplified in FIG. 26, lower end wall 368 may comprise or be an arrester plate 1280 which separates cyclone chamber 308 from dirt collection chamber 141. In this case, dirt outlet 324 may be formed by a gap between arrester plate 1280 and sidewall 376, where dirt particles may fall by gravity into dirt collection chamber 141.

In accordance with another aspect which is discussed in more detail subsequently, as exemplified, cyclone chamber 308 may include an inlet passage 384 for redirecting axially-directed inlet air to flow tangentially to promote cyclonic action in cyclone chamber 308. An upstream end 388 of inlet passage 384 may face axially (i.e. substantially parallel to cyclone axis 392), and a downstream end (not shown) of inlet passage 384 may face tangentially to cyclone chamber 308. Air entering upstream end 388 of inlet passage 384 from air inlet 316 may travel along inlet passage 384 and exit downstream end (not shown) in a tangential direction. After spiraling upwardly around vortex finder 400 of cyclone chamber 308, the airflow may enter vortex finder

18

400 and exit cyclone chamber 308 through air outlet 320 at a downstream end 404 of vortex finder 400.

Handvac cyclone chamber 184 may be any suitable cyclone chamber. In some embodiments, cyclone chamber 184 is substantially similar to cyclone chamber 308. For example, cyclone chamber 184 may include an air inlet 192, an inlet passage 420, a dirt outlet 200, a vortex finder 424, a dirt outlet 200, an air outlet 196, and a cyclone axis 248. Air from upright section 108 may axially enter air inlet 192, be redirected to a tangential direction by inlet passage 420, spiral upwardly around vortex finder 424, deposit dirt into dirt outlet 200, and then exit cyclone chamber 184 through air outlet 196 at a downstream end of vortex finder 424.

Modes of Operation

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, the surface cleaning apparatus is reconfigurable to operate in a plurality of different modes of operation. For example, the surface cleaning apparatus may be operable in two or more of a handvac mode, a stair-cleaning mode, an above-floor cleaning mode, a large dirt capacity upright mode, a lightweight upright mode, or a dual motor upright mode. In some cases, the surface cleaning apparatus may be reconfigurable between different modes of operation with a single act of connection or disconnection. This may permit the surface cleaning apparatus to be quickly reconfigured with minimal interruption.

Referring to FIGS. 1, 5, and 13, surface cleaning apparatus 100, 152, and 168 are shown in a large dirt capacity upright cleaning mode. In the large dirt capacity upright cleaning mode, surface cleaning apparatus 100, 152, and 168 may include surface cleaning head 104, upright section 108 including wand 144 and supplemental dirt collection assembly 140, and handvac 112. The airflow path may extend from dirty air inlet 124 of surface cleaning head 104 downstream through wand 144 and then cyclone bin assembly 136 of handvac 112 to separate dirt from the airflow and deposit that dirt into dirt collection chamber 141 of upright section 108 and/or handvac dirt collection chamber 188. In apparatus 152 and 168, cyclone bin assembly 160 is also positioned in the airflow path for separating and collecting dirt from the airflow and cyclone bin assembly 136 of handvac 112 may optionally be bypassed as discussed subsequently.

As exemplified in FIGS. 12 and 12a one or more of the surface cleaning head 104, upright section 108, and handvac 112 may be removably connected to each other so as to be able to be assembled in a number of different combinations to provide apparatus 152 with a number of different modes of operation. In some embodiments, the wand 144 and supplemental assembly 140, 160 of upright section 108 may also be removably connected to each other to provide additional modes of operation. For example, in the large dirt capacity upright cleaning mode, surface cleaning head 104 may be connected to upstream end 360 of wand 144, downstream end 364 of wand 144 may be connected to an air inlet 316 of cyclone bin assembly 160, and air outlet 320 of cyclone bin assembly 160 may connected to upstream end 416 of handvac nozzle 412.

The large dirt capacity upright cleaning mode as shown may be particularly effective for cleaning large surface areas (e.g. the floor of one or more rooms). The user may grasp handvac handle 484 to steer surface cleaning head 104 across the surface to be cleaned (i.e. handle 484 may be a drive handle of the surface cleaning apparatus). The tall height 492 of apparatus 100, 152, and 168 provided in part

by the interposition of wand **144** between surface cleaning head **104** and handvac **112** may permit apparatus **100** to be operated by a user standing upright. The large dirt capacity of dirt collection chamber **141** of upright section **108** may permit extended usage of apparatus **100** before the dirt collection chamber **141** becomes full and must be emptied.

As exemplified in FIGS. **4**, **5**, **12**, **12a**, **20** and **27-30**, and **37-44** dirt collection assembly **140** or cyclone bin assembly **160** may be selectively disconnected from upright section **108** to reconfigure apparatus **100**, **152**, or **168** from the large dirt capacity upright mode to a light weight upright mode. Likewise, dirt collection assembly **140** or cyclone bin assembly **160** may be selectively reconnected to upright section **108** to reconfigure apparatus **100**, **152**, or **168** from a light weight mode to a large dirt capacity upright mode.

Preferably, reconfiguring the apparatus from the large dirt capacity upright mode to the light weight upright mode may require only a single user action (e.g., disconnecting the dirt collection assembly **140** or cyclone bin assembly **160** from the upright section **108** may automatically close a dumping door of the handvac if the dumping door is open and may also automatically close a diversion member if the vacuum cleaner includes a supplemental cyclone bin assembly **160**).

As exemplified in apparatus **100**, door **228** which may have been open in the large dirt capacity upright mode for connecting dirt collection chambers **188** and **141**, may close automatically (i.e. without any further user interaction) upon disconnecting dirt collection chamber **141**, to seal bottom wall **216** of dirt collection chamber **141**. Exemplary mechanisms include a biasing member, such as a spring and a mechanical or electrical drive member drivingly connected to the door to close the door as supplemental assembly **140**, **160** is removed.

As exemplified in apparatus **168**, disconnecting cyclone bin assembly **160** from wand **144** may automatically reroute the airflow path to extend directly from upstream wand end **360** to downstream wand end **364** without the intermediary diversion to cyclone bin assembly **160**. Therefore, the airflow path between surface cleaning head **104** and handvac **112** is automatically reconfigured by disconnection of cyclone bin assembly **160** to reconfigure apparatus **168** to the light weight upright mode. Accordingly apparatus **168** may be continually operated while being reconfigured.

In alternative embodiments, door **228** of apparatus **100** may be manually closed as another step before, during or after dirt collection assembly **140** is disconnected from upright section **108** to complete the reconfiguration to the light weight upright mode. For example, a user may manually close the door. In other embodiments, as described in more detail below, a diversion valve of apparatus **168** may require manual closure as another step after cyclone bin assembly **160** is disconnected from wand **144** to complete the reconfiguration to the light weight upright mode. Alternately, a single actuator may be manually operated to close the door and the diversion valve.

As exemplified in FIG. **4**, apparatus **152** may be reconfigurable from the large dirt capacity upright mode to a light weight upright mode by disconnecting assembly **140**, **160** from wand **144**. In some cases, it may be desirable to momentarily reconfigure an apparatus to the lightweight upright mode to complete a task (e.g. clean under an article of furniture), and afterward reconfigure the apparatus to the large dirt capacity upright mode. In the illustrated example, the airflow path between surface cleaning head **104** and handvac **112** persists during and after reconfiguration of apparatus **100** from the large dirt capacity upright mode to the lightweight upright mode. This may permit apparatus

100, to be operated continuously (i.e. air to continue to travel between inlet **124** and outlet **132**) before, during, and after reconfiguration to the lightweight upright mode. In turn, this may allow for a quick reconfiguration with little or no disruption. It will be appreciated that if a cyclone is provided in the supplemental assembly (e.g., assembly **160**), there may be a short period during which the diversion valve is not closed during the transition.

In some cases, reconfiguring apparatus **100**, **152**, or **168** from the large dirt capacity upright mode to the lightweight upright mode may provide a reduction in weight (i.e. by the removal of dirt collection assembly **140** or cyclone bin assembly **160**), and a more slender profile. Thus, the lightweight upright mode may make apparatus **100**, **152**, or **168** easier to lift (e.g. carry upstairs), and easier to maneuver under and around furniture and the like. However, in this mode, all of the dirt separated by cyclone bin assembly **136** in the lightweight upright mode is collected in dirt collection chamber **188**. Thus, apparatus **100**, **152**, or **168** may have less dirt collection capacity in the lightweight upright mode as compared with the large dirt capacity upright mode.

Referring now to FIGS. **31-33**, **44a**, and **44b**, apparatus **100** and **168** are shown in an above-floor cleaning mode. As illustrated, apparatus **100** and **168** in the above-floor cleaning mode include handvac **112** and wand **144**. Apparatus **100**, **152**, and **168** may be reconfigured from the lightweight upright mode to the above-floor cleaning mode by disconnecting surface cleaning head **104** from wand **144**. It will be appreciated that assembly **140,160** may be retained in an above floor cleaning mode if desired. However, this would add extra weight to the apparatus in the above floor cleaning mode.

Referring to FIG. **36a**, apparatus **152** is shown in another above-floor cleaning mode. As shown, apparatus **152** in an above-floor cleaning mode may include handvac **112** and an accessory wand **145**. Accessory wand **145** may be provided supplementary to wand **144** of upright section **108**. For example, accessory wand **145** may be removably mountable to a sidewall of upright section **108**, as shown in FIG. **5**. Still referring to FIG. **36a**, in the above-floor cleaning mode shown, upstream end **360** may provide the dirty air inlet, and downstream end **364** may be removably fluidly connected to handvac nozzle **412**. Accessory wand **145** may have any suitable length **516**. For example, wand **144** may have a length sufficient to permit apparatus **100** to be used as an upright vacuum cleaner in the configuration of FIG. **5**. Accordingly, wand **144** may be 2-4 feet long. In contrast, accessory wand **145** may be shorter than wand **144** (e.g., a user wants to be closer to the area to be cleaned in an above floor cleaning mode) and accordingly accessory wand **145** may be 6-18 inches.

In the above-floor cleaning mode, the upstream end **496** of wand **144** may provide the dirty air inlet of apparatus **100**, **152**, or **168**. The above-floor cleaning mode may be well suited to cleaning surfaces above the floor, or more generally surfaces that are not substantially horizontal, and for cleaning in crevices which surface cleaning head **104** might be unable to access. The wand **144** may provide extended reach for distant cleaning surfaces (e.g. curtains, and ceilings). An auxiliary cleaning tool such as a crevice tool, brush or the like may be attached to the inlet end of the wand.

Preferably, apparatus **100**, **152**, or **168** may be reconfigured from the lightweight upright mode to the above-floor cleaning mode by a single user action—disconnection of surface cleaning head **104** from the upstream end **496** of wand **144**. This may permit the apparatus to be quickly reconfigured with little or no disruption. For example, the

apparatus may operate continuously before, during, and after reconfiguration from the lightweight upright mode to the above-floor cleaning mode. This may permit a user to conveniently reconfigure the apparatus to the above-floor cleaning mode to clean a surface inaccessible in the lightweight upright mode, and afterward reconfigure the apparatus to the lightweight upright mode to continue cleaning, e.g. the floor.

In some embodiments, the above-floor cleaning mode may further include dirt collection assembly **140**. For example, a user may reconfigure apparatus **100**, **152**, or **168** from the large dirt capacity upright mode (FIGS. **1**, **5**, and **13**) to the above-floor cleaning mode by disconnecting surface cleaning head **104** from wand **144**, while maintaining dirt collection assembly **140** in place on wand **144**. An above-floor cleaning mode of this configuration may provide apparatus **100** with the reach of the above-floor cleaning mode, and the storage capacity of the large dirt capacity upright mode. In some embodiments, dirt collection assembly **140** may be a one piece assembly with the wand **144** (i.e. irremovably connected to wand **144**), in which case the wand **144** may be an up flow duct.

Referring to FIG. **22**, apparatus **100**, **152**, and **168** may be reconfigured to a handvac mode from any other mode of operation by disconnecting handvac **112** (e.g. from wand **144**). As illustrated, the handvac mode may include handvac **112** alone. In the handvac mode, upstream end **416** of nozzle **412** may provide the dirty air inlet. Optionally, one or more accessories (not shown), such as a brush, crevice tool, auxiliary wand **145** may be connected to nozzle **412**. If a wand **144** is part of dirt collection assembly **140** then an accessory wand **145** may be provided which is connectable to nozzle **412**.

The handvac mode of apparatus **100** may be lighter, smaller, and more agile than the other modes of operation. However, the handvac mode may have a smaller dirt collection capacity than the large dirt capacity upright mode (FIGS. **1**, **5**, and **13**) for example.

In some cases, a user may wish to momentarily disconnect handvac **112** for use in the handvac mode (e.g. to clean a surface that is more accessible in the handvac mode), and then return the apparatus to the previous mode. For example, apparatus **100**, **152**, or **168** may be momentarily reconfigured from the large dirt capacity upright mode (FIGS. **1**, **5**, and **13**) or from the lightweight upright mode (FIGS. **27** and **37**) to the handvac mode be merely removing the handvac and afterward reconfigured again to the upright mode.

It may be beneficial for the dirt collection chamber **188** of handvac **112** to have capacity available for use in the handvac mode upon disconnecting handvac **112** from upright section **108**. Further, it may be beneficial for dirt collection chamber **188** of handvac **112** to reclaim capacity after reconnecting handvac **112** to upright section **108**. This may be achieved by having dirt collection chamber **188** empty into assembly **140**, **160** continually while handvac **112** is attached to the assembly, manually before removal of the handvac or upon removal of the handvac. The dirt capacity may be reclaimed by having dirt collection chamber **188** empty into assembly **140**, **160** upon replacing handvac **112** to the assembly (either manually or automatically upon replacement).

An example of such a reconfiguration is discussed with respect to the embodiment of FIG. **21**. In the illustrated example, handvac dirt collection chamber **188** has a bottom wall **216** that remains open to dirt collection assembly **140** while the handvac is attached to permit dirt from handvac dirt collection chamber **188** to transfer (e.g., by gravity) to

dirt collection chamber **141** thereby preventing dirt collection chamber **188** from being filled while the apparatus is used in one of the upright operating modes.

Apparatus **100** may be reconfigured from the handvac mode to the large dirt capacity upright mode by reconnecting handvac **112** to upright section **108**. Preferably, reconnecting handvac **112** to upright section **108** automatically opens handvac dirt collection chamber **188** to dirt collection chamber **141** for transferring at least a portion of the dirt, collected while in the handvac mode, to dirt collection chamber **141** thereby emptying dirt collection chamber **188** so that dirt collection chamber **188** is not full when the handvac is once again used in the handvac mode.

In some embodiments, handvac dirt collection chamber **188** does not empty into assembly **140**, **160** when attached to the assembly, manually or automatically. For example, FIGS. **25** and **26** show exemplary embodiments of apparatus **152** and **168** where assemblies **160** and **188** receive and store dirt separately at all times. As shown, upright dirt collection chamber **141** may receive and collect dirt separated by auxiliary cyclone bin assembly **160**, and handvac dirt collection chamber **188** may separately receive and collect dirt separated by handvac cyclone bin assembly **136**.

Turning now to FIGS. **123-126**, apparatus **152** is shown in accordance with another embodiment. As exemplified, handvac cyclone bin assembly **136** may include a plurality of cyclonic cleaning stages arranged in series. For example, and referring to FIGS. **125** and **126**, cyclone bin assembly **136** may include a first cyclonic cleaning stage **640** arranged in series upstream from a second cyclonic cleaning stage **644**. First cyclonic cleaning stage **640** may include one or more air outlet(s) **196a** which discharge into air inlet(s) **192b** of second cyclonic cleaning stage **644**.

Referring now to FIG. **127**, each cyclonic cleaning stage **640** and **644** may include one or more cyclone chambers **184** in parallel. For example, cyclonic cleaning stages **640** and **644** may each include one cyclone chamber **184**, or may each include a plurality of cyclone chambers **184**. Alternatively, one of cyclonic cleaning stages **640** and **644** may include one cyclone chamber **184** and the other stage may include a plurality of cyclone chambers **184**. In the illustrated example, first cyclonic cleaning stage **640** includes one cyclone chamber **184a**, and second cyclonic cleaning stage **644** includes a plurality of cyclone chambers **184b** arranged in parallel. For example, second cyclonic cleaning stage **644** may include four or more cyclone chambers **184b** arranged in parallel.

Second stage cyclone chamber(s) **184b** may have any suitable orientation relative to first stage cyclone chamber(s) **184a**. For example, each of second stage cyclone chamber(s) **184b** may have an air inlet **192b** and an air outlet **196b** both positioned proximate a rear end **648** of the second cyclonic cleaning stage **644** (rearward with respect to the inlet of the handvac), or both positioned proximate a front end **652** of the second cyclonic cleaning stage **644**. Alternatively, each of second stage cyclone chamber(s) **184b** may have an air inlet **192** positioned proximate one of the front and rear ends **648** and **652**, and an air outlet **196b** positioned proximate the other of the front and rear ends **648** and **652**. In the illustrated example, second stage cyclone chambers **184b** are shown including air inlets **192b** at front end **648** and air outlets at rear end **652**. This may reduce directional changes in the airflow which may reduce backpressure developed through second stage cyclone chambers **184b** for enhanced airflow efficiency. As shown, axes **248b** of second stage cyclone chamber **184b** may be parallel to axis **248a** of first stage cyclone chamber **184a**.

Handvac cyclone bin assembly **136** may include one or more dirt collection regions **188**. For example, cyclone chambers **184** of first and second cyclonic cleaning stages **640** and **644** may separate dirt into one common dirt collection region **188**, or each cyclonic cleaning stage **640** and **644** may include a separate dirt collection region **188**. In the latter case, all first stage cyclone chamber(s) **184a** may discharge dirt into the first stage dirt collection region **188a**, and all second stage cyclone chamber(s) **184b** may discharge dirt into the second stage dirt collection region **188b**. In the illustrated embodiment, handvac cyclone bin assembly **136** includes one first stage dirt collection region **188a**, and a plurality of second stage dirt collection regions **188b**, where each second stage dirt collection region **188b** receives dirt discharged by a respective second stage cyclone chamber **184b**.

Reference is now made to FIGS. **34-36**, which show apparatus **100**, **152**, or **168** in a stair-cleaning mode of operation. As shown, apparatus **100**, **152**, or **168** in stair-cleaning mode may include handvac **112** directly connected to surface cleaning head **104**. For example, nozzle **412** may be connected to pivot joint **116** of surface cleaning head **104**.

The stair-cleaning mode of operation may be especially suitable for cleaning stairs and the like, where frequent lifting is required to clean the desired surface areas.

Handvac Center of Gravity in the Upright Modes

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, when the apparatus is in an upright mode and, in particular in a large dirt capacity upright mode, the center of gravity of the handvac may be located directly above the cyclone bin assembly (or dirt collection chamber) of the upright section.

As exemplified in FIGS. **21** and **25**, apparatus **100** is shown in a large dirt capacity upright mode in a storage position. In the illustrated example, handvac **112** is shown including a handvac center of gravity **524**. As shown, center of gravity **524** may be positioned vertically above dirt collection assembly **140**/cyclone bin assembly **160** between the front and rear ends **532**, **544** and **536**, **548** of dirt collection assembly **140**/cyclone bin assembly **160**. Preferably, center of gravity **524** is positioned substantially centrally between front and rear ends **532**, **544** and **536**, **548** of dirt collection assembly **140**/cyclone bin assembly and may be aligned with the wand.

Alternately, or in addition, as exemplified, center of gravity **524** is positioned between cyclone bin assembly **136** and suction motor **204**, inside premotor filter chamber **556** of handvac **112**.

Configuration of the Auxiliary Assembly

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a surface cleaning apparatus may have an upright section with an auxiliary dirt collection assembly **140** or auxiliary cyclone bin assembly **160** sized, shaped, and positioned according any one of a plurality of different configurations relative to the wand of the upright section and the handvac.

In some embodiments, a surface cleaning apparatus is provided having an upright mode wherein the auxiliary assembly **140**, **160** and the handvac are positioned on the same side of the wand. As exemplified in FIGS. **1**, **21**, **24**, **45**, and **46**, auxiliary assembly **140**, **160** and handvac dirt collection chamber **188** may both extend rearwardly of wand **144**. Referring to FIG. **21**, rear end **536** of dirt collection assembly **140** is shown positioned a rearward distance **564** from wand axis **568**. Bottom wall **216** of dirt collection

chamber **188** is shown positioned a rearward distance **576** from wand axis **568**. Preferably, distances **564** and **576** are substantially equal. In alternative embodiments, distances **564** and **576** may be different. For example, distance **560** may be greater than distance **576**, or distance **576** may be greater than distance **564**. If rear end **536** is at an angle to the vertical as exemplified, then the handvac is preferable designed such that the rear end does not extend rearwardly past a projection of the line of rear end **536**. Accordingly, the lowest extend to which upright section **108** may be pivoted rearwardly is determined by the auxiliary assembly and not the handvac.

In some embodiments, a surface cleaning apparatus is provided having a upright mode wherein the auxiliary assembly **140**, **160** and the handvac are positioned on opposite sides of the wand. As exemplified in FIG. **26**, dirt collection assembly **140** of upright section **108** is positioned forwardly of wand **144**, and handvac dirt collection chamber **188** is positioned rearwardly of wand **144**. An advantage of this design is that the weight of the auxiliary assembly **140**, **160** is on the opposite side of wand **144** from the handvac and may assist in offsetting the hand weight of the handvac felt by a user holding the handle of the handvac.

In some embodiments, a surface cleaning apparatus is provided having a upright mode where the auxiliary assembly **140**, **160** and handvac are positioned on opposite left and right sides of the wand. For example, in apparatus **168**, cyclone bin assembly **160** may be mounted to one of the left or right sides of upright section **108** and handvac **112** may be oriented relative to the upright section **108** such that dirt collection chamber **188** extends to the other of the left or right sides of upright section **108**.

In some embodiments, the auxiliary assembly **140**, **160** of the upright section surrounds at least a portion of the wand. Referring to FIGS. **1**, **21**, **24**, **45** and **46**, apparatus **100** is shown including an upright section **108** having dirt collection assembly **140** which partially surrounds wand **144**. In the illustrated example, dirt collection assembly **140** includes a channel **584** for receiving at least a portion of wand **144**. As shown, channel **584** may extend the height **588** of dirt collection assembly **140** between lower and upper ends **292** and **596**. Channel **584** may also extend in depth from front end **532** rearwardly toward rear end **536**.

As exemplified, dirt collection assembly **140** includes left and right portions **600** and **604** on opposite left and right sides of channel **584**. In the upright mode of apparatus **100**, wand **144** may be at least partially received in channel **584**, whereby left and right portions **600** and **604** are positioned to the left and right sides of wand **144**. As shown, a front end **532** of dirt collection assembly **140** may extend forwardly of wand **144**, such that at least a portion of wand **144** is positioned between the front and rear ends **532** and **536** of dirt collection assembly **140**.

In the illustrated embodiment, dirt collection assembly **140** may also surround at least a portion of handvac **112** in the upright mode of apparatus **100**. In the illustrated embodiment, an outlet end **608** of wand **144** may be received in channel **584** of dirt collection assembly **140**. Accordingly, a front portion of handvac **112** may extend into channel **584** for connection with outlet end **608** of wand **144**. In the illustrated embodiment, nozzle **412** and inlet passage **420** of handvac **112** may be positioned inside channel **584** of dirt collection assembly **140** in the upright mode of apparatus **100**.

Upright Section with a Plurality of Cyclones

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one

or more other aspects of this disclosure, the supplemental cyclone bin assembly **160** may have a plurality of cyclones positioned in series and/or in parallel in the airflow path. The cyclones may be positioned to the same side of the upright section (e.g., front or back, left or right), or on different sides of the upright section (e.g. one front and one back or one on the right side and one on the left side). In one embodiment, the upright section may use two cyclones and the wand may be positioned between the two cyclones.

As exemplified in FIGS. 47-51, auxiliary cyclone assembly **160** comprises first and second supplemental cyclone bin assemblies **161**, which may be individual units or may be formed as a single unit or housing. Each cyclone bin assembly **161** is shown including a cyclone chamber **308** and a dirt collection chamber **141**. Dirt collection chambers **141** may be combined to form a common repository for dirt separated by both cyclone bin assemblies **161** or each cyclone bin assembly **161** may have a separate dirt collection chamber **141**.

Each cyclone chamber **308** may be any suitable cyclone chamber and maybe the same or different. As shown, each cyclone chamber **308** may include a tangential air inlet **344** proximate upper end **374**, and an axial air outlet **320** at a downstream end of vortex finder **400**.

Cyclone bin assemblies **161** may be positioned in parallel in the airflow path between surface cleaning head **104** and handvac **112**. As exemplified, the airflow path may extend from surface cleaning head **104** through an upstream wand portion **440**, diverge into the inlets **316** of cyclone chambers **308** through cyclone chambers **308** to their respective air outlets **320**. Each cyclone bin assembly **161** may include an outlet passage **476** connecting air outlets **320** to downstream portion **444** of wand **144** where the airflow path converges. From downstream portion **444** of wand **144**, the airflow path may extend through handvac **112** and exit out clean air outlet **132**.

As exemplified, upstream and downstream portions **440** and **444** of wand **144** may be divided by a diversion member **712**, which is described subsequently with respect to a further alternate aspect. Air traveling downstream through upstream portion **440** may contact diversion member **712** and be redirected laterally into air inlets **316** of cyclone chambers **308**. Outlet passages **476** of cyclone bin assemblies **161** may converge to form a single airflow path in downstream portion **444** of wand **144** above diversion member **712**.

Diversion Valve

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a diversion valve is provided which diverts air travelling through upright section **108** (e.g., the wand **144**) into the auxiliary assembly **160** (e.g., supplemental cyclone or cyclones **308**). Preferably, the diversion valve operates automatically upon the auxiliary assembly **160** being disconnected from and/or connected to the surface cleaning apparatus.

As exemplified in FIG. 20, cyclone bin assembly **160** may be selectively connected to upright section **108** whereby the airflow path may be reconfigured to extend through cyclone bin assembly **160**. Similarly, cyclone bin assembly **160** may be selectively disconnected from upright section **108** whereby the airflow path may be reconfigured to extend through wand **144** from end to end without diversion. Preferably, the airflow path reconfiguration is automatic upon connection and/or disconnection of cyclone bin assembly **160** to upright section **108**.

In some embodiments, wand **144** may include a diversion outlet **704** and a diversion inlet **708** positioned between the upstream and downstream ends **360** and **364** of wand **144**. The diversion outlet **704** and diversion inlet **708** may be selectively opened when connecting cyclone bin assembly **160** to upright section **108** to reconfigure the airflow path to divert into the cyclone bin assembly **160** at diversion outlet **704**, and to return to the wand **144** from cyclone bin assembly **160** at diversion inlet **708**. Upright section **108** may include a diversion valve for opening and closing diversion outlet **704** and inlet **708**.

A diversion valve **712** according to a first embodiment is exemplified in FIGS. 52-57. As exemplified, diversion valve **712** may include a sleeve **716** positioned inside of wand **144**, and a pedal **720** for moving sleeve **716** between an open position and a closed position.

Sleeve **716** may be a conduit for fluidly coupling upstream and downstream wand portions **440** and **444** in the closed position of diversion valve **712** (see FIGS. 52 and 55) to bypass diversion outlet and inlet **704** and **708**. Preferably, sleeve **716** may be a rigid conduit. Alternatively, sleeve **716** may include flexible and/or collapsible elements. Effectively, sleeve **716** may close diversion outlet and inlet **704** and **708** in the closed position of diversion valve **712**. Optionally, diversion valve **712** may include one or more sealing members (e.g. O-rings) which may form an air-tight seal between sleeve **716** and upstream wand portion **440**, and between sleeve **716** and downstream wand portion **444** to help prevent the escape of air through diversion outlet and inlet **704** and **708** in the closed position of diversion valve **712**.

Sleeve **716** may be movable axially along wand **114** between the closed position (FIGS. 52 and 55) and the open position (FIGS. 54 and 57). Preferably, sleeve **716** is moved to the open position automatically by mounting cyclone bin assembly **160** to upright section **108** (e.g. connecting to wand **144**), and/or moved to the closed position automatically by dismounting cyclone bin assembly **160** from upright section **108** (e.g. disconnecting from wand **144**). In the illustrated embodiment, sleeve **716** is drivingly coupled to a pedal **720**. Pedal **720** may be depressed to move sleeve **716** from the closed position of FIGS. 52 and 55 to the open position of FIGS. 54 and 57. As shown, pedal **720** may be positioned axially below sleeve **716** and extend outwardly of wand **144** to be depressed by cyclone bin assembly **160** when mounting cyclone bin assembly **160** to upright section **108**. Pedal **720** and sleeve **716** may be integrally molded, or separately formed and connected, to move axially up and down as a unit.

As exemplified, pedal **720** and sleeve **716** may be movably mounted to wand **144** for axial movement between the open and closed position. As shown, pedal **720** and sleeve **716** may move downwardly from the closed position (FIGS. 52 and 55) to the open position (FIGS. 54 and 57). In the closed position, sleeve **716** may extend the airflow path directly across the threshold between the upstream and downstream wand portions **440** and **444**. In the open position, sleeve **716** may be retracted into the upstream wand portion **440** to open diversion outlet **704** and inlet **708**, and thereby permit the airflow path to be diverted through diversion outlet **704**, cyclone bin assembly **160** and diversion inlet **708**. As shown, diversion outlet **704** may be positioned at a downstream end **724** of upstream wand portion **440**, and diversion inlet **708** may be positioned at an upstream end **728** of downstream wand portion **444**.

In an alternative embodiment, sleeve **716** may have one or more openings which align with diversion outlet and inlet

704 and 708 in the open position of valve 712. In the closed position, the openings in sleeve 716 may be closed by alignment with solid wall portions of wand 144, and diversion outlet and inlet 704 and 708 may be closed by alignment with solid wall portions of sleeve 716. In this case, sleeve 716 may be positioned inside the upstream and downstream wand portions 440 and 444 in both the open and closed positions of valve 712.

Preferably, sleeve 716 is biased to the closed position. For example, valve 712 may include a biasing member which acts on sleeve 716 to bias sleeve 716 to the closed position. In the illustrated example, valve 712 includes a spring 732 which acts on pedal 720 to urge pedal 720 and sleeve 716 upwardly to the closed position. In alternative embodiments, sleeve 716 may not be biased to the closed position. For example, sleeve 716 may include an actuator, such as a switch or lever, which must be manually activated to move sleeve 716 to the closed position or is moved by assembly 160 when assembly 160 is removed.

Still referring to FIGS. 52-57, cyclone bin assembly 160 may include an engagement member for mating with pedal 720 to mount cyclone bin assembly 160 on pedal 720. In the illustrated example, a cavity 736 is formed in sidewall 376 of cyclone bin assembly 160 for receiving pedal 720. In use, cyclone bin assembly 160 may be set onto pedal 720 such that pedal 720 is received in cavity 736. Preferably, the weight of cyclone bin assembly 160 on pedal 720 is sufficient to overcome the bias of valve biasing member 732, and move pedal 720 and sleeve 716 downwardly to the open position. In alternative embodiments, additional downward force must be applied by the user to move pedal 720 and sleeve 716 downwardly against the bias of the biasing member 732 and/or an actuator, such as a foot pedal, may be utilized.

Cyclone bin assembly 160 may be toed onto pedal 720 (see e.g., FIGS. 53, 56), and then pivoted on pedal 720 into position (see e.g., FIGS. 54, 57) after pedal 720 and sleeve 716 have moved downwardly to the open position. In the illustrated example, cyclone bin assembly 160 may be set onto pedal 720 with cyclone axis 392 extending at a (non-zero) angle to wand axis 740, and then lowered with pedal 720 to move valve 712 to the open position, and finally pivoted about pedal 720 toward wand 144 to complete the connection of cyclone bin assembly 160 to wand 144. An locking member, such as a latch 744, which may be located at the end of the upper end of wand 144, may be provided to secure assembly 160 in position. In some embodiments, cyclone axis 392 may be substantially parallel to wand axis 740 when cyclone bin assembly 160 is connected to wand 144.

Cyclone bin assembly 160 may include a diversion member 428 for dividing wand 144 into upstream and downstream wand portions 440 and 444, and for diverting flow from the upstream wand portion 440 into cyclone bin assembly inlet 316. Diversion member 428 may take any suitable form. In the illustrated embodiment, diversion member 428 is a substantially flat plate which extends outboard of sidewall 376 for protruding into wand 144 through one of diversion outlet 704, diversion inlet 708, or another opening into wand 144. Alternatively, diversion member 428 may be curved to provide a less abrupt change in airflow direction, which may reduce the pressure drop across the diversion member 428. Optionally, diversion member 428 may include or interface with a sealing member (e.g. a deformable elastomeric seal) to form an airtight barrier between upstream and downstream wand portions 440 and 444. Alternately, the diversion member may be a

separate member that is installed as a separate step when (i.e. before, during, and/or after) connecting cyclone bin assembly 160 to the wand 144.

As exemplified, when cyclone bin assembly 160 is mounted to wand 144, as shown in FIGS. 54 and 57, air inlet 316 of cyclone chamber 308 is connected to diversion outlet 704 for receiving air from upstream wand portion 440 into cyclone chamber 308, and outlet passage 476 is connected to diversion inlet 708 for discharging air from cyclone bin assembly 160 into downstream wand portion 444.

Cyclone bin assembly 160 may be removably mounted to wand 144 by any suitable mechanism. In the illustrated embodiment, cyclone bin assembly 160 includes a latch 744 on handle 616 for engaging a tab 746 which extends outwardly of wand 144. Latch 744 may be user-operable by a user grasping handle 616 to release latch 744 from tab 746 for disconnecting cyclone bin assembly 160 from wand 144. Preferably, biasing member 732 of valve 712 automatically and immediately moves sleeve 716 to the closed position upon disconnection of cyclone bin assembly 160 to reconfigure the airflow pathway by closing diversion inlet and outlet 704 and 708.

A diversion valve 712 according to a second embodiment is exemplified in FIGS. 58-63. Diversion valve 712 is similar to diversion valve 712 of FIGS. 52-57 in many respects except, for example that sleeve 716 is embodied by a collapsible hose 716 instead of a more rigid conduit.

As exemplified, diversion valve 712 includes a collapsible sleeve 716 positioned inside of wand 144, and a pedal 720 for moving hose 716 been an open position and a closed position.

Sleeve 716 may be a collapsible conduit for fluidly coupling upstream and downstream wand portions 440 and 444 in the closed position of diversion valve 712 (see FIGS. 60 and 63) to bypass diversion inlet and outlet 708 and 712. Optionally, diversion valve 712 may include one or more seals (e.g. O-rings) which form an air-tight seal between sleeve 716 and upstream wand portion 440, and between sleeve 716 and downstream wand portion 444 to help prevent the escape of air through diversion inlet and outlet 704 and 708 in the closed position of diversion valve 716.

In the illustrated embodiment, sleeve 716 has a fixed-position upstream end 756 sealed to upstream wand portion 440, and a downstream end 760 axially movable inside wand 144. Downstream end 760 may be movable toward upstream end 756 to the open position (FIGS. 60 and 63) whereby sleeve 716 is partially collapsed with downstream end 760 positioned in the upstream wand portion 440 upstream of diversion outlet 704. Downstream end 760 may also be movable away from upstream end 756 to the closed position (FIGS. 58 and 61) whereby sleeve 716 is extended with downstream end 760 position in the downstream wand portion 444 downstream of diversion inlet 708.

As exemplified, pedal 720 may be drivingly coupled to downstream end 760 of sleeve 716. Pedal 720 may be depressed (e.g. by the weight of cyclone bin assembly 160) to move downstream end 760 into the upstream wand portion 440, collapsing sleeve 716 into the open position of FIGS. 60 and 63. Pedal 720 may also be raised (e.g. automatically by action of biasing member 732 upon release of pedal 720 or pulled upwardly by assembly 160) to move downstream end 760 into the downstream wand portion 444, extending sleeve 716 into the closed position of FIGS. 58 and 61. Alternately, a manual actuator may be used.

A diversion valve 712 according to a third embodiment is exemplified in FIGS. 64-71. As exemplified, diversion valve 712 may include a diversion outlet door 772 and a diversion

inlet door 776. Doors 772 and 776 may be opened when cyclone bin assembly 160 is connected to wand 144 for reconfiguring the airflow path to extend through cyclone bin assembly 160. Doors 772 and 776 may also be closed when cyclone bin assembly 160 is disconnected from wand 144 for reconfiguring the airflow path to extend directly across the threshold between upstream and downstream wand portions 440 and 444.

In the illustrated embodiment, doors 772 and 776 are pivotally mounted to wand 144 for movement between a closed position (see FIGS. 64 and 67-69) in which doors 772 and 776 seal diversion outlet 704 and inlet 708 respectively, and an open position (see FIGS. 66 and 71) in which doors 772 and 776 are open to allow air to flow through doors 772 and 776 between wand 144 and cyclone bin assembly 160. Doors 772 and 776 may be pivotally mounted to wand 144 in any suitable manner. In the example shown, doors 772 and 776 are pivotally mounted to wand 144 by a common hinge 780. As shown, door 772 may pivot inwardly about hinge 780 toward a downstream direction, and door 776 may pivot inwardly about hinge 780 toward an upstream direction. In alternative embodiments, each of doors 772 and 776 may be pivotally mounted to wand 144 by a different hinge.

Preferably, doors 772 and 776 open automatically by connecting cyclone bin assembly 160 to wand 144. In the illustrated example, cyclone bin assembly 160 includes an inlet nose 784 for pushing open diversion outlet door 772, and an outlet nose 788 for pushing open diversion inlet door 776. As shown, noses 784 and 788 may extend outwardly of sidewall 376 for projecting through diversion outlet and inlet 704 and 708 respectively upon connecting cyclone bin assembly 160 to wand 144.

Preferably, when cyclone bin assembly 160 is connected to wand 144, an airflow path is formed between diversion outlet 704 and air inlet 316, and between diversion inlet 708 and air outlet 320, such that the airflow path from upstream wand portion 440 to downstream wand portion 444 is reconfigured to extend through cyclone bin assembly 160. In the illustrated example, connecting cyclone bin assembly 160 to wand 144 may include pushing noses 784 and 788 into diversion outlet and inlet 704 and 708 respectively to open doors 772 and 776.

Noses 784 and 788 may take any suitable form. As exemplified, nose 784 may be formed as a diversion member including an inlet passage having an upstream end 792 and a downstream end 796. Upstream end 792 may extend into wand 144 and form a seal with upstream wand portion 440 to redirect the airflow in upstream wand portion 440 to enter nose 784 toward downstream end 796. In the illustrated embodiment, upstream wand portion 440 includes a sealing ring 800 adjacent an upstream side 804 of diversion outlet door 772 onto which downstream end 796 may be seated for forming an airtight seal between upstream wand portion 440 and downstream end 796. Alternatively, or in addition, upstream side 804 may include a sealing member. Downstream end 796 of nose 784 may be integrally formed or otherwise connected with air inlet 316.

In the illustrated example, nose 788 is formed as a triangular plate which projects outwardly from air outlet 320. In other embodiments, nose 788 may have another suitable form for pushing diversion inlet door 776, such as a circular or rectangular plate or a rod for example. As shown, when cyclone bin assembly 160 is connected to wand 144, nose 788 projects into diversion inlet 708 pushing open diversion inlet door 776. This may permit air outlet 320 to sealingly abut diversion inlet 708 for forming an airflow path between air outlet 320 and downstream wand portion

444. Optionally, a seal 808 may be provided at the interface between air outlet 320 and diversion inlet 708 for enhancing the airtightness of the connection.

It will be appreciated that in alternative embodiments, nose 788 may be formed as an outlet passage, which may be curved similar to nose 784. This may make the change in airflow direction across nose 788 less abrupt, which may reduce pressure losses.

Preferably, when cyclone bin assembly 160 is disconnected from wand 144, doors 772 and 776 automatically close to reconfigure the airflow passage to extend directly from upstream wand portion 440 to downstream wand portion 444 without diversion through diversion outlet 704 or inlet 708. For example, doors 772 and 776 may be biased to the closed position by a biasing member, such as a spring. In the illustrated embodiment, diversion valve 712 includes a torsional spring 812. Spring 812 may be positioned to bias both of doors 772 and 776 to the closed position. In the illustrated embodiment, spring 812 is held in a spring housing 816 mounted to an inside face 820 of diversion outlet door 772. As shown, spring 812 may have an arm 824 connected to diversion inlet door 776, effectively biasing doors 772 and 776 away from each other to their respective closed positions. In alternative embodiments, each of doors 772 and 776 may have a separate biasing member.

A diversion valve 712 according to a fourth embodiment is exemplified in FIGS. 72-77. Diversion valve 712 is similar to diversion valve 712 of FIGS. 64-71 in many respects except, for example, the door which selectively closes diversion outlet 704 and inlet 708.

In the illustrated embodiment, diversion valve 712 includes a door 772. Door 772 may be movable between a closed position (FIGS. 72 and 75) in which door 772 seals diversion outlet 704 and inlet 708, and an open position (FIGS. 74 and 77) in which door 772 is unsealed from outlet 704 and inlet 708 to allow the airflow to pass through diversion outlet 704 and inlet 708. As exemplified, diversion valve 712 may include one door 772 for closing both of diversion outlet 704 and inlet 708, or separate doors 772 for diversion outlet 704 and inlet 708.

As shown, door 772 may be pivotally mounted to wand 144 in any suitable manner for movement between the open and closed positions. For example, door 772 may be pivotally mounted outside of wand 144 by a hinge 780. In the illustrated example, door 772 may pivot outwardly about hinge 780 away from wand 144 to the open position, and may pivot inwardly about, hinge 780 toward wand 144 to the closed position. Preferably, door 772 is manually openable, whereby a user may grasp door 772 and manually move door 772 from the closed position to the open position. For example, door 772 may have a lever 840, a handle, or another gripping member for a user to grasp for manipulating the position of door 772.

Once door 772 is opened, as shown in FIGS. 73 and 76, cyclone bin assembly 160 may be connected to wand 144. In the illustrated embodiment, cyclone bin assembly 160 includes a diversion member 428 of the type describe above with reference to FIGS. 52-57. Diversion member 428 may be moved into wand 144 through diversion outlet 704, diversion inlet 708, or another opening in wand 144, for dividing wand 144 into an upstream portion 440 and a downstream portion 444, substantially as described above.

When cyclone bin assembly 160 is disconnected from wand 144, door 772 may be moved back into the closed position for reconfiguring the airflow path in wand 144 to extend directly from upstream portion 440 to downstream portion 444 without diversion. For example, door 772 may

31

be manually moved from the open position to the closed position by hand, or door 772 may move automatically to the closed position by the bias of a biasing member (e.g. a spring).

In some embodiments, door 772 may be held in the closed position by the bias of a biasing member, or by a releasable locking mechanism (e.g. a latch). This may permit door 772 to form a tight seal against diversion outlet 704 and inlet 708.

In some embodiments, pedal 720 may be foot operable and may be located close to or on the surface cleaning head. Angular Surface of Upright Section

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a surface cleaning apparatus is provided having an upright section with a dirt collection chamber or cyclone bin assembly having a side profile that tapers or narrows from top to bottom. For example, the rear wall of the supplemental dirt collection chamber or supplemental cyclone bin assembly may extend upwardly at an acute angle relative to the wand axis such that the rear wall is farther from the wand axis at the top end than at the bottom end of the dirt collection chamber or cyclone bin assembly. An advantage of this design is that the surface cleaning, apparatus may extend under furniture while providing a large dirt collection capacity.

As exemplified in FIGS. 3 and 7, surface cleaning apparatus 100 and 152 include an upright section 108 having a dirt collection chamber 140 or cyclone bin assembly 160 that extends from a lower end 292, 856 proximate surface cleaning head 104 to an upper end 596, 860. A rear end 536, 548 of auxiliary assembly 140/160 may extend upwardly from lower end 292 or 856 at a (non-zero) acute angle 848 to wand axis 568. Angle 848 is preferably between 10 and 70 degrees, and more preferably between 20 and 40 degrees. For example, a distance 538 between wand axis 568 and rear end 536, 548, measured normal to wand axis 568, may increase continually or generally continuously from lower end 292, 856 upwardly. As shown, distance 538 is greater at upper end 596, 860 than at lower end 292, r 856.

Handvac with Angled Bottom Wall

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a handvac may be provided having a bottom, such as a flat bottom wall, for supporting the handvac on a horizontal surface, and which extends at an acute angle (e.g., between 20 and 40 degrees) away from the inlet nozzle axis, and optionally at about the in-use orientation of the hand vac. This may provide the handvac with a resting orientation that is closer to or essentially at the in-use orientation of the handvac. For example, the in-use orientation of the handvac may normally have the inlet nozzle axis extending at a downward angle relative to a horizontal surface to be cleaned. Thus, a user may not have to substantially reorient the handvac upon grasping the handvac in the resting orientation to reposition the handvac into the in-use orientation.

Reference is now made FIG. 78, where handvac 112 is shown resting on a horizontal surface 876. As shown, nozzle axis 884 extends at an angle 880 to horizontal surface 876. Angle 880 may be an acute angle which may be between 10 and 80 degrees, and preferably between 25 and 65 degrees, more preferably between 35 and 55 degrees or between 20 and 40 degrees. It will be appreciated that handvac 112 may be stably supported in any suitable manner, with nozzle axis 884 extending at angle 880 to horizontal surface 876. For example, handvac 112 may include one or more support

32

elements (e.g. a wall or feet) which collectively provide a support for handvac 112 on a horizontal planar surface at a desired acute angle, and a center of gravity 524 vertically aligned with or between the support elements for stability when handvac 112 is so supported by the support element(s) on the horizontal surface.

As exemplified, bottom wall 216 of handvac 112 may extend at an angle 880 to inlet nozzle axis 884 of nozzle 412. Bottom wall 216 may be planar, and the plane of bottom wall 216 may intersect with nozzle axis 884 at angle 880. Bottom wall 216 may provide a flat planar surface for making broad contiguous contact with horizontal surface 876, or bottom wall 216 may include a plurality of discrete contact points or surfaces which collectively contact the horizontal surface 876 to support the handvac 112 (e.g. as in the feet of a tripod, or the wheels of a car). Preferably, handvac center of gravity 524 is preferably aligned vertically above bottom wall 216 when handvac 112 is supported on horizontal surface 876 by bottom wall 216. This may permit handvac 112 to rest stably (i.e. statically without tipping over) on horizontal surface 876 while supported solely by bottom wall 216.

Handvac 112 may have an in-use orientation relative to horizontal surface 876 at which a user may comfortably operate handvac 112 during cleaning. Typically, handvac 112 is most comfortably operated in an orientation that does not require an application of torque by the user's hands when the handvac 112 is held by handle 484. This may be the case where the center of gravity 524 of the handvac 112 is aligned vertically below the user's hand. Accordingly, the center of gravity 524 may be vertically aligned below handle 484 in comfortable in-use orientations of handvac 112.

Preferably, center of gravity 524 is aligned vertically below handle 484 when handvac 112 is supported on horizontal surface 876. In the illustrated embodiment, center of gravity 524 is aligned vertically below handle 484 when bottom wall 216 is horizontal and supporting handvac 112 on a horizontal surface 876. Thus, the resting orientation of handvac 112 supported by bottom wall 216 on a horizontal surface 876 may be substantially the same as the in-use orientation of handvac 112. Accordingly, when a user grasps handvac 112 by handle 484 and lifts handvac 112, handvac 112 may already be in a balanced in-use position with the center of gravity 524 aligned below the user's hands.

In many cases, handvac 112 may be stored on a surface below a user's elbows. A user may angle their forearm downwardly to grasp handle 484 of handvac 112. In this case, the user's fingers and palm may be naturally aligned for grasping a handle which is angled forwardly of vertical. For example, to grasp a vertically oriented handle that is positioned below a user's elbow, a user may need to contort their wrist to conform to the orientation of the handle.

In the illustrated embodiment, handle axis 888 of handle 484 extends at a (non-zero) forward angle 892 to the vertical (e.g., e.g. when bottom wall 216 is horizontal). This may provide a comfortable handle alignment for grasping by a user when picking up handvac 112, and when using handvac 112 for cleaning surfaces below the user's elbows. Preferably, angle 892 is an acute angle of between 10 and 80 degrees, more preferably between 20 and 70 degrees and most preferably between 30 and 60 degrees.

Bottom wall 216 may be a wall of any component of handvac 112. In the illustrated embodiment, bottom wall 216 is a wall of cyclone bin assembly 136. Preferably, bottom wall 216 is a wall of dirt collection chamber 188. In the example shown, bottom wall 216 is an openable wall of dirt

collection chamber **188**. FIG. **79** shows another embodiment of handvac **112** where bottom wall **216** is not openable.

Referring to FIG. **78**, bottom wall **216** of handvac **112** may include front wheels, rear wheels, or both. Wheels may provide rolling support for handvac **112** when cleaning under furniture, for example. In alternative embodiments, handvac **112** may not include wheels on bottom wall **216** as shown.

Handle Position

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a floor cleaning apparatus is provided having a handvac with a handle, and an upright section with a cyclone bin assembly or dirt collection chamber with a handle. Preferably, the handles are centrally aligned with a plane of symmetry of the apparatus. This may permit the handles to be grasped for a balanced control of the apparatus. For example, the handles may be parallel to the same plane of symmetry.

Alternately, as exemplified in FIG. **2**, one handle may be parallel to a plane of symmetry and the other transverse thereto but positioned such that the plane of symmetry extends through the transversely oriented handle. In the illustrated example, handvac **112** includes a handle **484** which extends along a handle axis **888**. As exemplified, handle axis **888** may lie in a vertical plane **1044**, which is aligned centrally between left and right sides of apparatus **100** (i.e., a plane of symmetry). Turning to FIG. **78**, handle **484** is shown extending in length between a first handle end **1048** at the upper end **1052** of handvac **112**, and a second handle end **1056** intermediate the upper and lower ends **1052** and **1060** of handvac **112**.

Returning to FIG. **2**, assembly **140** is shown including a handle **1064**. As illustrated, handle **1064** may have a handle axis **1068** which extends perpendicularly or transverse to plane **1044** and handle axis **888**. Handle **1064** may be formed in a rear end **536** of assembly **140**. For example, handle **1064** may be flush with rear end **536** and include a concave finger cavity **1072** to facilitate grasping handle **1064**. Preferably, handle **1064** is positioned laterally centrally such that plane **1044** intersects handle **1064**, and optionally bisects handle **1064** at a midpoint between handle ends **1076** and **1080**.

Handles **484** and **1064** may be positioned on opposite sides of surface cleaning apparatus **100**. For example, handle **484** is shown extending from an upper end **1052** proximate the front surface of apparatus **100**, and handle **1064** is shown extending flush with a rear surface of apparatus **100**.

Apparatus **100** may include one or more actuator controls (e.g. buttons, levers, or switches) for controlling various functionality such as opening or disconnected elements, or connecting power to elements. Preferably, at least some of the actuator controls are positioned on or within finger reach of a handle to permit the control to be activated while grasping the handle. This may permit single handed operation of the function provided by the control.

Referring to FIG. **1**, apparatus **100** is shown including a power switch **1084** located on upper end **1052** of handvac **112** proximate first handle end **1048** within finger-reach when grasping handvac handle **484**. As illustrated, power switch **1084** may be laterally centrally positioned such that plane **1044** intersects and more preferably bisects power switch **1084**.

Referring now to FIGS. **15** and **16**, apparatus **168** is shown including an upright section **108** having a cyclone bin assembly **160** with a handle **616**, and handvac **112** with handle **484**. As shown, handle axis **1092** of handle **616**, and

handle axis **888** of handvac handle **484** may extend in a same plane **1096**. Preferably, plane **1096** is a vertical plane positioned laterally centrally between left and right sides of apparatus **168** as shown. In the illustrated embodiment, plane **1096** bisects handles **616** and **484**.

In the illustrated embodiment, handvac **112** includes a power switch **1084** located on upper end **1052** of handvac **112** which is bisected by plane **1044**. Handle **616** of cyclone bin assembly **160** is also shown including a button **1100** for releasing latch **744** to disconnect cyclone bin assembly **160** from wand **144**. As illustrated, button **1100** may be positioned laterally centrally between left and right sides of apparatus **168** such that button **1100** is bisected by plane **1096**.

Handvac Axial Alignment

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a plurality of airflow path segments in the handvac may extend in parallel. In some cases, this may reduce the number of bends in the airflow path through the handvac, which may reduce the pressure drop across the airflow path.

As exemplified in FIG. **96**, handvac inlet nozzle **412** may extend in length from an upstream nozzle end **416** rearwardly along a nozzle axis **884**, handvac cyclone chamber **184** may extend from an air inlet **192** along a cyclone axis **248** to an air outlet **196**, and handvac suction motor **204** may extend from a motor inlet **1108** along a motor axis **252** to a motor outlet **1112**.

In some embodiments, two or more of nozzle axis **884**, cyclone axis **248**, and motor axis **252** may be parallel. For example, in the illustrated embodiment, nozzle axis **884**, cyclone axis **248**, and motor axis **252** are parallel. In some embodiments, two or more of nozzle axis **884**, cyclone axis **248**, and motor axis **252** may be co-axial. For example, in the illustrated embodiment, nozzle axis **884** and cyclone axis **248** are co-axial. In other embodiments, nozzle axis **884**, cyclone axis **248**, and motor axis **252** may all be co-axial.

In the illustrated embodiment, handvac **112** may include an electrical connector **1116** for providing power to an upstream attachment (e.g. a surface cleaning head). As shown, connector **1116** may extend from a front connector end **1120** along a connector axis **1124** to a rear connector end **1128**. In some embodiments, connector axis **1124** may be parallel to one or more of nozzle axis **884**, cyclone axis **248**, and motor axis **252**. In the illustrated embodiment, connector axis **1124** is parallel to nozzle axis **884**, cyclone axis **248**, and motor axis **252**.

In some embodiments, handvac **112** may include one or more electrical cables **1132** which extend from electrical connector **1116** rearwardly to electrically couple electrical connector **1116** with a source of power (not shown). In the illustrated embodiment, electrical cables **1132** extend from electrical connector **1116** rearwardly along vortex finder **1136** of cyclone chamber **184** toward motor housing **1138**. As shown, at least the portion of electrical cables **1132** which along vortex finder **1136** across cyclone chamber **184** is parallel to cyclone axis **248**.

Axial Cyclone Inlet

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a handvac may be provided having a cyclone chamber with an axial inlet. That is, the inlet axis may be parallel to the cyclone axis, and more preferably co-axial with the cyclone axis. In some cases, this may reduce the bends in the airflow path through the cyclone, which may reduce the pressure drop across the

cyclone for better pneumatic efficiency. Preferably, the cyclone is a uniflow cyclone wherein the air outlet is at the opposite end from the air inlet. Alternately, or in addition, the axial inlet includes a portion that converts the axial flow to a tangential flow wherein the portion is provided within the diameter of the cyclone chamber. Optionally, the axial inlet is parallel to and may be co-axial with the handvac air inlet.

As exemplified in FIG. 96, handvac cyclone chamber 184 includes an air inlet 192 and an air outlet 196. As shown, air inlet 192 may include an inlet axis 1140 which is parallel to cyclone axis 248. Air inlet 192 may have a circular section transverse to axis 1140 with an inlet diameter 1144, or rectangular with a side dimension 1144. Preferably, the cross-sectional area of air inlet 192 is approximately equal to the cross-sectional area of inlet nozzle 412. Preferably, the cross-sectional area of air inlet 192 is between 80%-125% of the cross-sectional area of the inlet nozzle 412, more preferably 90%-120%, and most preferably 100%-115%.

Preferably, inlet 192 is in fluid communication with an upstream end 388 of an inlet passage 384. Inlet passage 384 may redirect the axial flow through inlet 192 to a tangential flow for developing a cyclonic motion inside cyclone chamber 184. Referring to FIGS. 23 and 23a, inlet passage 384 may extend from upstream passage end 388 to downstream passage end 396 across an arcuate angular extent 1148. Preferably angular extent 1148 is between 45 and 300°, more preferably between 60 and 250°, and most preferably between 90 and 200°.

Returning to FIG. 96, inlet passage 384 is shown having a width 1152, and a height 1108. In some embodiments, the cross-sectional area of inlet passage 384 may be approximately equal to the cross-sectional area of air inlet 192. Preferably, the cross-sectional area of inlet passage 384 is between 80%-125% of the cross-sectional area of the inlet passage 384, more preferably 90%-120%, and most preferably 100%-115%.

Vortex finder 1136 may define an outlet passage to air outlet 196 of cyclone chamber 184. As shown, vortex finder 1136 may be substantially cylindrical having a diameter 1160. In the illustrated embodiment, the cross-sectional area of vortex finder 1136 may be approximately equal to the cross-sectional area of inlet nozzle 412. For example, diameter 1160 may be approximately equal to diameter 1164 of inlet nozzle 412. Preferably, the cross-sectional area of vortex finder 1136 is between 80%-125% of the cross-sectional area of the inlet nozzle 412, more preferably 90%-120%, and most preferably 100%-115%.

Uniflow Cyclone
In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, a handvac may be provided having a cyclone chamber wherein the air outlet is at the opposite end from the air inlet. In some cases, this may reduce the bends in the airflow path through the cyclone, which may reduce the pressure drop across the cyclone for better pneumatic efficiency. Optionally, the cyclone inlet is at the front or inlet end of the handvac and may be parallel to or co-axial with the handvac air inlet.

As exemplified in FIG. 96, handvac inlet 192 is shown positioned at a front end 220 of cyclone chamber 184, and outlet 196 is shown positioned at a rear end 224 of cyclone chamber 184. Inlet 192 may have an inlet axis 1140 that is parallel to the outlet axis 1168 of air outlet 196. In the illustrated embodiment, inlet axis 1140 is co-axial with outlet axis 1168.

Optionally, the suction motor axis may be parallel to or co-axial with axis 1140, 1168. Accordingly, air may travel in a generally uniform direction through the components of the handvac.

5 Handvac Cyclone Dirt Collection Chamber

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, the dirt collection chamber of the handvac may have a dirt inlet which is located at the upper end of the dirt collection chamber when the hand vac is oriented for cleaning a floor (see e.g., FIGS. 81 and 103). In addition, the dirt collection chamber may be shaped to encourage dirt to collect at another end of the handvac away from the dirt outlet of the cyclone chamber (e.g., it may extend downwardly away from the dirt inlet). This may clear the dirt inlet to permit additional dirt to enter.

As exemplified in FIG. 96, dirt may enter dirt collection chamber 188 from cyclone chamber 184 through dirt outlet 200 of cyclone chamber 184. In the illustrated embodiment, dirt outlet 200 is at a rear end 224 of cyclone chamber 184. In use, handvac 112 may be normally oriented with the nozzle 412 at the front end oriented downwardly for cleaning a surface below. Accordingly, dirt entering dirt collection chamber 188 from dirt outlet 200 may fall by gravity toward front end 220 of dirt collection chamber 188 away from dirt outlet 200. This may help to keep dirt outlet 200 clear for subsequent dirt to move through dirt outlet 200 during use.

In the illustrated embodiment, handvac 112 may be supported on a horizontal surface 876 by contact between dirt collection chamber 188 and the horizontal surface 876. For example, dirt collection chamber 188 may include a bottom wall 216 for supporting handvac 112 on horizontal surface 876. Preferably, as discussed previously, handvac 112 is inclined with nozzle 412 facing downwardly when handvac 112 is supported on horizontal surface 876 by bottom wall 216. In the illustrated embodiment, bottom wall 216 is angled downwardly between front end 220 and rear end 224 for orienting nozzle axis 884 downwardly to horizontal when handvac 112 is supported on horizontal surface 876. As shown, this may provide dirt collection chamber 188 with a wedge-like shape having a height 1172 measured between upper and lower dirt collection chamber walls 226 and 216 which increases from the front end 220 to the rear end 224.

45 Pre-Motor Filter Housing

In accordance with another aspect of this disclosure, which may be used by itself or, in combination with any one or more other aspects of this disclosure, a pre-motor filter housing may be provided in the airflow path between the cyclone bin assembly and the suction motor for directing the airflow through one or more pre-motor filters contained therein.

As exemplified in FIGS. 96 and 117, handvac 112 has a pre-motor filter chamber 556 containing pre-motor filters 1176 and 1180, and a suction motor housing 1138 containing suction motor 204. The airflow path from inlet nozzle 412 to clean air outlet 132 may extend downstream from cyclone bin assembly 136 to pre-motor filter chamber 556 to suction motor housing 1138. That is, cyclone bin assembly 136, pre-motor filter chamber 556, and suction motor housing 1138 may be positioned in the airflow path with pre-motor filter chamber 556 downstream of cyclone bin assembly 136 and suction motor housing 1138 downstream of pre-motor filter chamber 556.

In the illustrated example, pre-motor filter chamber 556 extends in height 1184 between an upper end 1188 to a lower end 1192 in the direction of pre-motor filter axis 560, and

extends in depth 1216 between front wall 1220 and rear wall 1224. In some embodiments, cyclone axis 248 and motor axis 252 may be parallel and vertically offset as shown. For example, each of cyclone axis 248 and motor axis 252 may intersect pre-motor filter chamber 556 as shown. In some embodiments, outlet axis 1168 of cyclone chamber outlet 196 and, motor inlet axis 1196 of motor inlet 1108 may be parallel and vertically offset. For example, each of outlet axis 1168 and motor inlet axis 1196 may intersect pre-motor filter chamber 556 as shown.

In some embodiments, cyclone chamber outlet 196 discharges air from cyclone chamber 184 into pre-motor filter chamber 556, and pre-motor filter chamber 556 discharges air into motor inlet 1108. For example, cyclone chamber outlet 196 may be positioned at the threshold between cyclone chamber 184 and pre-motor filter chamber 556, and motor inlet 1108 may be positioned at the threshold between pre-motor filter chamber 556 and suction motor housing 1138. In alternative embodiments, one or more conduits (not shown) may separate pre-motor filter chamber 556 from cyclone chamber outlet 196 and/or motor inlet 1108.

In the illustrated embodiment pre-motor filter chamber 556 extends in length between a front end 1200 and a rear end 1204. As shown, pre-motor filter chamber 556 may hold pre-motor filters 1176 and 1180 in the airflow path between cyclone chamber outlet 196 and motor inlet 1108 for filtering residual dirt particles remaining in the airflow. In some embodiments, pre-motor filter chamber 556 may hold pre-motor filters 1176 and 1180 in spaced apart relation to front and rear ends 1200 and 1204. An upstream plenum 1208 may be provided in the space between upstream pre-motor filter 1176 and front end 1200. A downstream plenum 1212 may be provided in the space between downstream pre-motor filter 1176 and rear end 1204. Air entering upstream plenum 1208 from cyclone bin assembly 136 may distribute across the surface area of pre-motor filter 1176 for traversing filters 1176 and 1180 to downstream plenum 1212.

In the illustrated embodiment, cyclone chamber outlet 196 may direct air into an upper portion of upstream plenum 1208. For example, cyclone chamber outlet 196 may be connected to pre-motor filter chamber 556 proximate upper end 1188. In the illustrated embodiment, motor inlet 1108 may receive air from a lower portion of downstream plenum 1212. For example, motor inlet 1108 may be connected to pre-motor filter chamber 556 proximate lower end 1192. Accordingly, pre-motor filter chamber 556 may be used to redirect the air from transversely to the cyclone and motor axis without requiring conduits having bends therein.

Battery Power

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, the surface cleaning head or upright section of the surface cleaning apparatus may include one or more batteries for powering the handvac when the handvac is connected to the surface cleaning head or upright section. The handvac may also include handvac batteries which may power the handvac when connected to or disconnected from the upright section and surface cleaning head (e.g. In an above-floor cleaning mode or handvac mode). When the handvac is electrically connected to the surface cleaning head, the batteries in the surface cleaning head may supplement the batteries in the handvac or be the sole power source.

As exemplified in FIG. 3, surface cleaning apparatus 100 (or any other surface cleaning, apparatus embodiment disclosed herein) may include one or more handvac batteries 1268 mounted to the handvac 112, and one more supple-

mental batteries 1272. Supplemental batteries 1272 may be mounted to any other suitable component of apparatus 100 other than handvac 112. For example, supplemental batteries 1272 are shown mounted to surface cleaning head 104. Alternatively or additionally, supplemental batteries 1272 may be mounted to upright section 108.

As used herein, the plural term “batteries” means one or more batteries. For example, supplemental batteries 1272 may be one battery or a plurality of batteries. Similarly, handvac batteries 1268 may be one battery or a plurality of batteries. Batteries 1272 and 1268 may be any suitable form of battery such as NiCad, NiMH, or lithium batteries, for example. Preferably, batteries 1272 and 1268 are rechargeable, however, in alternative embodiments, one or both of batteries 1272 and 1268 may be non-rechargeable single-use batteries.

In the illustrated embodiment, when handvac 112 is connected to upright section 108, an electrical connection may be formed between supplemental batteries 1272 and handvac 112, e.g. for powering suction motor 204.

In some embodiments, supplemental batteries 1272 may provide handvac 112 with enhanced power for generating greater suction with suction motor 204. For example, suction motor 204 may operate in a high power consumption mode, drawing power from supplemental batteries 1272, or supplemental batteries 1272 and handvac batteries 1268 simultaneously.

In some embodiments, supplemental batteries 1272 may provide the handvac 112 with extra energy for prolonged cleaning time between charges. For example, supplemental batteries 1272 may have a greater energy capacity (e.g. measured in Watt-hours) than handvac batteries 1268, such that handvac 112 may be sustained by supplemental batteries 1272 for a longer operating time. In some embodiments, handvac 112 may draw power from both of supplemental batteries 1272 and handvac batteries 1268, which have a greater combined energy storage capacity than handvac batteries 1268 alone.

In some embodiments, supplemental batteries 1272 may supply power to the handvac in preference to the handvac batteries 1268 to delay or avoid draining the handvac batteries 1268. For example, handvac 112 may draw power from supplemental batteries 1272 until substantially depleted before drawing power from handvac batteries 1268. This may conserve power in handvac batteries 1268 for use when handvac 112 is disconnected from supplemental batteries 1272 (e.g. In an above-floor cleaning mode, or handvac mode of apparatus 100). In some embodiments, handvac 112 may never draw power from handvac batteries 1268 when handvac 112 is electrically connected to supplemental batteries 1272.

In some embodiments, handvac 112 may draw power from supplemental batteries 1272 to recharge handvac batteries 1268. This may help to ensure that handvac batteries 1268 are not depleted when handvac 112 is disconnected from supplemental batteries 1272 (e.g. for use in an above-floor cleaning mode, or handvac mode of apparatus 100). In some cases, supplemental batteries 1272 may recharge handvac batteries 1268 only when apparatus 100 is not turned on.

In some embodiments, supplemental batteries 1272 may be recharged whenever the surface cleaning apparatus is connected to an external power outlet. In some cases, handvac batteries 1268 may be recharged when handvac 112 is electrically connected to an external power outlet (e.g. when surface cleaning head 104 or upright section 108 is connected to a power outlet by an electrical cord (not

shown), and handvac **112** is connected to the surface cleaning head **104** or upright section **108**).

In some embodiments, one or, more of supplemental batteries **1272** and handvac batteries **1268** may be positioned in the airflow path. This may provide cooling for the batteries so positioned, which may help to prevent the batteries from overheating and may improve the performance of the batteries. In the illustrated example, handvac batteries **1268** are positioned in the airflow path inside motor housing **1138**. For example, handvac batteries **1268** may be positioned inside motor housing **1138** between suction motor **204** and clean air outlet **132**. The air passing over the handvac batteries **1268** may help to keep the batteries **1268** cool.

Supplemental batteries **1272** may be positioned in the airflow path to promote cooling of the batteries **1272**. In the illustrated example, supplemental batteries **1272** are shown positioned inside surface cleaning head **104** in the airflow path between dirty air inlet **124** and downstream end **1240**. The air passing over batteries **1272** may help to keep batteries **1272** cool.

In alternative embodiments, one or both of supplemental batteries **1272** and handvac batteries **1268** may be positioned outside of the airflow path (e.g. to be cooled passively).

Handvac Wheels

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, the handvac may be provided with one or more sets of wheels, and a handle which may articulate to facilitate different cleaning postures.

As exemplified in FIGS. **106-109**, surface cleaning apparatus **1292** may include a surface cleaning head **104**, an upright section **108** (which may receive any assembly **140**, **160** discussed previously), and a handvac **112**. An airflow path through apparatus **1292** may extend from dirty air inlet **124** in surface cleaning head **104**, downstream through upright section **108** and then handvac **112** to clean air outlet **1304**. Upright section **108** may include a wand **144** having an upstream end **360** drivingly connected to a pivot joint **116** of surface cleaning head **104**, and a downstream end **364** connected to an inlet nozzle **412** of handvac **112**.

Handvac **112** may include an air treatment member positioned in the airflow path between inlet nozzle **412** for separating dirt from the airflow. In the illustrated example, handvac **112** includes a cyclone bin assembly **136** including a cyclone chamber **184**, and a dirt collection chamber **188**. Optionally, a bottom wall **216** of dirt collection chamber **188** may be pivotally openable for emptying dirt collection chamber **188**.

As exemplified, apparatus **1292** may be movable between an upright storage position (FIG. **106**) in which handvac **112** is substantially vertically aligned above surface cleaning head **104** and wand **144** is substantially vertically oriented, and an in-use floor cleaning position (FIG. **108**) in which surface cleaning head **104** is positioned behind surface cleaning head **104** and wand **144** extends at an angle to vertical.

In the illustrated example, apparatus **1292** may include a handle **1340**. Handle **1340** may be connected to wand **144** by an arm assembly **1344**. As shown, arm assembly **1344** may include a first arm **1348** joined to a second arm **1352** by an articulating joint **1356**. First arm **1348** may be connected to wand **144** and joint **1356**, and second arm **1352** may be connected to handle **1340**. Alternately, joint **1356** may be used to connect second arm **1352** to wand **144**.

As shown, first arm **1348** may be rigidly connected to wand **144**, and extend transversely to wand **144**. For

example, first arm **1348** may extend perpendicularly to wand **144**. Second arm **1352** may be rotatable about joint **1356** between at least two positions. In the first position (FIG. **108**), second arm **1352** may extend at an angle to first arm **1348** substantially in parallel with wand **144**. In the second position (FIG. **109**), second arm **1352** may extend substantially parallel to first arm **1348**. An actuator (e.g., a button) **1358** may be provided on handle **1340** for toggle joint **1356** between an unlocked position in which second arm **1352** can move with respect to first arm **1348**, and a locked position in which the position of second arm **1352** is fixed with respect to first arm **1348**. Optionally, joint **1356** may be locked in a number of alternate positions. Alternately, joint **1356** may not be locked in the second bent position shown in FIG. **109**.

The first position (FIG. **108**) may be suitable for cleaning open areas where vertical clearance is not an issue. The second position (FIG. **109**) may be suitable for cleaning under furniture and the like, where wand **144** must be lowered to clear the furniture height. In the second position, the orientation of second arm **1352** may permit a user to grasp handle **1340** and lower wand **144** while conveniently standing, upright.

In some embodiments, handvac **112** may include one or more front wheels **1364**. Front wheel **1364** may be positioned to make rolling contact with a horizontal surface when wand **144** is lowered sufficiently. Thus, front wheel **1364** may assist with supporting the weight of handvac **112** and permit handvac **112** to roll across the horizontal surface. In the illustrated example, a front end **1360** of bottom wall **216** is provided with one or more front wheels **1364**.

It will be appreciated that if rear end of assembly **140,160** is tapered as discussed previously, then assembly **140,160** is configured to permit the vacuum cleaner to extend further under furniture than if the assembly **140,160** had the depth (front to back when in an upright storage position) as the upper end of the assembly **140,160**.

Openable Handvac Cyclone Bin Assembly

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, the cyclone bin assembly of the handvac may be opened to empty the cyclone chamber and/or the dirt collection chamber, to access the pre-motor filter or access a door to open the cyclone chamber and/or the dirt collection chamber by moving part or all of the cyclone bin assembly relative to a main body of the handvac which include the suction motor while the parts remain connected together. For example, the parts, may be pivotally mounted to each other.

Referring to FIGS. **110a** and **110b**, front portion **1372** of handvac **112** may be pivotally connected to rear portion **1376** of handvac **112** for pivoting between the open position shown and a closed position. In the open position, cyclone bin assembly **136** may be accessible, e.g. for emptying or cleaning.

Front portion **1372** may be pivotally connected to rear portion **1376** in any suitable fashion. In the illustrated embodiment, front portion **1372** is pivotally connected to rear portion **1376** by a hinge **1380** for rotation about a hinge axis **1384** between the open and closed positions.

In the illustrated embodiment, front portion **1372** and rear portion **1376** separate at the interface between cyclone bin assembly **136** and pre-motor filter chamber **556**. For example, front portion **1372** may include cyclone bin assembly **136** except for second end wall **224**, and rear portion may include pre-motor filter chamber **556** and second end wall **224** of cyclone bin assembly **136**. Accordingly, in the

open position, access may be provided to empty and clean dirt collection chamber 188 and cyclone chamber 184 of cyclone bin assembly 136.

Referring to FIG. 116, in some embodiments handvac 112 may include a handle assembly 300 including handle 484 and suction motor 204. As exemplified, handle assembly 300 and rear wall 1224 of pre-motor filter chamber 556 may be removable from (entirely, or pivotally connected to) pre-motor filter chamber 556 as a unit to access the pre-motor filters 1176 and 1180 inside pre-motor filter chamber 556, e.g. for cleaning or replacement. As shown in FIG. 117, in some embodiments, handle assembly 300 may also be removably connected to rear wall 1224. In alternative embodiments, handle assembly 300 may be permanently connected to rear wall 1224.

Openable Dirt Collection Chamber

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, the supplemental assembly may have a top and/or bottom openable portion.

As exemplified in FIGS. 111-113, dirt collection assembly 140 is shown including an upper portion 276 in an open position. Upper portion 276 may be moveably connected to (e.g., pivotally) or removable from dirt collection assembly 140 in any suitable manner. As exemplified, upper portion 276 may be connected to dirt collection chamber 140 by a hinge 1392 for rotation about a hinge axis 1 (not shown) between the open and closed positions.

Upper portion 276 may be retained in the closed position in any suitable fashion. In the illustrated example, dirt collection chamber 140 includes a latch 1400 for securing upper portion 276 in the closed position. Latch 1400 may be user operable for selectively releasing upper portion 276 for movement to the open position.

As exemplified in FIGS. 114 and 115, upright section 108 of surface cleaning apparatus 152 is shown including a cyclone bin assembly 160. Cyclone bin assembly 160 is preferably openable for accessing cyclone chamber 308 and dirt collection chamber 141, e.g. for cleaning or emptying. Preferably, an upper and/or lower portion of cyclone bin assembly 160 may be openable. In the illustrated embodiment, upright section 108 includes an upper portion 1408 and a lower portion 1412. As shown, upper portion 1408 may be moveably connected to (e.g., pivotally connected to) or removable from lower portion 1412 for movement between a closed position (FIG. 114) and an open position (FIG. 115).

Upper portion 1408 may be pivotally connected to lower portion 1412 in any suitable manner. In the illustrated embodiment, lower portion 1412 is pivotally connected to lower portion 1412 by a hinge 1416 for rotation about a hinge axis 1420 between the closed and open positions.

Upper portion 1408 may be retained in the closed position in any suitable manner. For example, upper portion 108 may include a releasable catch for selectively securing upper portion 1408 to lower portion 1412 in the closed position. Handvac Cyclone Bin Assembly Bypass

In accordance with another aspect of this disclosure, which may be used by itself or in combination with any one or more other aspects of this disclosure, the cyclonic air treatment member of the handvac may be bypassed when a supplemental cyclonic bin assembly is provided. This may prevent accumulation of dirt in the handvac so that the handvac may have more or all of its dirt collection capacity available when disconnected from the upright section. Alternately or in addition, a pre-motor filter of handvac 112 may be bypassed when a supplemental cyclonic bin assembly is provided. For example, the supplemental cyclonic bin

assembly may be provided with a pre-motor filter. The pre-motor filter may have a larger surface area than the pro-motor filter of handvac 112. Accordingly, by bypassing the pre-motor filter of handvac 112, the pre-motor filter of handvac 112 may only be used in an above floor cleaning mode thereby extending the useable time of the pre-motor filter of handvac 112 before cleaning or replacement may be needed.

Referring to FIGS. 99-101, handvac 112 may include a primary airflow path 1228 and a bypass airflow path 1232. As shown, primary airflow path 1228 may extend from air inlet 192 through cyclone bin assembly 136 to suction motor 204, and bypass airflow path 1232 may extend from air inlet 192 to suction motor 204 bypassing cyclone bin assembly 136. In some embodiments, bypass airflow path 1232 may extend through the pre-motor filters of pre-motor filter chamber 556, and in other embodiments, bypass airflow path 1232 may bypass pre-motor filters of pre-motor filter chamber 556. It will be appreciated that the cyclone and/or the pre-motor filter of the handvac may be bypassed. If both are bypassed, then the handvac may be used to provide some or all of the motive force to draw air through apparatus 168 but not any air treatment upstream of the suction motor.

In the illustrated embodiment, bypass airflow path 1232 is formed in part by a bypass passage 1236. Bypass passage 1236 may have an upstream end 1238 in airflow communication with handvac inlet 416, and a downstream end 1240 in airflow communication with motor inlet 1108. As exemplified by the embodiment illustrated in FIG. 101, upstream end 1238 may be formed in a sidewall of handvac nozzle 412, and downstream end 1239 may be formed in a wall of premotor filter chamber 556. In some embodiments, downstream end 1239 may direct air from bypass passage 1236 into upstream plenum 1208 for routing bypass airflow path 1228 through pre-motor filters 1176 and 1180 as shown. In alternative embodiments, downstream end 1239 may direct air from bypass passage 1236 into downstream plenum 1212 for bypassing pre-motor filters 1176 and 1180.

As exemplified, apparatus 168 may include a bypass valve 1240 for selectively opening and closing primary and bypass airflow paths 1228 and 1232. Bypass valve 1240 may be positioned in any one or more of handvac 112, wand 144, and supplemental cyclone bin assembly 160, and may take any suitable form. For example, in some embodiments bypass valve 1240 may include components parts positioned in two or more of handvac 112, wand 144, and supplemental cyclone bin assembly 108 which cooperate and interact to open and close primary and bypass airflow paths 1228 and 1232.

In the illustrated embodiment bypass valve 1240 is positioned in inlet nozzle 412 of handvac 112. Bypass valve 1240 may be movable between a first position (FIGS. 99 and 100) in which bypass airflow path 1232 is closed and primary airflow path 1228 is open, and a second position (FIG. 101) in which bypass airflow path 1232 is open and primary airflow path 1228 is closed.

As exemplified in FIGS. 99-101, bypass valve 1240 may include a wheel 1242, a door 1244, and an actuator 1246. Wheel 1242 may be rotatably connected to nozzle 412 for rotation about its center. Door 1244 may be rigidly connected to wheel 1242 for rotation as one with wheel 1242. For example, door 1244 and wheel 1242 may rotate together as a unit. As shown, door 1244 and wheel 1242 may be rotatable between a first position (FIGS. 99 and 100) in which door 1244 seals an upstream end 1238 of bypass passage 1236, and a second position (FIG. 101) in which door 1244 seals an air inlet 192 of cyclone chamber 184.

As exemplified, actuator **1246** may include an upper end **1248** connected to wheel **1242** radially outboard of the center of wheel **1242**. Actuator **1246** may be movable vertically between a lowered position (FIGS. **99** and **100**), and a raised position (FIG. **101**). As shown, moving actuator **1246** from the lowered position to the raised position may rotate wheel **1242** and door **1244** clockwise which may move door **1244** to the second position (FIG. **101**) in which door **1244** seals air inlet **192** of cyclone chamber **184**. Further, moving actuator **1246** from the raised position to the lowered position may rotate wheel **1242** and door **1244** counter clockwise which may move door **1244** to the first position (FIGS. **99** and **100**) in which door **1244** seals upstream end **1238** of bypass passage **1236**.

In some embodiments, actuator **1246** may be biased to the lowered position (FIGS. **99** and **100**). Consequently, door **1244** and wheel **1242** may be biased to the first position (FIGS. **99** and **100**) in which door **1244** seals an upstream end **1238** of bypass passage **1236**. Actuator **1246** may be biased in any suitable fashion, such as by a linear coil spring **1250**. In alternative embodiments, wheel **1242** may be biased clockwise in a suitable manner, such as by a torsional spring.

Actuator **1246** may have a lower end **1252** which extends outside of the airflow path. Lower end **1252** may be acted upon to move actuator **1246** vertically from the lowered position to the raised position for opening bypass airflow path **1232** and closing primary airflow path **1228**. As shown, when handvac **112** is disconnected from wand **144** (FIG. **99**), bypass valve **1240** may close the bypass airflow path **1232** (e.g. under the bias of spring **1250**). Further, when handvac **112** is connected to wand **144** without supplemental cyclone bin assembly **160** (FIG. **100**), bypass valve **1240** may also close the bypass airflow path **1232**. In each of these cases, the air entering handvac **112** is directed through handvac cyclone bin assembly **136** to separate dirt from the airflow. This may permit handvac **112** to operate when disconnected from supplemental cyclone bin assembly **160**.

As shown in FIG. **101**, when handvac **112** and cyclone bin assembly **160** are both connected to wand **144**, an upper end **1254** of cyclone bin assembly **160** (handle **1254** in the illustrated example) may push against actuator lower end **1252** thereby moving actuator **1246** upwardly. This may rotate wheel **1242** and door **1244** counter clockwise, opening bypass airflow path **1232** and closing primary airflow path **1228**. As shown, air exiting cyclone bin assembly **160** may travel through bypass airflow path **1232** toward suction motor **204** bypassing cyclone chamber **184**. This may permit supplemental cyclone bin assembly **160** to separate and collect dirt from the airflow path instead of handvac cyclone bin assembly **136**. In turn, this may inhibit dirt accumulation in handvac dirt collection chamber **188**, which may help to maximize the available dirt collection capacity of handvac dirt collection chamber **188** when the user chooses to disconnect cyclone bin assembly **160**.

In the illustrated example, lower end **1252** is sloped. This may permit supplemental bin assembly **160** to be toed into wand **144** and then rotated horizontally towards wand **144** to complete the connection with wand **144**, whereby the upper end **1254** of supplemental bin assembly **160** may ride the slope of lower end **1252** to push actuator **1246** upwardly.

Accordingly, bypass valve **1240** may be actuated to reconfigure the airflow path through handvac **112** automatically upon connecting and disconnecting supplemental bin assembly **160** from airflow communication with handvac **112**. For example, bypass valve **1240** may be biased to close bypass airflow path **1232** whenever handvac **112** is not in

airflow communication with supplemental bin assembly **160** so that the air treatment member of handvac **112** may separate dirt from the airflow. Similarly, bypass valve **1240** may be configured to open bypass airflow path **1232** and close primary airflow path **1228** whenever handvac **112** is in airflow communication with supplemental bin assembly **160** so that the air treatment member of handvac **112** does not separate and store dirt from the airflow.

The following is a description of numerous embodiments of surface cleaning apparatus **168**, in the figures associated with some embodiments, a bypass valve **1232** and/or a diversion valve **712** may be represented schematically. It will be appreciated that the embodiments may be practiced using the bypass valves **1232** and/or diversion valves **712** described above, or other suitable valves.

Referring to FIG. **102**, in some embodiments supplemental cyclone bin assembly **160** may include one or more pre-motor filters **1256** (herein after referred to as pre-motor filter **1256** in the singular) positioned in the airflow path. Preferably, pre-motor filter **1256** is positioned downstream of cyclone chamber **308**. As shown, pre-motor filter **1256** may be positioned between cyclone chamber air outlet **320** and outlet passage **476**.

In some embodiments, pre-motor filter **1256** may separate fine dirt particles from the airflow in substitution for the pre-motor filters **1176** and **1180** of handvac **112**. As shown, bypass valve **1232** may divert air from supplemental cyclone bin assembly **160** into a bypass airflow path which bypasses handvac cyclone bin assembly **136** and pre-motor filters **1176** and **1180**. For example, downstream end of **1239** of bypass passage **1236** may direct the bypass airflow path **1232** to downstream plenum **1212** for bypassing pre-motor filters **1176** and **1180**.

It will be appreciated that a pre-motor filter will have a certain filtering capacity of fine particles at which point the filter should be cleaned or replaced. By incorporating a pre-motor filter into the supplemental cyclone bin assembly **160**, and using this filter whenever the supplemental cyclone bin assembly **160** is connected to the handvac, the filtering capacity of the handvac pre-motor filters may be preserved. This may permit extended use of the handvac pre-motor filters before they require cleaning or replacement.

It will also be appreciated that there will be a measurable pressure drop across a pre-motor filter placed in an airflow path. If positioned in series, too many filters may produce a pressure drop that materially reduces air flow at the dirty air inlet. By filtering the airflow alternately by the supplemental pre-motor filter **1256** and by the handvac pre-motor filter when the handvac is used without assembly **140**, **160** attached the operational life of the handvac pre-motor filter may be extended.

As exemplified in the alternate embodiment of FIG. **103**, surface cleaning head **104** may include a second suction motor **1258**. Second suction motor **1258** may operate in parallel with or alternately instead of handvac suction motor **204** when handvac **112** is attached in flow communication with surface cleaning head **104**. For example, a portion of air exiting supplemental cyclone bin assembly **160** may proceed to handvac suction motor **204** and a different portion may proceed to second suction motor **1258**. In the illustrated embodiment, a second airflow path **1260** from diversion valve **712** to second suction motor **1258** is formed by an airflow conduit **1262** which connects diversion valve **712** to surface cleaning head **104**.

As shown, when supplemental cyclone bin assembly **160** is in airflow communication with handvac **112**, the airflow path extends through the air treatment member(s) of supple-

mental cyclone bin assembly **160** (e.g. cyclone chamber **308** and pre-motor filter **1256**) and then divides into two parallel air flow paths **1232** and **1260**. Bypass airflow path **1232** directs one portion of the airflow to the handvac suction motor **204** bypassing handvac cyclone chamber **184** (and optionally bypassing handvac pre-motor filters **1176** and **1180**), and second airflow path **1260** directs a second portion of the airflow path to the second suction motor **1258** in head **104**.

It will be appreciated that suction motors **1258** and **204** operating in parallel may generate greater suction at surface cleaning head **104** than any one of suction motors **1258** and **204** may generate operating alone. This may also permit supplemental cyclone bin **160** to include a pre-motor filter **1256** having greater surface area than the pre-motor filter of the handvac, where the additional pressure drop due to the use of two pre-motor filters may be compensated for by the enhanced suction generation of the parallel motors **1258** and **204**.

As exemplified in the alternate embodiment of FIG. **104a**, supplemental suction motor **160** may include a second suction motor **1258** which may operate in the same way as the embodiment of FIG. **103**. Second suction motor **1258** may operate in parallel with handvac suction motor **204**. For example, a portion of air exiting supplemental cyclone chamber **160** may proceed to handvac suction motor **204** and a different portion may proceed to second suction motor **1258**. In the illustrated embodiment, a second airflow path **1260** from outlet passage **478** to second suction motor **1258** is formed by an airflow conduit **1262**.

As shown, when supplemental cyclone bin assembly **160** is in airflow communication with handvac **112**, the airflow path extends through the air treatment member(s) of supplemental cyclone bin assembly **160** (e.g. cyclone chamber **308** and pre-motor filter **1256**) and then divides into two parallel air flow paths **1232** and **1260**. Bypass airflow path **1232** directs one portion of the airflow to the handvac suction motor **204** bypassing handvac cyclone chamber **184** (and optionally bypassing handvac pre-motor filters **1176** and **1180**), and second airflow path **1260** directs a second portion of the airflow path to the second suction motor **1258**.

As shown, second suction motor **1258** may be positioned below dirt collection chamber **140** and cyclone chamber **308** of supplemental cyclone bin assembly **160**, and second suction motor **1258** may be vertically aligned above surface cleaning head **104**. This may help to lower the center of gravity of the apparatus **168** for enhanced stability against tipping.

In some embodiments, a pre-motor filter may be positioned in each of bypass airflow path **1232** and second airflow path **1260**, as shown. For example, a pre-motor filter **1256** may be positioned in the second airflow path **1260** between outlet passage **478** and second suction motor **1258**, and bypass airflow path **1232** may direct the airflow through handvac pre-motor filters **1176** and **1180**. In the illustrated embodiment, pre-motor filter **1256** is shown positioned below dirt collection chamber **140** of supplemental cyclone bin assembly **160**.

In alternative embodiments, air exiting cyclone chamber **308** may pass through a common pre-motor filter before dividing between the second airflow path **1260** and bypass airflow path **1232**. For example, in FIG. **104b** pre-motor filter **1256** is shown positioned downstream of cyclone chamber **308** and upstream of outlet passage **478**. As shown, bypass airflow path **1232** may bypass handvac pre-motor filters **1176** and **1180**. This may permit the filtration capacity of handvac pre-motor filters **1176** and **1180** to be preserved

for use when supplemental cyclone bin assembly **160** is disconnected from airflow communication with handvac **112**. In alternative embodiments, pre-motor filters **1176** and **1180** may be positioned in the bypass airflow path **1232**.

As exemplified in FIG. **105a** dirt collection chamber **140** and cyclone chamber **308** may be removable as a sealed unit from wand **144** and second suction motor **1258**. For example, second suction motor **1258** may be mounted or removably mounted to wand **144** so that dirt collection chamber **140** and cyclone chamber **308** may be removed while second suction motor **1258** remains mounted to wand **144**. This may permit cleaning and/or emptying of dirt collection chamber **140** and cyclone chamber **308** (e.g. carrying the same to a garbage bin to dump their contents) without having to carry second suction motor **1258** (which may have a non-trivial weight). Also, assembly **160** may be removable as a unit to convert the apparatus to a lightweight or above floor operating mode.

As exemplified in FIG. **118**, the air treatment members of handvac **112** and supplementary cyclone bin assembly **160** may operate in parallel. For example, handvac **112** and supplementary cyclone bin assembly **160** may separate dirt from mutually exclusive portions of the airflow entering dirty air inlet **124**.

In the illustrated example, wand **144** may define two airflow paths. A first airflow path **1428** may be formed by a first division of wand **144** and may direct airflow moving therein to supplemental cyclone bin assembly **160** for cleaning, and then from supplemental cyclone bin assembly **160** to bypass airflow path **1232** of handvac **112**. A second airflow path **1432** may be formed by a second division of wand **144** and may direct airflow moving therein to primary airflow path **1228** of handvac **112** for cleaning by cyclone bin assembly **136**.

As exemplified, dirty air entering dirty air inlet **124** may divide into two airflows at wand upstream end **360** and then travel through the first and second airflow paths **1428** and **1432**. Dirt may be separated from each airflow stream by a different one of supplementary cyclone bin assembly **160** and handvac **112**. In the illustrated embodiment, the two airflows may recombine in pre-motor filter chamber **556**. For example, the two airflows may recombine at the upstream plenum **1208** so that both airflows pass through pre-motor filters **1176** and **1180** before exiting through suction motor **204**. In alternative embodiments, the two airflows may recombine at the downstream plenum **1212**. For example, supplemental cyclone bin assembly **160** may have its own pre-motor filter for filtering the air of the first airflow path **1428**.

In some embodiments, surface cleaning apparatus **168** may include two or more suction motors operating in series. In one aspect, this may enhance the suction at dirty air inlet **124** and/or compensate for suction loss from additional or higher efficiency air treatment members.

Referring to FIGS. **119a** and **119b**, a second suction motor **1258** may be positioned in the airflow path between dirty air inlet **124** and handvac **112**. For example, second suction motor **1258** may be a dirty air suction motor positioned in surface cleaning head **104**. As shown, dirty air entering dirty air inlet **124** may be drawn through second suction motor **1258** before the airflow is cleaned by supplemental dirt collection chamber **160** and/or handvac **112** and discharged through handvac suction motor **204**.

Referring to FIG. **120**, second suction motor **1258** may be a clean air motor positioned downstream of handvac suction motor **204**. As exemplified, motor outlet **1112** of handvac suction motor **204** may be fluidly connected to second

47

suction motor **1258** in surface cleaning head **104** by an airflow path **1436**. As shown, airflow path **1436** may be formed by a conduit **1440**.

Referring to FIG. **121a**, in some embodiments second suction motor **1258** may be positioned in supplementary cyclone bin assembly **160**. For example, second suction motor **1258** may be positioned below dirt collection chamber **140**. As shown, airflow path **1436** from motor outlet **1112** may direct air from suction motor **204** to second suction motor **1258** in supplementary cyclone bin assembly **160**. For example, conduit **1440** may extend from motor outlet **1112** to second suction motor **1258**. Conduit **1440** may take any suitable form. For example, conduit **1440** may be a rigid conduit as shown. Alternatively, FIG. **121b** shows an embodiment where conduit **1440** is a flexible hose.

In some embodiments, when handvac is connected with supplement cyclone bin assembly **160**, handvac **112** may not be positioned in the airflow path through the surface cleaning apparatus. For example, air entering the dirty air inlet **124** of the surface cleaning head may be cleaned by the supplementary cyclone bin assembly **160** and discharged without ever passing through handvac **112**. In this way, handvac **112** may act as a handgrip for manipulating and steering surface cleaning apparatus **168** in the upright mode but not as an air cleaning, implement.

In some embodiment, as exemplified in FIG. **122**, the handvac may be bypassed when assembly **160** is attached to upright section **108**. As exemplified, air entering dirt air inlet **124** may move through wand **144** to supplemental cyclone bin assembly **160** and be discharged without moving through handvac **112**. For example, the airflow path through surface cleaning apparatus **168** may direct all air from dirty air inlet **124** through wand **144** to cyclone chamber **308** to outlet passage **476** to second airflow path **1260** to suction motor **1258** of supplemental cyclone bin assembly **160**, which may discharge the air to the outside environment.

Still referring to FIG. **122**, in some embodiments there may be a plurality of suction motors in series. In the illustrated embodiment, surface cleaning head **104** includes a suction motor **1258** positioned in the airflow path between dirty air inlet **124** and wand **144**. In alternative embodiments, suction motor **1258** may be the only suction motor in the airflow path.

While the above description provides examples of the embodiments, it will be appreciated that some features and/or functions, of the described embodiments are susceptible to modification without departing from the spirit and principles of operation of the described embodiments. Accordingly, what has been described above has been intended to be illustrative of the invention and non-limiting and it will be understood by persons skilled in the art that other variants and modifications may be made without departing from the scope of the invention as defined in the claims appended hereto. The scope of the claims should not be limited by the preferred embodiments and examples, but should be given the broadest interpretation consistent with the description as a whole.

The invention claimed is:

1. A surface cleaning apparatus comprising:

- a) a surface cleaning head having a dirty air inlet;
- b) an air flow path extending from the dirty air inlet to a clean air outlet;
- c) an upright section having a first end movably mounted to the surface cleaning head and an opposed second end, the upright section moveable between a storage position and a floor cleaning position;

48

d) an upstream dirty-air suction motor in the air flow path downstream from the dirty air inlet;

e) a portable vacuum cleaner unit detachably mounted to the upright section, the portable vacuum cleaner unit comprising an air treatment member in the air flow path and a portable unit suction motor in the air flow path downstream from the upstream dirty-air suction motor; and,

wherein the surface cleaning apparatus is operable in an upright mode in which the portable vacuum cleaner unit is mounted to the upright section and the upstream dirty-air suction motor and the portable unit suction motor are concurrently operated such that air travels sequentially through the dirty air inlet, the upstream dirty-air suction motor, and then the portable unit suction motor, and

wherein the portable vacuum cleaner unit is operable in a portable mode wherein the portable vacuum cleaner unit is detached from the upright section.

2. The apparatus of claim 1, wherein the upstream dirty-air suction motor is disposed in or on one of the surface cleaning head and the upright section.

3. The apparatus of claim 1, wherein the portable vacuum cleaner unit is a hand vacuum cleaner.

4. The apparatus of claim 1, wherein the upstream dirty-air suction motor is disposed in the surface cleaning head.

5. The apparatus of claim 1, wherein the portable vacuum cleaner unit is drivingly connected to the surface cleaning head.

6. The apparatus of claim 5, wherein the upright section comprises a rigid wand that forms a portion of the air flow path between the surface cleaning head and the portable vacuum cleaner unit, the wand having an upstream end fluidly connected to the surface cleaning head and an opposed downstream end fluidly connected to the portable vacuum cleaner unit.

7. The apparatus of claim 6, wherein the portable vacuum cleaner unit comprises a nozzle that is detachably connected to the downstream end of the wand.

8. The apparatus of claim 7, wherein an electrical cord is provided on one of the surface cleaning head and the upright section and, in the upright mode, the portable vacuum cleaner unit is electrically connected to the electrical cord.

9. The apparatus of claim 8, wherein the portable vacuum cleaner unit comprises one or more batteries mounted to the portable vacuum cleaner unit for powering the portable unit suction motor.

10. The apparatus of claim 6, wherein the wand extends longitudinally along a wand axis and the portable unit suction motor rotates about a portable unit suction motor axis, and when the portable vacuum cleaner unit is mounted to the wand the portable unit suction motor axis is generally parallel to the wand axis.

11. The apparatus of claim 1, wherein the air treatment member comprises a cyclone chamber and the portable unit suction motor is external to the air treatment member.

12. The apparatus of claim 11, further comprising a pre-motor filter in the air flow path between the cyclone chamber and the portable unit suction motor.

13. The apparatus of claim 12, wherein air exiting the upstream dirty-air suction motor passes through both the cyclone chamber and the pre-motor filter before reaching the portable unit suction motor.

14. The apparatus of claim 1, wherein the portable vacuum cleaner unit comprises one or more batteries mounted to the portable vacuum cleaner unit for powering the portable unit suction motor.

15. The apparatus of claim 14, wherein an electrical cord is provided on one of the surface cleaning head and the upright section and, in the upright mode, the portable vacuum cleaner unit is electrically connected to the electrical cord.

5

16. The apparatus of claim 14, further comprising one or more supplemental batteries mounted to one of the surface cleaning head and the upright section.

17. The apparatus of claim 16, wherein an electrical connection is formed between the one or more supplemental batteries and the portable vacuum cleaner unit when the portable vacuum cleaner unit is mounted to the upright section.

10

18. The apparatus of claim 17, wherein an electrical cord is provided on one of the surface cleaning head and the upright section and, in the upright mode, the portable vacuum cleaner unit is electrically connected to the electrical cord.

15

* * * * *